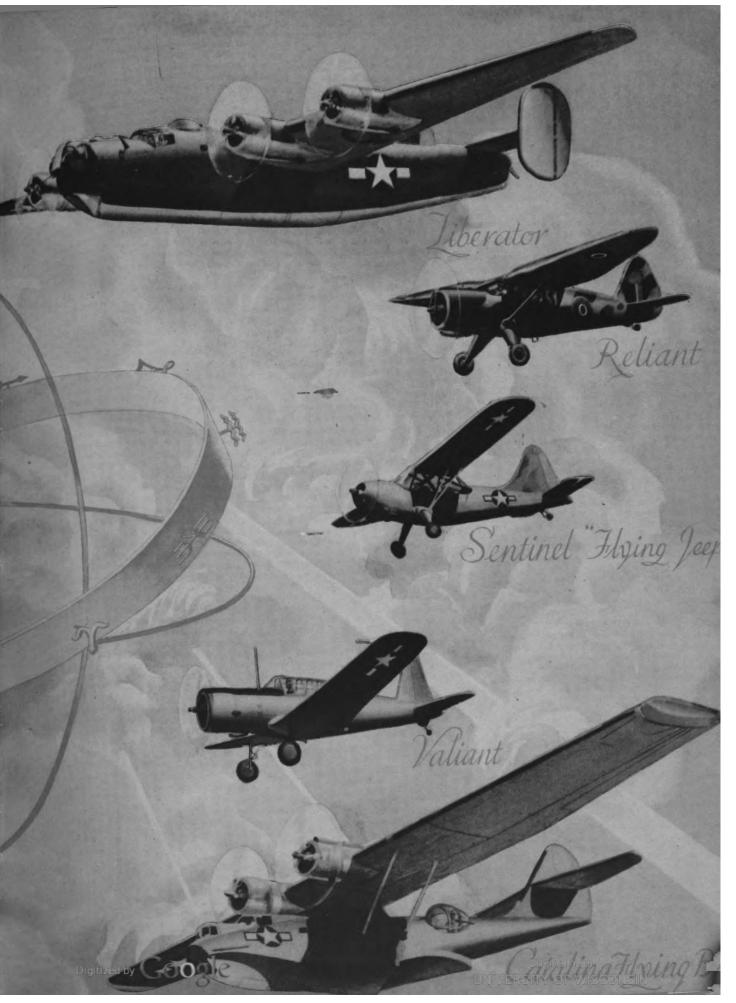
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AMERICAN AIR NAVIGATOR

ERRATA

- Page 60—after "for range reception . . . ," add "in conjunction with homing using left-right indicator"
- Page 136—Problem Work No. 29—Date: "May 1, 1943."
- Page 220—Problem Work No. 10—Answer No. 13 = 183°/41 D. R. REVIEW No. 1—Answer No. 6(a) TAS = 188 knots; Answer No. 6(b) = 191 knots. TAS.
- Page 221—Problem Work No. 14 Answer No. $4 = 52^{\circ}$; Answer No. $16 = 150^{\circ}$.
- Page 223—Problem Work No. 23—Answer No. 19, LHA = 122°E.



AMERICAN AIR NAVIGATOR

CHARLES MATTINGLY

Chief Navigator

Consolidated Vultee Aircraft Corporation



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The American Air Navigator is published by Consolidated Vultee Aircraft Corporation as a token of the organization's faith in the brilliant future of global transportation.



PREFACE

"American Air Navigator" is intended primarily for the serious student of aerial navigation, and for those actually engaged in this interesting and vital profession. This book attempts to present air navigation as it really is today; it is strictly a training text for instructional purposes, and a reference source for professional navigators.

During twelve years of actual experience as a navigator, both surface and aerial, I have attempted to read carefully every book published on the subject of navigation and, in more recent years, books on aerial navigation. One characteristic seems common to most of them—an over-emphasis of the theoretical. Obviously, there is need for thorough coverage of theory, and many of these texts cover the subject as comprehensively as present limited knowledge of this science allows.

Acting on the conviction that there is need for a book which separates practical, applicable information from the vast field of theory, and which presents such information in compact form, I have attempted to collect into this volume all the data essential to successful aerial navigation as we know it today.

The fact that the book is laid out in outline form is no coincidence. Rather, it is the writer's belief that its outline form will make the volume an easy, intelligible teaching aid, and will permit rapid reference.

Appreciation is due here to the many navigators, both surface and aerial, who have assisted me in the compilation of this book. Special credit must be given Peter Selby, without whose help and encouragement this volume might never have reached publication. Likewise, David Hellyer gave valuable assistance in editing and correlating material in the book. For the high quality of the illustrations, thanks are due the Consolidated Vultee (San Diego Division) Service Illustration Section, under the direction of Charles Bundo, Jr.

C. D. M.

June 1, 1944 San Diego



INTRODUCTION

Half a dozen years ago, the professional aerial navigator was a newcomer to the aviation industry, and virtually unknown to the public. Non-stop flights across vast stretches of ocean still were regarded with awe, and few indeed had experienced the thrill of an aerial journey to Australia, India or London.

In 1940, Richard Archbold, renowned explorer and adventurer, accomplished one of the first extended, over-water flights "without incident" in a Consolidated Aircraft Corporation airplane, the PBY "GUBA." The flight of the Guba marked a milestone in the history of aerial navigation, and helped to blaze a trail which today is followed by hundreds of giant aircraft each month.

Pioneering with Archbold in this epic adventure were veteran pilot Russell Rogers, now director of Flight and Service for Consolidated Vultee Aircraft Corporation, and S. J. Barinka, superintendent of field operations for Convair at San Diego, who acted as the Guba's flight engineer. The experience these men gained on this pioneer flight, and on scores of later trips, helps make Consolidated Vultee's flight department today outstanding in the industry.

Forced by the second World War to regard the entire globe as a flying field, aviation today considers trans-oceanic flights little more than commonplace. At this moment, no spot on earth is more than 60 hours removed from your front door—thanks to aviation—and this "time-distance" rapidly is diminishing as the industry produces faster, longer-ranged aircraft.

So, just as yesterday he was a newcomer, today the aerial navigator is symbolic of the history-making strides taken by aviation since Pearl Harbor. His importance in the stirring drama of aviation stresses the fact that global air transportation is today a reality, where only yesterday it was a fond hope and dream.

In the "American Air Navigator," Charles Mattingly, Chief Navigator for Consolidated Vultee Aircraft Corporation, has recorded much of the valuable information and experience gained during his 12 years of navigating. Hundreds of Consolidated Vultee pilots, copilots, navigators, radiomen, and engineers have received instruction in aerial navigation under Mattingly's able tutelage, and the enviable safety record of Consolidated Vultee's over-water air transportation bears witness to the accuracy and thoroughness of this instruction.

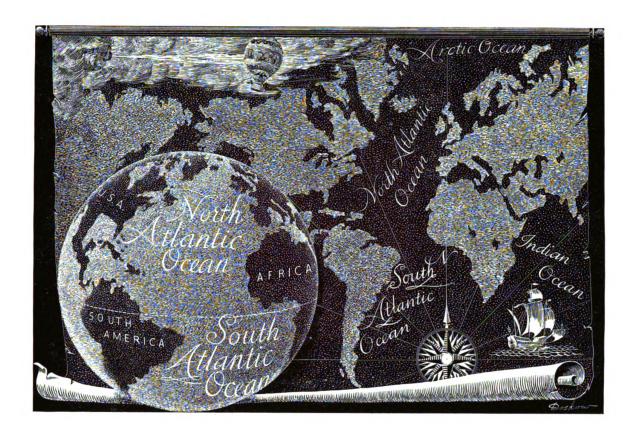
Though "American Air Navigator" is published primarily as a textbook for training the corporation's flight personnel, it is fitting that Consolidated Vultee, as a leader and pioneer in the field of global transportation, should make this vital information available to all, in the interests of advancing world-wide air travel.

TOM M. GIRDLER, Chairman of the Board, Consolidated Vultee Aircraft Corporation, San Diego, California.



AMERICAN AIR NAVIGATOR





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EARTH AND CHARTS

AN INTIMATE, working knowledge of the earth's shape, size and geography is as essential to the well-informed aerial navigator as is a knowledge of aerodynamics to the successful pilot. It is not enough that the navigator know that the earth is round. He must understand what this spherical shape means in terms of his job; he must realize that the earth's very shape gives rise to many navigational problems which it will be his duty to solve.

The navigator must think of the entire earth as his workshop. In fact, the whole universe is his laboratory, for he must employ the stars and planets themselves in his daily work. No other calling in the aviation industry—and few in any industry—requires thinking and working in such universal concepts!

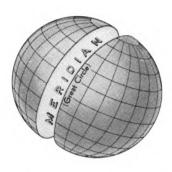
From the start, then, the navigator must prepare himself to learn a new language. He must break away from habits of thinking which have taught him to regard a neighboring city as "distant," for his work soon may make a 10,000-mile flight appear commonplace.

Realizing the necessity of thinking in global concepts, the navigator should study the following information earnestly and sincerely. If he adopts such an approach, he will find mere definitions will become living phrases to be added to his new vocabulary. A working familiarity with these terms, and a thorough understanding of their meaning, might some day mean the difference between life and death.

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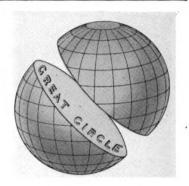


FIG. 1-GREAT CIRCLES

THE EARTH

Shape—The earth is an oblate spheroid; that is, a sphere slightly flattened at the poles. The polar diameter is about twenty-seven (27) miles less than the diameter at the equator. However, for purposes of navigation, the earth may be regarded as a sphere.

Size:

TERMS

A Sphere is a body bounded by a surface, all points of which are equidistant from a point within, called the center.

A Great Circle is an imaginary circle on the earth's surface, the plane of which passes through the center of the earth. (Figure 1)

A Small Circle is an imaginary circle on the earth's surface, the plane of which does not pass through the center of the earth. (Figure 2) Meridians are great circles passing through the earth's poles. (Figure 3)

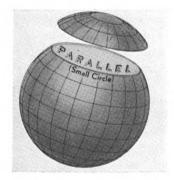
The Prime Meridian is the meridian used as reference line for the measurement of longitude. Known also as the Greenwich meridian because it passes through the Naval Observatory at Greenwich, England, it was selected arbitrarily as a reference line and is so employed by navigators of most countries of the world. (Figure 3)

Longitude is angular distance East or West of the prime meridian, measured in degrees of arc from 0°-180°. (Figure 3)

The Equator is a great circle on the earth's surface lying midway between the poles. It is used as the prime reference line for the measurement of latitude. (Figure 4)

Parallels of Latitude are divisions of latitude parallel to the equator. They are small circles on the earth's surface. (Figure 4)

Latitude is angular distance North and South of the equator measured in degrees of arc from 0°-90°. (Figure 4)



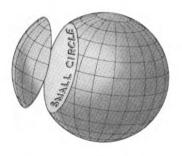




FIG. 2—SMALL CIRCLES

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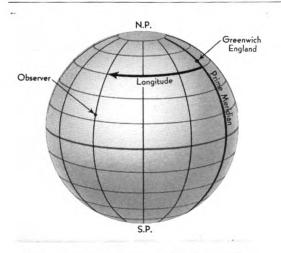


FIG. 3—MERIDIANS, PRIME MERIDIAN AND LONGITUDE

A Statute Mile is a unit of distance equal to five thousand, two hundred and eighty (5,280) feet, and is used only in over-land flying.

A Nautical Mile is a unit of distance equal to six thousand, eighty (6,080) feet, and is used in all ocean flying.

A Knot is a unit of speed and is equal to one nautical mile per hour.

A Great Circle Track is the path made good over the ground when flying a great circle course. It is the shortest distance between any two places on the earth's surface. (Figure 5)

Due to the convergence of the meridians toward the poles, the great circle track between two places will cross each meridian at a different angle, except at the equator or when the track coincides with a meridian.

A Rhumb Line is a line (or course) which intersects all meridians at the same angle. (Figure 5) Because it appears as a straight line on a Mercator chart (Figure 6) it is the course line most used in ocean aerial navigation. Actually, on the surface of the earth, it is a curved line which is sometimes known as a loxodromic curve, or equiangular spiral. On the equator, or along a meridian, the rhumb line coincides with the great circle track.

CHARTS

A Chart, or a map, is a graphic representation of a portion of the earth's surface laid out upon a plane surface.

When man first began to draw maps, the world he knew was very small indeed. His ideas about the world around him, like the maps he drew, were crude and incomplete.

At first his map-making experiments were, in all probability, attempts to satisfy a natural curiosity about his surroundings. In time, however, maps became vital necessities. Caravans to the East used them for guidance through strange lands. Ship captains felt more secure in navigating from port to port if the best available maps were aboard.

Then, as mariners gained more courage, and ventured farther and farther from sight of land, the need arose for a new type of map, a

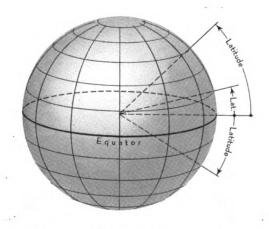


FIG. 4—EQUATOR, LATITUDE AND PARALLELS OF LATITUDE

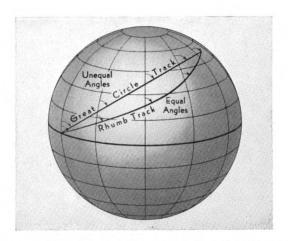


FIG. 5—GREAT CIRCLE AND RHUMB TRACK ON EARTH'S SURFACE

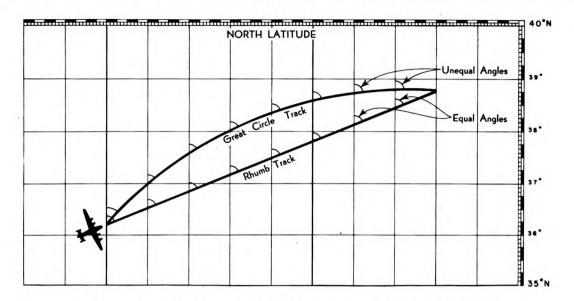


FIG. 6-GREAT CIRCLE AND RHUMB TRACK ON MERCATOR CHART

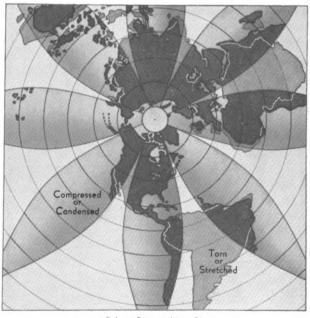
map which would represent large areas of water and adjacent or included land in some graphic manner. These maps, which dealt primarily with water areas, came to be known as charts.

Thus arose the distinction between maps

and charts: a map is primarily concerned with the land, while a chart supplies information mostly about water and land bounded by water. This distinction makes the chart especially valuable to the navigator, for whom—in fact the chart was designed.



FIGS. 7-8 SURFACE FEATURES OF EARTH DISTORTED ON PLANE SURFACE



Sphere Distorted into Plane

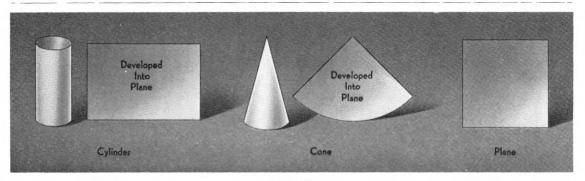


FIG. 9

FIG. 10

FIG. 11

DEVELOPMENT OF CHARTS

The Ideal Chart would be one which represented graphically the entire surface of the earth, exactly to scale, on a flat sheet of paper. However, the earth's surface bounds a sphere (Figure 7) which cannot be developed upon a plane surface for the same reason that a section of orange peel cannot be made to lie flat unless it is torn, stretched, or compressed (Figure 8). Therefore, a system of map making has been devised which permits the surface features of the earth to be projected upon surfaces capable of development into a plane.

Three Surfaces which may be developed into a plane surface are:

Cylinder (Figure 9) Cone (Figure 10) Plane (Figure 11)

Chart Projections—Charts are transferred to developable surfaces by a method known as "projection." By projection is meant to project, from the center of the earth (theoretically) the surface features of the area to be charted upon a developable surface held tangent (touching) or nearly tangent to the earth's surface. Actually, the chart is made by mathematical computation. The principle of the projection may best be illustrated, however, by imagining the eye of the observer at the center of the earth.

A certain amount of distortion of surface features will remain even when charts are made by projection. Each of the three developable surfaces will produce a chart with varying degrees of distortion. For this reason, many different types of projection have been devised, each intended to meet a specific need by embodying certain desirable characteristics while

eliminating, so far as possible, characteristics which are less desirable.

The Four Principal Projections most commonly used by the aerial navigator are:

Mercator Lambert Gnomonic Polyconic

MERCATOR CHART

Importance — Because its particular features make it best suited for ocean flying, the Mercator chart is the most important chart used in ocean navigation.

Description—The Mercator chart principle involves depicting surface features of the earth as they would appear if projected onto a cylinder held tangent to the earth at the equator (Figure 12). It is not a true geometric projection, however, since the projection point (eye) is considered to move along the earth's axis toward the poles in order that the distances between parallels of latitude will increase in the same proportion as the distances between meridians at the same latitude (Figure 13). Thus, the surface features of the earth when projected on the cylinder retain their shape, although they become proportionately larger as the latitude increases. The actual magnifying factor is equal to the secant of the latitude (a mathematical equation).

Desirable Features — The desirable features of the Mercator projection arise primarily from the fact that all meridians of longitude and parallels of latitude are represented as parallel straight lines, perpendicular to each other. As a result, positions are easily plotted on it, courses and bearings are straight lines easily measured, and charts of the same scale

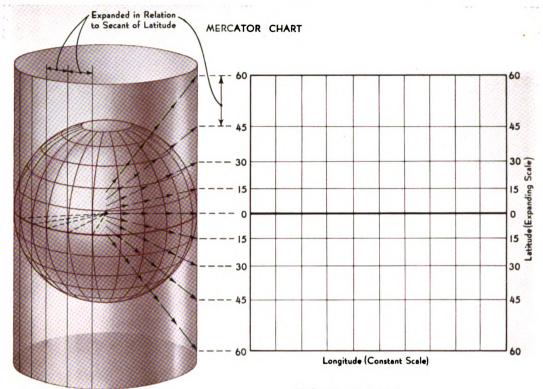


FIG. 12 Projection

FIG. 13 Development

may be joined together accurately. Other advantages are a distance scale in nautical miles, simplicity of graphic construction, and the important fact that a rhumb line appears as a straight line (Figure 14).

Undesirable Features—Perhaps the least desirable feature of this projection is the expanding latitude, which results in a non-uniform distance scale as well as in great distortion in high latitudes. Undesirable also is the fact that a great circle track—actually the shortest distance between two points—appears as a curved line, hence radio bearings must be converted to Mercator bearings (rhumb lines) for plotting.

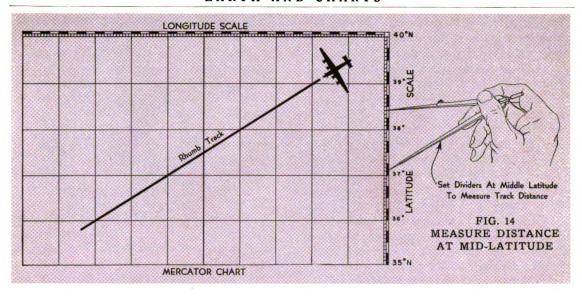
Measuring Distances — Since one minute of latitude equals one nautical mile, the latitude scale (Figure 14) is used to measure distance. However, due to the fact that latitude expands, it is necessary to measure distance at the mid-latitude of the track being measured. (Figure 14)

Graphic Construction - This method of

construction, by which the navigator may make his own chart, does not result in an exactly correct Mercator chart, although it is sufficiently accurate for obtaining a fix or plotting a position if the North and South extent is limited to 6° and latitude does not exceed 60°.

These limitations are, however, of a very general nature. Actually, for purposes of air navigation, sufficient accuracy can be obtained even when much greater extents of latitude are employed. The nearer the area to be covered by the chart is to the equator, the less distortion exists, hence the greater the area that can be included while retaining reasonable accuracy.

Graphic construction is a quick and easy method of making a chart, and charts so constructed may be used throughout the remainder of this book wherever needed. The reader is especially urged to utilize this method of construction to develop charts which he will need in connection with the problem work. Charts so constructed also can be used for actual navigation in the event the navigator should



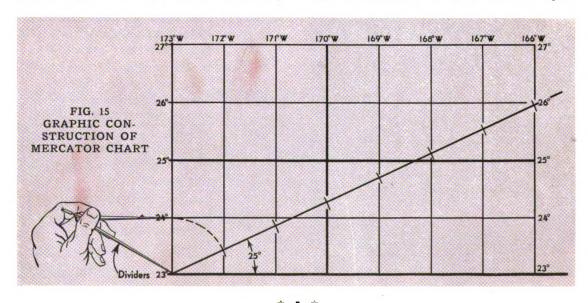
find himself without the proper plotting chart.

Example: It is desired to plot a fix which is approximately 25° North latitude, and 170° West longitude. (Refer to Figure 15)

- a. Draw a horizontal line near lower edge of paper.
- b. Erect a perpendicular to this line near left edge of paper.
- c. At the point of intersection of these two lines, draw a line making an angle of 25° with the horizontal line.
- d. Using any convenient scale, set the dividers equal to 60 units (each a "minute")

and mark off 60-unit intervals on the sloping line, and also on the perpendicular.

- e. Through these points draw lines parallel to the horizontal and perpendicular lines, and number them for latitude and longitude as per problem, making the mid-latitude 25° and the mid-longitude 170°.
- f. Through the use of the 60-unit latitude scale, the latitude of any position on the chart may be quickly found, and distances easily measured. By setting the zero and 60-unit points of the reference scale to coincide with the meridians on either side of the point



whose longitude is desired, and aligning the scale edge to pass through the point, longitude can be read directly off the scale. (Figure 15)

Construction by Meridional Parts-Since the meridians on a Mercator chart are parallel, it can be shown that the longitude must have been expanded by the secant of the latitude. Hence, in order for the projection to remain conformal, the latitude must be expanded similarly. Therefore, in constructing an accurate Mercator chart, each minute of latitude has to be multiplied by the secant of the latitude at which it is located. But a minute of latitude is equal to a minute of longitude at the equator, and since the longitude does not vary on the Mercator chart, it is customary to establish the chart scale by letting a minute of longitude equal any convenient unit of length. The length of any minute of latitude then will be equal to the length of a minute of longitude multiplied by the secant of the latitude. Thus the length of a minute of latitude at 30° North is equal to a length of a minute of longitude times the secant of 30°. As an illustration, if 1' longitude = 1/16 inch, then 1' latitude at 30° N (or S) = 1/16 inch x secant 30°.

These expanded minutes of latitude, from the equator to the poles, are known as meridional parts, and the table of meridional parts (Table No. 5, Bowditch*) gives the sum of the

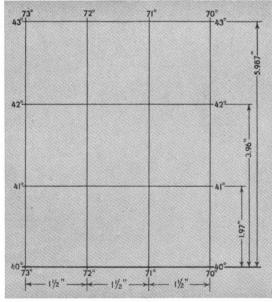


FIG. 16

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meridional parts from zero, at the equator, to the desired latitude.

Example: It is desired to construct a Mercator chart based on the following information: latitude 40° to 43° North, longitude 70° to 73° West, scale 1½ inch equals one degree of longitude at the equator, or 1/40 inch equals one minute of longitude at equator. (Refer to Figure 16)

a. Draw parallel North and South lines 1½ inch apart. Number these lines even degrees of longitude: 70°, 71°, 72°, 73° from East to West. These are the meridians.

b. Near the lower edge of the work sheet, erect a perpendicular to the meridians. Assume this line to be the principal parallel and number it 40° North latitude.

c. In the table of meridional parts, find meridional parts of principal parallel and all other parallels of latitude.

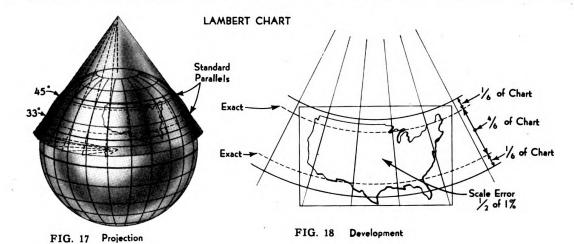
d. Compute separately the lengths of the meridians between each parallel of latitude and the principal parallel by multiplying the difference of meridional parts by the scale unit representing one minute of longitude:

2607.6	Meridional parts latitude 40°	
	(principal parallel)	
2686.2	Meridional parts latitude 41°	
78.6	Difference of meridional parts	
x 1/40"	Scale for 1' of longitude	
1.97"	Length of meridian between latitude 40° and 41°	
2607.6	Meridional parts latitude 40°	
	(principal parallel)	
2766.0	Meridional parts latitude 42°	
158.4	Difference of meridional parts	
x 1/40"	Scale for 1' of longitude	
3.96"	Length of meridian between	
	latitude 40° and 42°	
2607.6	Meridional parts latitude 40° (principal parallel)	
2847.1	Meridional parts latitude 43°	
239.5	Difference of meridional parts	
x 1/40"	Scale for 1' of longitude	
5.987"	Length of meridian between	

latitude 40° and 43°
*BOWDITCH, or Hydrographic Office Publication
No. 9. Originally published by Nathaniel Bowditch
in 1802, the volume is regarded as the "Bible" of

surface navigation by most ocean navigators.

8



e. From principal latitude 40° measure off the computed meridian lengths (1.97"; 3.96"; 5.987"), and through these points draw lines parallel to the principal latitude 40°. Number these toward the pole 41°, 42°, 43° respectively.

Note: Minutes of longitude are found by dividing the degrees into 60 equal parts. Minutes of latitude must be computed from the principal parallel, the same as degrees, if extreme accuracy is desired.

LAMBERT CHART

Description—In the Lambert chart, the surface features of the earth are projected upon a right circular cone which is made to intersect the earth's surface at two parallels of latitude, called standard parallels of the chart (Figure 17). Along the standard parallels the scale is exact, but between them there is a slight dis-

tortion due to compressing or condensing of the features (Figure 18) and beyond them expansion or stretching of features occurs. Hence, in order to maintain as nearly as possible the same limits of error throughout the chart, the standard parallels are so chosen that one-sixth of the area to be projected is above, and onesixth below, these parallels.

This chart was developed by Lambert in 1772, but it was not until the first World War that its possibilities were fully realized. At that time, the Allies used it for military maps because it afforded a maximum of accuracy in measuring directions and distances where the difference of latitude was not too great. Because of the accuracy with which it portrays topographical features, and because of the fact that, for all practical purposes, radio bearings may be drawn as straight lines, the Lambert

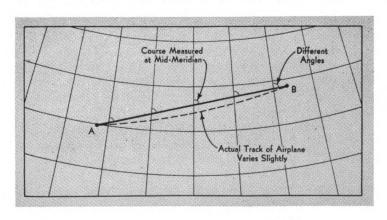
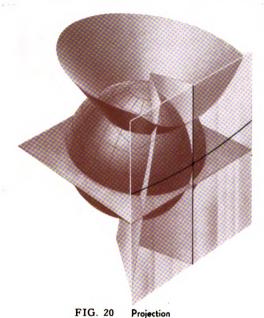




FIG. 19—MEASURING COURSE ON LAMBERT CHART





GNOMONIC CHART

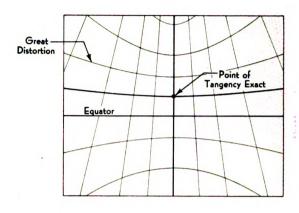


FIG. 21 Development

projection was selected by the Coast and Geodetic Survey for the development of aeronautical charts of the United States and Alaska.

Desirable Features—The scale is so nearly exact that distances may be measured directly, as though the scale were constant. A straight line very closely approximates a great circle, hence it may be considered the shortest route. This latter fact makes the chart extremely useful for radio navigation, as it is possible to plot radio bearings directly. Another advantage is that any number of charts may be joined together in any direction with perfect junctions.

Undesirable Features—Since on this projection the meridians converge, a straight course line will cross each meridian at a different angle (Figure 19). However, instead of flying a constantly changing course in order to follow a direct line, the practice generally is to measure the course at the midmeridian. Though this method of measurement causes the actual track of the aircraft to differ slightly from the course plotted, it enables the pilot to hold a constant heading (Figure 19).

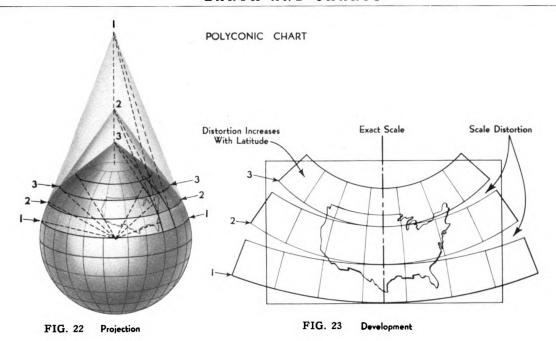
Plotting of position also is more difficult on this type of projection because the meridians and parallels of latitude are not shown as parallel straight lines as on the Mercator projection.

GNOMONIC CHART

Description—The gnomonic chart is developed by projecting a portion of the earth's surface onto a plane held tangent to the earth at a point (Figure 20). At this point of tangency, the surface features will be exact, but distortion is great in all directions away from this point (Figure 21).

Desirable Features—This chart was developed primarily in order to show true great circle tracks as straight lines. Its principal use is in measuring the shortest distance between two points and in providing a graphic method of plotting the great circle track. The great circle track, drawn as a straight line on the gnomonic chart, is divided up into a series of chords, and the coordinates of these chords may then be re-plotted upon the Mercator chart for actual navigation.

Undesirable Features—Great distortion of the surface features in all areas except at the one point of tangency, and great difficulty in plotting positions because of a non-uniform scale are the principal drawbacks to this type of chart.



POLYCONIC CHART

Description—The polyconic chart derives its name from its method of development, which involves projecting from the center of the earth a portion of the surface features onto a series of cones, each tangent to the earth's surface at a different parallel of latitude, but having a common axis (Figure 22). This chart (Figure 23) is useful for small areas where accuracy of topographical features is most important, since it incorporates even less distortion error than the Lambert chart.

Desirable Features — The scale being almost exact near the central meridian, even for

large North and South areas, it is a highly desirable projection for pilotage charts, such as harbor and small coast line charts. It is used also by U. S. Army Engineers for fire control and tactical maps.

Undesirable Features—Use of the chart for practical navigation is limited to small areas for several reasons. The type of distortion inherent in this projection limits its use to charts of wide latitude and narrow longitude. On larger charts, positions are difficult to plot and courses are hard to measure because the meridians are curved and the parallels of latitude do not intersect them at right angles.



PROBLEM WORK

- No. 1 Make drawings showing principle of the Mercator, Lambert, and gnomonic projections. List desirable and undesirable features of each.
- No. 2 Construct graphically a Mercator chart for an area extending 2° North and South of latitude 25° N., and 2° East and West of longitude 127° W.

☆ 11 ☆





☆ 2 ☆

INSTRUMENTS

UST as the entire globe is the aerial navigator's workshop, so his aircraft's navigational instruments are his most important tools. Those to be discussed in this chapter are the instruments actually employed by the long-range navigator for extended, over-water flights. Included are:

Compass
Altimeter
Airspeed Indicator
Thermometer
Chronometer
Drift Meter

Not included in this chapter are discussions

of the radio compass and the aircraft octant. Each of these is sufficiently important to merit detailed treatment in later chapters.

No attempt is made to describe the construction of instruments discussed in this chapter except where such descriptions are vital to an understanding of their actual use. Detailed mechanical descriptions are, for the most part, left to manufacturers' manuals, which are available to those interested in the construction and servicing of these units. Furthermore, all aircraft instruments are subject to such change that any text which attempted to describe them in detail might well be rendered obsolete overnight.

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The stress in both text and illustrations, therefore, is laid on principle and use of these navigational "tools," rather than on their physical make-up.

COMPASS

Description — Both functionally and historically, the compass is first and foremost among all navigational instruments. Briefly, the compass is an instrument which points in a constant direction regardless of the aircraft's movements, and from which, by reference to a graduated card, the aircraft's direction of flight may be determined. The earliest-type compass probably was discovered when ancient navigators learned that a piece of lodestone or a magnetic needle, when floated on a cork in a bowl of water, would point in a constant direction, thus enabling them to navigate their sailing ships without reference to landmarks. Refinements on this early compass were made through the centuries, and the process of refinement continues today.

In recent years several other scientific principles have been utilized in attempts to develop a compass which would be even more reliable and constant than the magnetic compass. Among principles utilized are those of the gyro, and the movements of celestial bodies.

- 1. Gyro Compass—The gyro compass has proved highly successful aboard surface ships, but so far no model light and rugged enough for aircraft use has been developed. It has great future possibilities because it indicates the true North pole, and is, therefore, the ideal in compass construction. Its directive force is obtained mechanically by means of a rotating gyro which automatically aligns its axis with the true axis of the earth. The principle of this compass is derived from Foucalt's Law, which states that a spinning body (the gyroscope) tends to swing around so as to place its axis parallel to the axis of any impressed force (the force in this case being the earth spinning on its axis).
- 2. Sun Compass The sun compass is a special instrument designed for use in polar regions where the magnetic compass may be uncertain. It indicates direction by means of the sun, utilizing the principle of the sun dial. It has to be set continuously to local apparent

time, and the sun's shadow indicates direction of flight.

MAGNETIC COMPASS

Description — Though many attempts are being made to develop compasses operating on various scientific principles, the magnetic compass, greatly refined since the ancient navigator's floating lodestone, is still the most dependable and least liable to mechanical failure. For this reason, and also because it is the most fundamental of all navigational instruments, the magnetic compass should be thoroughly understood by the navigator.

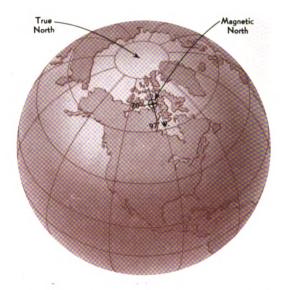


FIG 24—LOCATION OF MAGNETIC NORTH

The Directive Force of the magnetic compass is the magnetic field surrounding the earth. The magnetic compass, therefore, does not point to the true North pole but towards the magnetic North pole, which is approximately 1200 miles away from the true North pole, just north of Hudson Bay in about latitude 70° North, longitude 97° West (Figure 24). This difference between true North and magnetic North causes an error in the compass reading known as variation, which will be discussed thoroughly later on.

Principle — From elementary physics one learns that when two magnets are brought together, like poles repel and unlike poles attract





each other. Also, that the earth itself exhibits the properties of a great magnet, having North and South magnetic poles (Figure 25). Therefore, when a magnet is fully supported in space and is free to rotate in a horizontal plane, it tends to align itself with the earth's magnetic field, its ends pointing toward the North and South magnetic poles.

Dip—Notice in Figure 25 that the magnetic lines of force are parallel to the earth's surface at the magnetic equator, but that on either side of the equator they dip toward the poles, becoming vertical at the poles themselves. Because of this fact, the compass magnets also dip toward the poles appreciably in higher latitudes. For this reason the magnetic compass is not reliable in polar regions.

The Basic Construction of all magnetic compasses is similar, consisting of a card, graduated in degrees, to which is attached a magnet, or group of magnets, parallel to the North and South axis of the card. The whole card assembly, freely supported on a pivot, is contained in a non-magnetic bowl.

There Are Many Types of magnetic compass which have been developed for aviation and marine use, each designed for best performance under different conditions, but all constructed on the same basic principle. Two magnetic compasses, of different types, usually are installed in airplanes designed for long-range flying. They are:

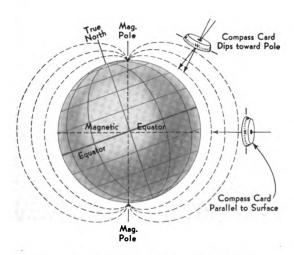


FIG. 25—EARTH'S MAGNETIC FIELD



Courtesy Eclipse Pioneer Division Bendix Aviation Corporation.

FIG. 26-APERIODIC COMPASS

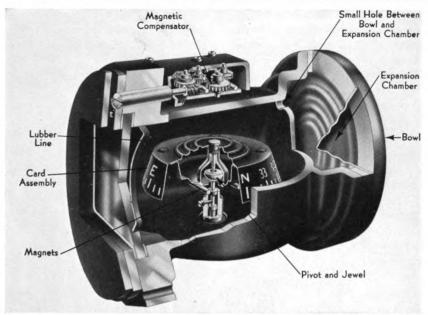
- 1. Aperiodic compass (the navigator's compass) (Figure 26).
 - 2. Pilot's compass (Figure 27).

The aperiodic compass was designed especially for aerial navigation. It is easy to read and is so constructed that the compass card, when deflected from a position of equilibrium, will return to its heading slowly and positively and will not oscillate about the point of reading.

The Principal Parts of the magnetic compass (Figure 27) are the following:

- 1. The Compass Card usually is graduated in degrees. The four cardinal points (North, East, South and West) are lettered N, E, S, W. Some compasses, such as the aperiodic, show 1° graduations, but many of the pilots' type have only 5° graduations with every 30° numbered. The pilots' type compass is viewed from the side opposite its heading. The N marking, if viewed from the top, would actually be on the South end of the card. Because this compass is viewed "in reverse," the degree markings are backwards. Therefore, a change of heading causes the card to appear as though it were turning in the wrong direction.
- 2. The Magnetic Elements which supply the directive force to the card usually consist of a small bundle of hardened steel, magnetized needles. Magnetized needles are used because their magnetic influence is stronger than that of a single magnet. Two or more of these ele-





Courtesy Eclipse Pioneer Division Bendix Aviation Corporation.

FIG. 27-PILOTS' TYPE MAGNETIC COMPASS

ments are secured to the underside of the compass card parallel to the North and South axis.

- 3. Pivot and Jewel—The pivot, made of hardened steel, balances the card and magnets on a jeweled support, usually a sapphire. This arrangement reduces friction and wear so that the card and magnets are as freely suspended as possible. A shock-absorbing spring keeps the pivot on the jewel and also insures maximum protection from vibration.
- **4. The Bowl** is cylindrical. It is constructed of non-magnetic material to provide a housing for the card assembly and a container for the dampening fluid.
- 5. The Lubber's Line is usually a thin wire fixed to the center line of the bowl just clear of the freely-moving card assembly. Since the card always points in the direction of magnetic North, when the bowl is turned (as the airplane turns) the lubber's line, fixed to it, also turns and so indicates the amount of turn on the graduated card.
- 6. The Dampening Fluid is colorless, acidfree kerosene which completely fills the bowl. Its purpose is to dampen excessive oscillations of the card assembly, and to reduce shock, vibration, and friction of the pivot by supporting most of the weight of the card assembly. It

also prevents corrosion and keeps the jewel washed clean of foreign matter.

- 7. The Expansion Chamber is either a thin metal diaphragm, located in the liquid, or a hollow chamber in the top of the bowl, which keeps the bowl completely filled at all times by balancing the expansion of the liquid due to temperature changes.
- 8. Compensating Magnets usually consist of two sets of screw-adjustable magnets located either above or directly beneath the compass card. Both sets of magnets are arranged in the horizontal plane, but one set is placed so that it will lie on the fore and aft axis of the airplane, and the other so that it will lie on the athwartship axis. These magnets set up a compensating field which, when properly adjusted, greatly reduces the error known as deviation. Deviation is caused by local disturbing magnetic forces inherent in the aircraft itself, such as those created by engines, ferrous metals, and electrical circuits.

Location and Installation—The magnetic compass should be located where it may be easily read, but as far removed as possible from all sources of artificial magnetic disturbance. All direct current wires nearby should be closely twisted or they will set up a magnetic



field. The compass should be installed so that the planes of the lubber's line and the card pivot are vertical and parallel to the fore and aft axis of the aircraft. When so installed, the lubber's line will indicate the correct heading on the compass card, and the card assembly itself will be level in normal flight.

Compensation—To compensate a compass means to remove as completely as possible all error due to local disturbing magnetic forces existing in the aircraft. The procedure follows:

- a. Before starting to compensate, place the airplane on some part of the field free from any artificial magnetic disturbance, such as power lines, pipes and steel structures.
- b. Determine the correct magnetic heading of the airplane. There are two recognized methods of doing this:

By reference to a magnetic compass rose. By means of a pelorus.

- (1) By Compass Rose. This is the easiest and most common method. The magnetic compass rose is a large compass card laid out on the ground to indicate correct magnetic directions at every 15° or 30° throughout the 360°, starting at magnetic North. It is large enough so that the aircraft being compensated may be accurately headed on each of these 15° intervals.
- (2) By Pelorus. The pelorus is a dummy compass card upon which sighting vanes may be arranged to take bearings on distant objects. These distant objects may either be objects on the earth, or celestial bodies (usually the sun). For compass compensation the magnetic bearing of the object to be used is first determined. The airplane may then be directed on any correct magnetic heading by reference to the pre-determined bearing. Knowing this method is of advantage because it may be used in the air to check compass error while flying a constant heading.

To continue compensation procedure:

- c. Center compensating magnets, or, if they are the removable type, remove them.
- d. Simulate all conditions of normal cruising operation and reduce to a minimum any deviation error caused by electro-magnetic influences (by shifting position of, and twisting together, direct current wires). With tail elevated and engines running, turn on and off the radio

receiver, radio transmitter, navigation lights, panel lights, Pitot-static tube heater, and generator. Check position of head sets, control positions and engine operation. Check individually and in practical combinations, on every 30° heading, the effect on the compass of these various influences. Any deviation remaining should not exceed 15°, and the ideal would be 0°. The compass is now ready for compensation.

- e. Adjust compensating magnets to reduce remaining deviation as much as possible by the following procedure:
- (a) Head the aircraft correct magnetic North. Adjust athwartship magnet (marked "N.S."), with a non-magnetic screwdriver, so the compass reads "N."
- (b) Head the aircraft correct magnetic East. Adjust fore and aft magnet (marked "E.W.") so compass reads "E."
- (c) Head the aircraft correct magnetic South. Adjust "N.S." magnet to reduce by one-half any error remaining on this heading.
- (d) Head the aircraft correct magnetic West. Adjust "E.W." magnet to reduce by one-half any error remaining on this heading.

The deviation error in the compass now has been corrected for as much as possible, and the remaining error will have to be recorded and applied to all headings flown.

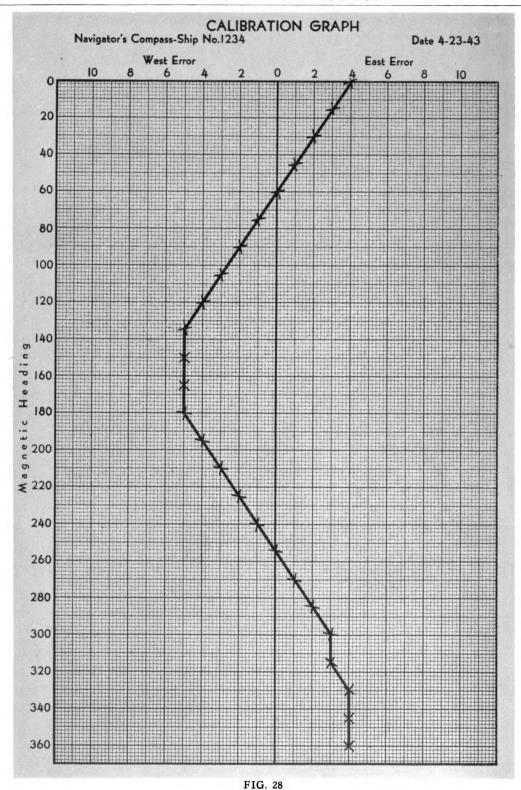
Calibration—Calibration is the determination and recording of existing deviation error, for use in flight. The amount of deviation error remaining in the compass on each compass heading is determined by swinging the aircraft through a complete circle and recording the error on each 15° heading. The error also should be recorded for actual flight conditions with radio and lights, on and off. With this information a curve of the deviation error is plotted which shows the amount of correction to be applied to any heading. A calibration graph is shown in Figure 28.

As is apparent from the above discussion, there are two basic errors in all magnetic compasses, namely, *variation* and *deviation*.

Variation—Variation is the angular difference, measured at the airplane, between *true North* and *magnetic North* (Figure 29).

The amount of variation error affecting a magnetic compass generally ranges from 0° to





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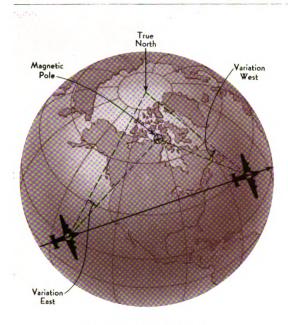


FIG. 29—VARIATION

about 40°, either East or West, depending upon an aircraft's geographical position. However, in polar regions variation up to 180° may be encountered. Besides changing with a plane's geographical position, variation also undergoes a progressive annual change which in the course of several years becomes appreciable, but which need not be considered for shorter periods.

The amount of variation for different geographical positions on the earth is indicated on all air navigation charts by lines connecting points of equal magnetic variation called isogonic lines. The line connecting points of zero variation, found wherever the plane's position is in line with the true and magnetic poles, is called the agonic line. The amount of annual change of variation also is noted on the face of the chart.

Deviation—Deviation is the angular difference, measured at the airplane, between *compass North* and *magnetic North* (Figure 30), compass North being the direction indicated by the compass needle.

Deviation error, as can be seen on the calibration chart (Figure 28), varies for each different heading of the aircraft. Therefore, it has to be applied on every change of heading. This error is recorded as accurately as possible. However, many conditions in the air may cause it to vary. These may be local magnetic attractions in the area being flown over, or acceleration and swirl errors caused by speed, turns and vibrations, or mechanical failure of the compass itself. These additional errors may be reduced somewhat by lightly tapping the compass before reading, and only reading it when flying straight and level at a constant speed.

Note: Great stress has been placed by some writers of aerial navigation textbooks on the importance of knowing exact deviation. The author agrees that if the navigator were entirely dependent upon dead reckoning, such knowledge would be essential. He wishes to point out, however, that it seldom is necessary for the long-range aerial navigator to depend solely upon dead reckoning for more than a few hours. Usually it is possible to check the plane's position either by visual or celestial When this is possible, temporary changes in deviation from those tabulated cease to be a serious consideration, since any unknown compass error simply combines with the unknown wind to yield a total error which can be accurately determined between fixes. This would, of course, mean that the wind calculated would not be entirely accurate since it

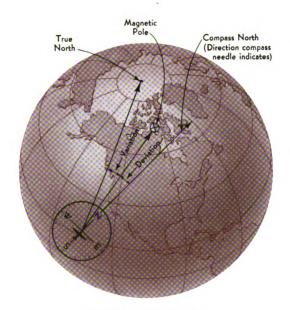


FIG. 30—DEVIATION

would include some deviation error not known, hence not allowed for. And while error in reporting the existing winds is certainly undesirable from a meteorological viewpoint, it in no way endangers the safety of the aircraft. Thus there is no real basis for the rather prevalent belief that an aircraft will become lost if exact deviation is not known. (Application of compass errors is covered in Chapter III).

ALTIMETER

Description—An aircraft altimeter (Figure 31) is an instrument which measures existing air pressure in the same way as does a barometer, the only difference being that the altimeter scale is graduated to read in feet of altitude rather than inches of mercury.

Indicated Reading Errors

- 1. Constant Error is instrument error of a permanent nature which can be calibrated, hence compensated for by proper application of the calibration correction to each instrument reading. Such error usually is due either to faulty construction or installation of the instrument. However, such error does not always exist.
- 2. Variable Error is caused by variations in atmospheric pressure and changes in temperature. This error likewise may be corrected if existing conditions are known. Since the instrument is actuated by atmospheric pressure, which is a variable factor, the manufacturer graduates the instrument card under artificial, simulated standard conditions.



FIG. 31-ALTIMETER

Standard conditions are:

At sea level-

Air pressure = 29.92" Hg.

Temperature = $+15^{\circ}$ C.

For change in altitude-

Air pressure decreases approximately one-half for each increase in altitude of 18,000 feet.

Temperature lapse rate is approximately 2 C per 1000 feet.

Due to changing weather phenomena, these standard conditions seldom are encountered. Therefore, it is apparent that an instrument graduated to standard conditions normally would read with a certain amount of error. To compensate the indicated reading for variable air pressure, a knob is provided on the altimeter which enables the dial to be rotated to agree with actual barometric pressure. Temperature variations are accounted for by calculation.

Altimeter Uses—The altimeter measures the altitude of the aircraft above any given point on the earth's surface. Therefore, it may be used for two purposes:

- 1. To measure the aircraft's height above an airport, regardless of the airport's altitude, or
- 2. To measure the height of the aircraft above sea level.

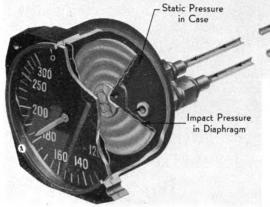
In over-ocean navigation, the navigator is interested primarily in the true altitude above sea level, obtained as follows:

- a. Set altimeter to standard sea level pressure (29.92" Hg.). The altimeter then will read as pressure altitude.
 - b. Note outside air temperature.
- c. Again adjust altimeter to latest known barometric pressure. The altimeter then will read as indicated altitude. (This barometric pressure may be obtained by radio contact with the nearest ground station or from the isobars indicated on the latest weather map).
- d. On the computer set air temperature opposite pressure altitude. Read true altitude opposite indicated altitude. (Computers vary slightly but give similar results).

AIRSPEED INDICATOR

Description—The airspeed indicator (Figure 32) is an instrument for measuring the aircraft's speed with reference to surrounding air.

The principle of operation is as follows: A tube, known as the Pitot (pee-tow) tube, is placed forward, outside of the aircraft, and clear of the slipstream. Impact air pressure upon this tube is relayed to a metallic diaphragm inside the instrument. The diaphragm also is affected by existing atmospheric density, and in order that the diaphragm will be responsive to true barometric pressure, a second



Courtesy Eclipse Pioneer Division Bendix Aviation Corporation. tube, called the static tube, is mounted alongside the impact tube. The static tube relays the actual, static atmospheric pressure outside the aircraft to the interior of the airspeed meter case surrounding the metallic diaphragm. The excess of impact pressure over static pressure expands the diaphragm, which in turn actuates a dial graduated in terms of air speed at sea level and under standard atmospheric conditions.

The impact tube and static tube mounted together are called the Pitot-static tube. In some newer installations, the Pitot and static tubes are mounted separately.

The airspeed indicator does not indicate the true air speed of the aircraft, mainly because of installation errors and the fact that it is actuated by variable atmospheric pressure. For this reason the following terms are employed to indicate what corrections, if any, have been applied.

Indicated air speed Calibrated air speed True air speed

Indicated Air Speed—Indicated air speed is the speed as read on the instrument.

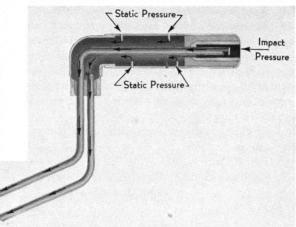


FIG. 32-AIRSPEED METER AND PITOT TUBE

It is based upon standard velocity head values at sea level and standard atmospheric pressure. It does not, however, take into account variations in pressure altitude, air temperature or Pitot-static tube installation errors. Therefore, it is necessary to apply certain corrections to obtain true air speed.

Some aircraft airspeed indicators read directly in knots, although most indicators read in statute miles. In ocean aerial navigation, all distances are measured in nautical miles. Therefore, if the aircraft is equipped with an instrument graduated to read in statute miles, convert the reading into nautical miles before applying further corrections.

Example: 175 m.p.h. indicated = 152 knots indicated.

Calibrated Air Speed—Calibrated air speed is simply correct indicated air speed, i.e., instrument reading corrected for Pitot-static tube installation error and minor instrument calibration crror.

The instrument error usually is slight, but the installation errors in some aircraft are quite large, depending upon the location of the Pitotstatic tube.

Several methods are employed for finding the corrections which must be applied to indicated air speed in order to determine calibrated air speed (correct indicated air speed).

One method often used is to fly over a measured course at various speeds, noting the elapsed time.



Another method is to trail a "static bomb," an instrument which indicates correct air speed, having previously been calibrated in a wind tunnel. Regardless of the method used, the calibrated air speed, when found, is recorded in each individual ship along with corresponding indicated air speeds for future reference in flight.

Flight performance manuals usually show the calibration thus:

For PBY:

Indicated air speed of 102 knots = calibrated 109 knots.

For B-24:

Indicated air speed of 175 m.p.h = calibrated 176 m.p.h.

Note: Calibration error correction for different speeds varies but slightly. Therefore, the same amount of calibration error correction is applied to all indicated air speeds.

True Air Speed—True air speed is the actual speed of the aircraft with reference to the surrounding air, and is obtained by correcting the calibrated air speed (correct indicated air speed) for existing temperature and pressure altitude of the aircraft.

The airspeed meter is graduated for sea level and standard atmospheric pressure, but since atmospheric density decreases as altitude increases, the excess of impact pressure over static pressure also decreases, causing the true air speed to be (nearly always) greater than the indicated air speed.

Air Speed Correction Problems:

Temperature = $+10^{\circ}$ C.

Pressure altitude = 10,000 feet.

Example No. 1

Indicated air speed = 102 knots Calibration error correction = +7 knots

Calibrated air speed $= \overline{109}$ knots

True air speed = 131 knots

Example No. 2

Indicated air speed = 175 m.p.h. Calibration error correction = +1 m.p.h. Calibrated air speed = $\overline{176}$ m.p.h.

Calibrated air speed = 153 knots True air speed = 183 knots

Note: (Use the aircraft computer in converting m.p.h. into knots and in finding true air speed from calibrated air speed).

THERMOMETER

Description—The thermometer is an instrument used to measure the free air temperature outside the aircraft.

It operates on the principle that a substance expands or contracts with an increase or decrease of heat. The aircraft thermometer utilizes a thin, coiled, bi-metallic strip which on expanding or contracting actuates a dial graduated in degrees of temperature.

Two temperature scales commonly used are the Fahrenheit and Centigrade scales. They differ only in the size of graduation intervals.

The Fahrenheit scale is so graduated that 32° equals the freezing point of water and 212° equals the boiling point of water at sea level, under standard atmospheric conditions.

The Centigrade scale, more often used in aircraft, is graduated so that 0° equals the freezing point of water and 100° equals the boiling point.

CHRONOMETER

Description—A chronometer is a very accurate timepiece.

The aircraft chronometer is a watch of exceptionally fine construction and usually has a

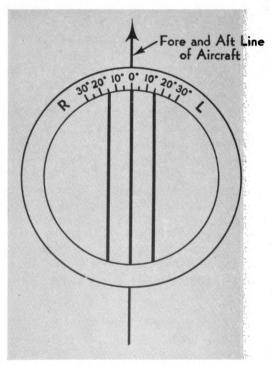
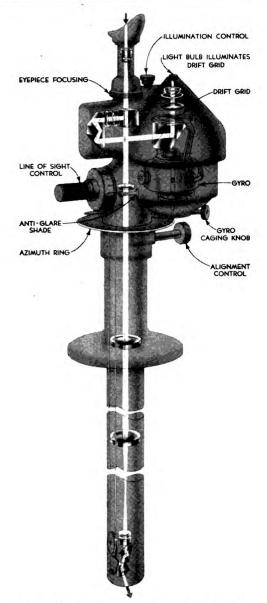


FIG. 33-SIMPLE DRIFT METER



Courtesy Eclipse Pioneer Division Bendix Aviation Corporation.
FIG. 34—TYPE B-3 DRIFT METER

24-hour dial with a stop-second hand which enables it to be set for zero error. Since it is a precision instrument, it should be handled with the greatest of care. It should be wound at the same time each day, and kept in a case to protect it as much as possible from temperature changes and shock.

The chronometer is set to Greenwich civil time, and should be checked frequently either by reference to a master watch or from radio time signals (ticks), in order to determine its "rate." The rate is the amount it gains or loses each day. As long as the rate is constant and not more than a few seconds each day, a record can be kept so that correct time will always be had by applying the amount of gain or loss since the last accurate check. If the rate is erratic, the watch should be sent to a jeweler for repair.

DRIFT METER

General—Drift represents the effect of crosswind on the aircraft's heading. If the wind's force and direction were accurately known it would be easy to calculate drift. Unfortunately, however, no reliable method yet has been devised to accurately pre-determine the wind force and direction for any proposed flight. Therefore the navigator must use all available methods to measure the aircraft's drift while in the air. The easiest method of doing this is by means of a drift meter, which is an instrument for determining the angle at which an aircraft is drifting to the right or left of its course.

The Simplest Type of drift meter (Figure 33) is a grid of parallel lines, installed in an opening in the floor of the aircraft. The center line, when parallel to the fore and aft axis of the aircraft, is marked 0° drift. In flight, the number of degrees to the right or left which the grid must be rotated in order to align the grid lines with the apparent motion of the ground, is the angle of drift.

A Refined Type of drift meter is the type B-3* (Figure 34). It utilizes the same principle as the type above described except that the ground is viewed through an optical system, and the grid is kept parallel to the ground by a self-erecting gyroscope. Besides an azimuth scale for reading drift or taking visual bearings through 360°, the B-3 meter incorporates a graduated line of sight control which can be used either for reading drift or measuring the vertical angles used in computing ground speed.

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^{*}A complete description of the B-3 drift meter may be found in Air Corps Technical Manual No. 205 or in the Bendix Instruments Manual.

Caution—Many types of drift meter have been devised, and their correct use makes accurate dead reckoning navigation possible. However, it should be remembered that a drift meter is a mechanical device, and therefore liable to error. The drift meter should be used whenever possible, but only as an added help to celestial navigation and other available navigation aids.

Use of Type B-3 Drift Meter to Measure Drift:

- a. Turn on the gyro and, when it has attained operating speed (3 to 5 minutes), release the gyro caging knob which is located under the gyro housing. The gyro should be released only in level flight and should be caged during maneuvers or when the gyro is not in use.
- b. Adjust the light rheostat so that the grid and the image on the ground are easily seen.
- c. Rotate the instrument until the apparent motion of a whitecap, object on the ground, or a signal device previously dropped from the aircraft follows the fore and aft grid wires. The drift angle then is read on the azimuth scale.

Note: By rotating the line of sight control, the ground object may be viewed directly beneath or to the rear of the aircraft.

Use of Type B-3 Drift Meter to Determine Ground Speed: Ground speed may be determined by the following formula after measuring the time (in seconds) it takes for an object on the ground to pass over a convenient angle, measured on the line of sight control.

Formula for ground speed-

Ground speed =
$$\frac{\text{Altitude}}{\text{Time}} \times \text{Factor}$$

[For factor see factor table (Figure 35)]

One procedure is as follows:

- a. Determine the true altitude.
- b. Uncage gyro and allow five minutes for it to erect itself.
- c. With the line of sight control set at 0° (starting angle), sight a ground object on the center athwartship grid wire and follow its motion by revolving the line of sight control for ten seconds. (The line of sight control may be set other than at 0° at start and the time al-

lowed may be other than 10 seconds; however, the method cited simplifies solution.)

- d. Read the angle on the line of sight control (finish angle) and obtain the factor by inspection of the factor table (Figure 35).
 - e. Compute formula.

Example No. 1

True altitude = 10,000 feet

Start on line of sight control 0°, finish 18° Total time = 10 seconds.

$$\frac{10,000 \text{ ft.}}{10 \text{ sec.}} \times .1932 =$$

 $1,000 \times .1932 =$

193.2 knots ground speed.

Note: Factor (.1932) is for finish angle 18° and is found by interpolating between 15° and 20° as follows:

$$.159 = 15^{\circ}$$
 factor

$$.216 = 20^{\circ}$$
 factor

$$.057 = difference$$

$$3/5$$
 of $.057 = .0342$

$$.159 = 15^{\circ}$$
 factor

$$+.0342 = 3^{\circ}$$
 of difference

$$.1932 = 18^{\circ}$$
 factor

FAC	TOR 1		FOR C		D SPE	ED
Finish			Starting	g Angle		
Angle	0°	10°	20°	30°	40°	50°
5°	.052					41
10°	.104		LILL I			
15°	.159	.054				
20°	.216	.111				
25°	.276	.172	.061			
30°	.342	.238	.126			-
35°	.415	.310	.199	.073		
40°	.497	.392	.281	.155		
45°	.592	.488	.377	.250	.095	
50°	.706	.601	.490	.364	.209	
55°	.846	.741	.630	.504	.349	.140
60°	1.026	.922	.810	.684	.529	.320
65°	1.270	1.165	1.054	.928	.773	.564
70.9°	1.706	1.602	1.490	1.364	1.209	1.000

FIG. 35

Practical Alignment — For accurate drift meter readings it is necessary that the drift wires be parallel with the longitudinal axis of the aircraft, and that the azimuth scale read 0° forward and 180° aft when the drift wires are thus aligned.

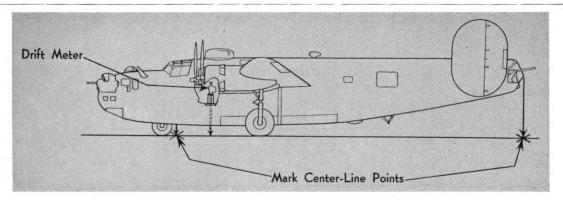


FIG. 36-ALIGNING DRIFT METER (SIDE VIEW)

This alignment may be accomplished quickly and accurately enough for practical navigation by means of a length of string and a plumb bob. The procedure is as follows: (see Figures 36 and 37)

- a. Establish center line of aircraft by dropping a plumb bob from center of tail and center of nose (or center line behind nose wheel, if tricycle landing gear). (Figure 36)
- b. Drop plumb bob from center of drift meter coverglass, and mark point vertically be-

neath on ground. Measure distance of this point from center line and then measure out a similar distance from the fore and aft center points. Through these three points hold a string parallel to center line (Figure 37).

c. Rotate drift meter, with gyro caged, sighting the string line fore and aft by turning line of sight control until parallel wires of drift meter are aligned with string line. Azimuth drift scale should then indicate 0° forward; if not, loosen screws and adjust azimuth ring.

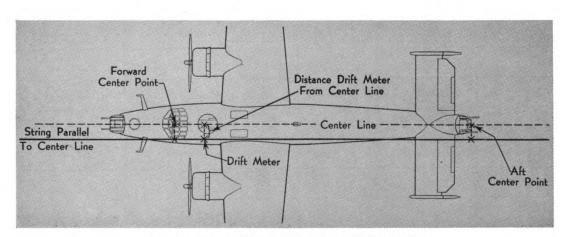


FIG. 37—ALIGNING DRIFT METER (TOP VIEW)



PROBLEM WORK

No. 3 Draw diagram of pilots' type magnetic compass and indicate the principal parts.



PROBLEM WORK NO. 4

ALTIMETER CORRECTION

(Find true altitude. Use computer.)

No.	PRESSURE ALTITUDE	INDICATED ALTITUDE	TEMPERATURE	TRUE ALTITUDE
1	7500′	8000′	+ 10°C	
2	3300′	3000′	+ 15°C	
3	24,000′	23,000′	— 22°F	
4	10,000	11,000′	0°C	
5	4500′	5000′	+ 15°C	
6	16,400′	17,000	+ 14°C	
7	1700′	2000′	+ 10°C	
8	8000′	8400′	+ 18°C	
9	17,000	16,500′	+ 32°F	
10	15,000′	14,000′	0°F	
11	5500′	6000′	+ 12°C	
12	1000′	1300′	+100°F	
13	2750	3000′	− 7°C	
14	10,000′	9500′	+ 15°C	
15	8500′	8000′	+ 15°C	
16	6000′	5900′	+ 20°C	
17	7500	7500′	0°C	4
18	9500′	10,000′	— 5°C	
19	8000′	8500′	+ 42°F	
20	13,000	12,400	— 16°C	

PROBLEM WORK NO. 5 AIR SPEED CORRECTION

If	I.A.S in m.p	.h. =	90	100	110	120	130	140	150	160	170	180	190	200	210		
Th	en C.A.S. in m.p.	.h. =	90	102	113	124	135	146	157	168	178 185 19		196	204	212		
No.	I.A.S. (m.p.h.)	C.A (m. ₁	A.S. o.h.)			.A.S.			SSUF		т	EMP.			r.A.S. knots)		
1	142							11	,000			0°C					
2	160								3000			3°C					
3								V.	6000		+	42°F		1	85		
4									9000′		+	21°F		1	91		
5	163								7000′		-	3°C					
6									3000′		+	32°F		1	65		
7	145								6000′		+ 4°C		+ 4°0				
8									9000,		+42°F			1	92		
9	158								2000′		+	1°C					
10	139								4000′		-	- 6°C					
11	151								9000′		+	-18°Ç					
12						_			3000′		-	- 1°C		1	82		
13	165								6000′		+	-26°F					
14	180							14	ł,000 ′		_	- 6°C					
15	186							11	,000′		+	-14°C					
16	157								1000′		+	-76° F					
17									6000′		+	-19°C		1	86		
18									9000′		+	- 6°C		1	95		
19	180								8000′		+	-14°F					
20	121								3000′		+	-23°F					





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DEAD RECKONING

THE term "Dead Reckoning" is commonly supposed to have evolved from "Deduced Reckoning." First, "Ded. Reckoning" as an abbreviation, the form eventually became "Dead Reckoning" for convenience.

Dead Reckoning (DR) is the basic method of determining the location of an aircraft with reference to a known position by keeping an account or reckoning of the estimated distance flown and calculated track made good. It involves taking into account all available knowledge of time, speed, drift, heading, track, and weather conditions. If the direction and velocity of the wind actually were known, the dead

reckoning position likewise would be very accurate; however, weather data quite often is vague, and different navigators using the same information probably would obtain varying results.

One navigator, after making several flights across the South Atlantic with unusually correct DR calculations (in which luck certainly played a part), applied for employment with a different company. In his application he stated: "I feel I should be hired because of my unusual 'homing pigeon' instinct!" He wasn't hired, as his colorful claim was entirely without foundation.

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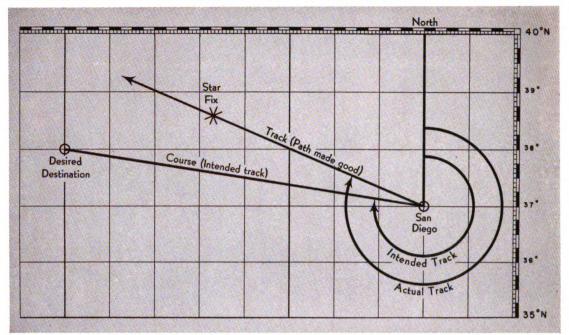


FIG. 38-TRACK AND COURSE

When a navigator continuously calculates fairly accurate DR positions, the "homing pigeon" instinct would more likely be the result of the following:

- 1. Complete understanding of all methods known of establishing and plotting positions.
- 2. A working knowledge of wind velocity triangles.

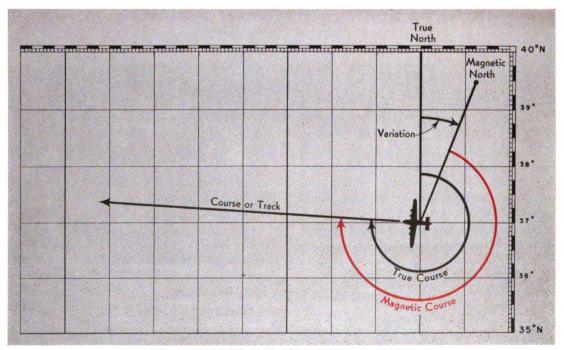


FIG. 39-TRUE AND MAGNETIC COURSE

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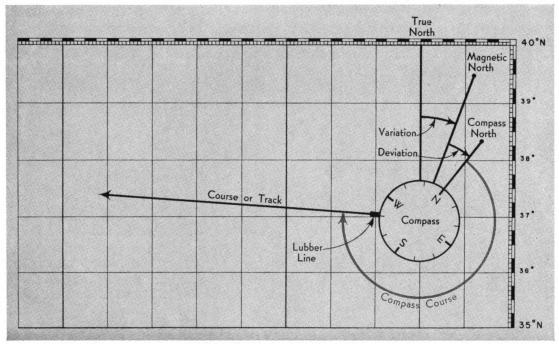


FIG. 40—COMPASS COURSE

- 3. A thorough proficiency in observing drift and the ability to correctly interpret values obtained.
- 4. Most important of all, the ability through reasoning and deduction from all available data regarding drift and speed, to determine his most probable position.

TRACK AND COURSE

Track is the path which the aircraft actually makes good over the ground. It is considered to be true track (i.e., measured from true North) unless otherwise indicated. (Figure 38)

Course is the intended track, i.e., the path which it is intended that the aircraft will follow in flying from one point to another over the ground. Unless otherwise indicated, it is considered to be true course. (Figure 38) Reference points from which courses are measured give rise to the following course terms:

- 1. **True Course** is the angular direction of the course measured from *true North*. It is obtained by applying both variation and deviation to compass course or variation to magnetic course. (Figure 39)
- 2. **Magnetic Course** is the angular direction of the course measured from magnetic North. It is obtained by applying variation to

true course or deviation to compass course. (Figure 39)

3. Compass Course is the direction indicated on the magnetic compass. It is the angular direction of the course with reference to compass North, and can be obtained from true course by applying both variation and deviation. (Figure 40)

Note: The term "compass course" is used here only for aiding the navigator in visualizing course corrections and for determining compass errors when the aircraft is stationary. In flight the aircraft does not fly a compass course because the direction indicated on the aircraft compass is actually compass heading. Compass heading (see page 33) also is affected by an additional course correction known as drift, which represents the effect of wind on the aircraft.

APPLYING COMPASS ERRORS

General—Orientation of the aircraft with respect to true North is most important to the navigator. However, it is imperative to bear in mind that only by applying the errors of variation and deviation to the magnetic compass reading can the aircraft's direction with respect to true North be obtained.



Thus it is apparent that true North is obtained indirectly from the magnetic compass reading. This simple fact sums up the principle of course conversions. The application of compass errors is not difficult, but must be mastered by the navigator if he is to be reliable.

Course Relationship—Course conversion is simplified once the navigator thoroughly understands the relationship of the various course terms to each other. This relationship may be outlined as follows:

True Course: No error.

Magnetic Course: One error—variation

(from true course).

Compass Course: Two errors—variation and deviation (from true course).

Therefore

 (\pm) (\pm)

True Var. Magnetic Dev. Compass

Variation is error between true and magnetic.

Deviation is error between magnetic and compass.

Conversion "Jingle"—To simplify course conversions, the navigator should adopt some positive method which will:

- 1. Help him determine the correct application of errors.
- 2. Double check his course computa-

The following "jingle" may prove helpful:

"TRUE RIGHT EAST" "TRUE LEFT WEST"

TRUE RIGHT EAST means—If error is East the more correct course is right. (Figure 41)

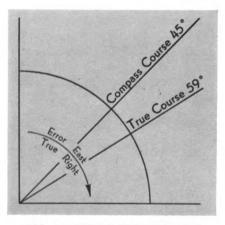


FIG. 41—"TRUE RIGHT EAST"

TRUE LEFT WEST means—If error is West the more correct course is left. (Figure 42)

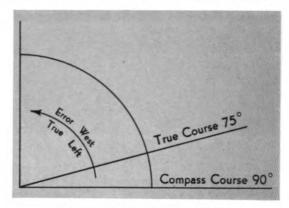


FIG. 42—"TRUE LEFT WEST"

In using the jingle, remember—True course contains no error and therefore is *more correct* than either magnetic or compass course.

Also remember—Magnetic course, containing one error, is *more correct* than compass course, which contains two errors.

Example No. 1

The compass course of an aircraft is 45° .

Required: True course.

Variation = 18° East

Deviation = 4° West

Total error = 14° East

The true course, therefore, is 14° right of the compass course, hence:

True course = 59°

Note: Variation was found on the chart; deviation on the calibration graph, for a course of 45°.

Example No. 2

The true course to be flown is 75°.

Required: Compass course.

Variation = 20° West

Deviation = 5° East

Total error = 15° West

The true course, therefore, is 15° left of the compass course, hence:

Compass course $= 90^{\circ}$.

Note: Variation was found on the chart; Deviation, on the calibration graph for a course of 90°.

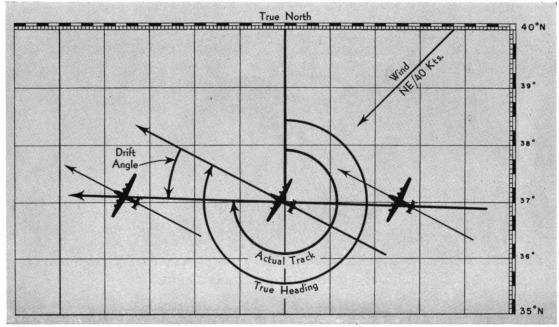


FIG. 43-DRIFT ANGLE AND HEADING

Sometimes compass errors are applied one at a time, as illustrated in examples No. 3 and 4.

Example No. 3

Compass course = 45°

Deviation = -4° West (magnetic left)

Magnetic course = 41°

Variation $=+18^{\circ}$ East (true right)

True course $= 59^{\circ}$

Example No. 4

True course $= 75^{\circ}$

Variation = +20° West (true left)

Magnetic course = 95°

Deviation = - 5°East (mag. right)

Compass course = 90°

DRIFT ANGLE

Drift angle, or drift, represents the effect of crosswind on the aircraft and may be defined as the angular difference between heading and track.

HEADING

Heading is the direction in which the longitudinal axis of the aircraft is pointed and, except in the case of tail-wind, is always into the wind. (Figure 43) Unless otherwise indicated, it is considered to be true heading. Reference points from which headings are measured give rise to the following heading terms:

- 1. True Heading is the heading of the aircraft measured from true North. It can be obtained by applying drift angle to true course.
- 2. Magnetic Heading is the heading of the aircraft measured from magnetic North. It can be obtained by applying drift angle to magnetic course.
- 3. Compass Heading is the heading of the aircraft measured from compass North. It can be obtained (theoretically) by applying drift angle to compass course. However, as the heading of an aircraft changes, the deviation changes. Therefore, since the drift angle may be large, a more accurate compass heading can be determined if the magnetic heading is computed first, and the compass heading is then computed by applying deviation to the magnetic heading.

Course-Drift-Heading Relationship — In Figure 44 it is apparent that when drift angle is applied to any course, the result is heading. Thus it may be assumed that the term "heading" indicates an additional error—drift angle—which for purposes of course conversion can be applied as an additional compass error.



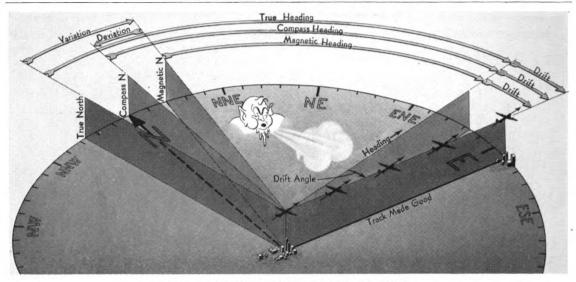


FIG. 44—CORRECTING FOR DRIFT ANGLE

Thus:

True heading: One error—drift (from true course).

Magnetic heading: Two errors—drift and variation (from true course).

Compass heading: Three errors—drift, variation and deviation (from true course).

Therefore, to find the compass heading necessary to fly in order to make good a desired true course, or to determine the true course being flown while steering a certain compass heading, the same jingle—True Right East—True Left West—holds good.

Example No. 1

To find compass heading necessary to fly in order to make good a desired true course:

True course $= 120^{\circ}$ Drift $= 5^{\circ}$ Right (true course

True heading $= 115^{\circ}$ right)
Variation $= 20^{\circ}$ East (true right)

Magnetic heading $= 95^{\circ}$ Deviation $= 3^{\circ}$ West (magnetic left)

Compass heading $= 98^{\circ}$

Example No. 2

To find the true course being flown while steering a certain compass heading:

Compass heading = 320° Deviation = 6° East (mag. right) Magnetic heading = 326° Variation = 32° West (true left) True heading = 294° Drift = 14° Left (true course True course = 280° left)

SPEED

Ground Speed is the speed of the aircraft with reference to the ground.

Air Speed is the speed of the aircraft with reference to the surrounding air.

Note: Ground speed is measured along the true course or track because both ground speed and course or track are related to the ground.

Air speed is measured along the true heading, because both air speed and heading are related to the air.

Where a no-wind condition exists, ground speed and air speed are the same. Where there is wind present, they will differ by a vector amount equal to the velocity of the wind. ("Vector" is defined on page 35).

TIME—SPEED—DISTANCE

Time is the measure of duration which determines how long a plane has flown or can fly.

Time = Distance divided by Speed Example:

 $\frac{480 \text{ nautical miles (Distance)}}{150 \text{ knots (Speed)}} = \frac{3.2 \text{ hours or }}{3^{\text{h}}12^{\text{m}}(\text{Time})}$

Speed is the rate of motion, or ratio of time and distance.

Speed = Distance divided by Time Example:

480 naut. mi. (Distance) = 150 knots (Speed)

3.2 hours (Time)

Distance is the measurement of space between two points which determines how far a plane has flown or can fly.

Distance = Time multiplied by Speed Example:

(Time) (Speed) (Distance) 3.2 hours \times 150 knots = 480 nautical miles

Note: As can be seen from the formulas, time, speed, and distance definitely are related to each other, and each is the result of division or multiplication of the other two. It should be remembered, however, that only like units can be multiplied together or divided by one another to obtain correct results. That is, if distance is in nautical miles, speed will have to be in knots; and, if speed is in knots (nautical miles per hour) then the time must be in hours and tenths of an hour, not hours and minutes.

Minutes are converted into tenths of an hour by dividing them by sixty. Similarly, tenths of an hour may be converted into minutes by multiplying them by sixty.

Example:

$$\frac{1 \text{ minute}}{60} = .017 \text{ hours}$$

$$.017 \text{ hours} \times 60 = 1 \text{ minute}$$

$$\frac{2 \text{ minutes}}{60} = .033 \text{ hours}$$

$$.033 \text{ hours} \times 60 = 2 \text{ minutes}$$

$$\frac{3 \text{ minutes}}{60} = .05 \text{ hours}$$

$$.05 \text{ hours} \times 60 = 3 \text{ minutes}$$

VECTOR DIAGRAMS

The term "vector," as used in dead reckoning, refers to a straight line whose length, drawn to any chosen scale, represents the magnitude of a velocity, and whose direction (usually shown by an arrowhead) indicates the direction of the velocity. Thus the velocity of an aircraft flying East at 120 knots can be represented graphically by a straight line 120 units in length and directed at an angle of 90° measured clockwise from true North.

Since wind, ground speed and air speed are

quantities which have direction and magnitude, they can be represented by vectors. When the three are combined graphically, the result is a vector diagram, or triangle of velocities. Given sufficient known conditions to permit construction of a vector triangle, the navigator can determine unknown elements by direct measurement. In air navigation, known conditions may be resolved into three basic triangles for determining unknown conditions.

Three Basic Types:

Type No. 1 (Figure 45)

Given: True course or track

True air speed

Wind

Find: True heading

Ground speed

Drift

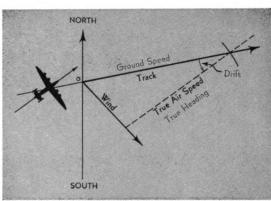


FIG. 45-VECTOR DIAGRAM: TYPE I

Type No. 2 (Figure 46)

Given: True heading

True air speed

Wind

Find: True course or track

Ground speed

Drift

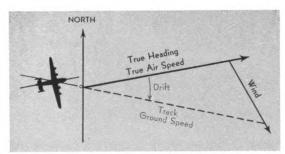


FIG. 46-VECTOR DIAGRAM: TYPE II

Type No. 3 (Figure 47)

Given: True course or track

Ground speed True heading

Air speed Find: Wind Drift

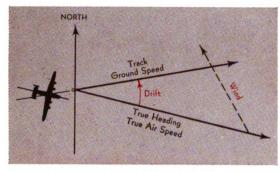


FIG. 47-VECTOR DIAGRAM: TYPE III

Sample Problems:

Type No. 1 (Figure 48)

Given: True course $= 308^{\circ}$

True air speed = 150 knots Wind $=20^{\circ}/35$ knots

Find: True heading

Ground speed

Drift

Type No. 2 (Figure 49)

Given: True heading = 250°

True air speed = 125 knots

Wind = 140°/50 knots

Find: True course or track

Ground speed Drift

Type No. 3 (Figure 50)

Given: Track $= 230^{\circ}$

Ground speed = 132 knots

True heading = 245° True air speed = 175 knots

Find: Wind Drift

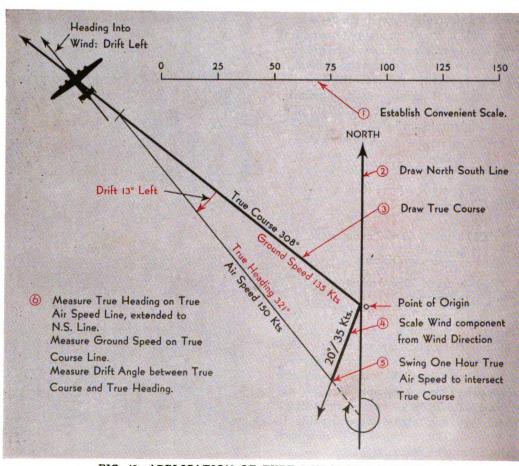
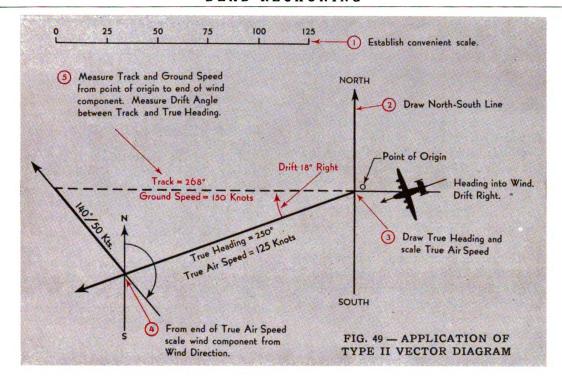
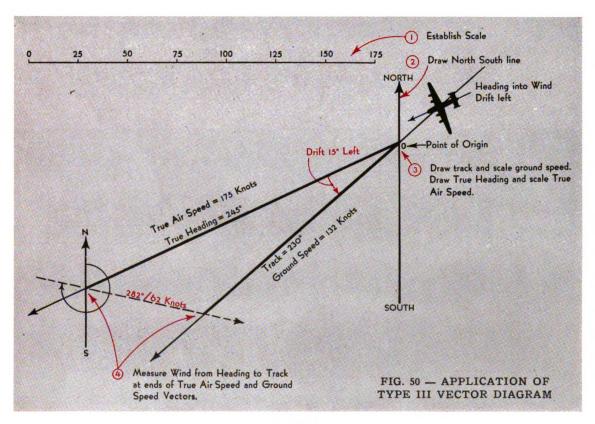


FIG. 48—APPLICATION OF TYPE I VECTOR DIAGRAM

DEAD RECKONING





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Note: In actual practice, wind vector triangles are worked on a computer, which permits solution of the problems with a minimum of effort. Knowing their construction, however, helps visualize wind effect.

DOUBLE DRIFT

Double drift is a method of determining the direction and velocity of the wind at the flight altitude of the aircraft. As the term implies, it involves taking drift meter readings on two separate headings. From the elements of drift angle, true heading, and true air speed thus obtained, it is possible to combine two vector triangles which will contain a common vector, equal to the wind.

If the two headings are approximately 90° apart and the drift is carefully measured, it is possible by this method to determine the wind's direction within 20° and its velocity within three knots. Since wind is the most important factor in determining an accurate dead reckoning position, a double drift is highly important to the ocean navigator, especially when the sky is overcast and navigation is entirely dependent upon dead reckoning.

Procedure—Figure 51 illustrates the following steps:

- 1. Determine true air speed.
- 2. From on-course heading turn 45°. When the aircraft is steady in this off-course heading, carefully measure the drift angle reading.

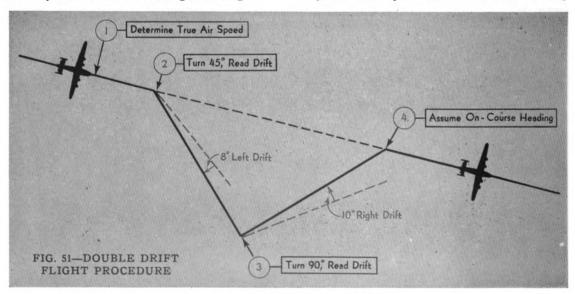
- 3. Turn 90° back toward the on-course heading. When the aircraft is steady on this second off-course heading, carefully measure the drift angle reading.
 - 4. Turn 45° to assume on-course heading.

Then solve for wind by the graphic method shown in Figure 52 (sometimes known as the "wind star method"), or directly on the aircraft computer.

Note: If the double drift is taken during daylight hours, whitecaps on the waves will serve as reference points with which to line up the drift grid. At night, a flare must be dropped onto the water to provide a reference point.

Problem—Unable to obtain a celestial fix because the sky is overcast, and finding the radio undependable because of interference. the navigator of an aircraft, on an over-water flight, decides it would be advisable to take a double drift in order to assure maximum accuracy in his dead reckoning.

Upon gaining the captain's approval to proceed with a double drift, the navigator notes the aircraft's true air speed (170 knots) and the true on-course heading (105°). He then requests the captain to steady the aircraft on a true heading of 150° (which is 45° right of the on-course heading). After the aircraft has flown on this heading long enough to permit the navigator to take a careful drift reading (usually about five minutes), the navigator requests the captain to steer a true heading



of 60° (which is 45° to the left of the oncourse heading). The navigator then takes his second drift reading, and after the aircraft has flown on this second off-course heading for the same number of minutes as were, required for the first off-course leg, he advises the captain to return to the on-course heading of 105°.

Note: Flying an equal time on each offcourse leg will bring the aircraft back to the original track.

Solution (Figure 52)

Given: On-course true heading 105°

True air speed 170 knots

First true heading 150°

(45° right of on-course heading)

Drift 8° left

Second true heading 60°

(45° left of on-course heading)

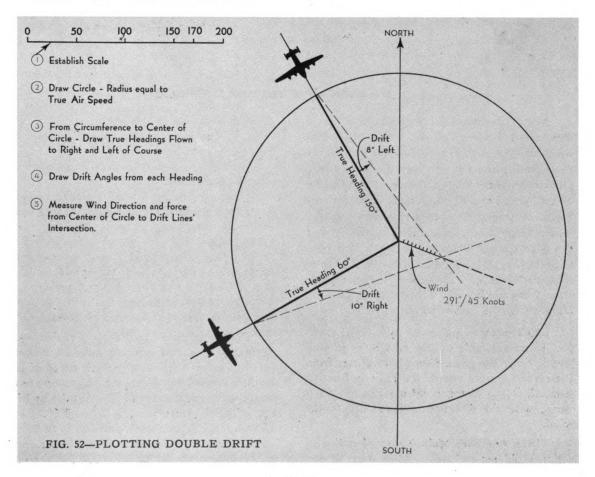
Drift 10° right

Find: Wind—direction and velocity.

RADIUS OF ACTION

Radius of Action is the distance an aircraft can fly with a given amount of fuel, and under given wind conditions, and still return to its starting base or an alternate base. Radius of action is sometimes called, in ocean navigation, the "point of no return," or "splash point." Once the pilot has flown past this point he cannot safely return, and must reach his destination, or "splash"!

Safe Return means to allow sufficient fuel reserve for safe landing and for unforeseen conditions. In long range flying, from San Diego to Honolulu, for example, fuel for two hours flying deducted from the total flying time is considered a safe reserve above available fuel hours. On shorter flights, with proportionately less fuel, 25% usually is kept in reserve.



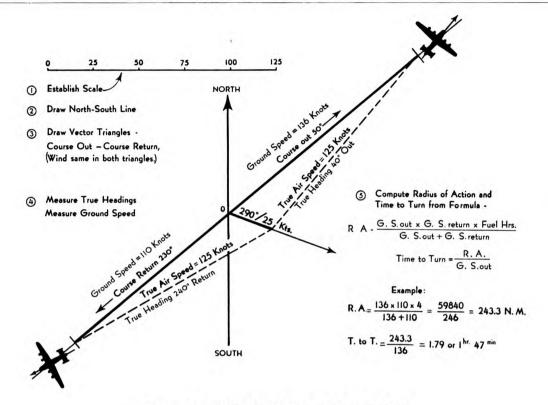


FIG. 53-RADIUS OF ACTION TO SAME BASE

Wind Conditions—The radius of action is determined before take-off, using estimated wind, and the wind is considered to remain the same during the trip out and the return trip. Obviously, the force of the wind affects the ground speed and heading on both legs of the flight. However, the change of heading for the return flight results in a different wind vector triangle. Actual winds encountered in a long range flight sometimes differ considerably from estimated winds. Therefore, the navigator should re-calculate the splash point while in flight, using the known wind.

The Distance a plane can fly is equal to the fuel hours available multiplied by the ground speed. Since the ground speed out differs from the return ground speed, the radius of action—which is the distance out a plane can fly—varies with the direction and velocity of the wind.

There Are Two Main Types of radius of action problem:

- 1. Returning to the same base.
- 2. Turning off-course to an alternate base.

In both problems the following information is determined:

Distance out (radius of action); time to turn; true heading out and true heading back or to an alternate; ground speed out and ground speed back or to an alternate. The true headings and ground speeds out and back result in two parts in each type problem, both of which may be solved by vector triangles.

The radius of action and time to turn, however, are solved by special formulas.

Returning to Same Base — Problem — A navigator of an aircraft containing sufficient fuel to fly five hours at a true air speed of 125 knots is notified by the captain that they are to search on a true course of 50° for a missing lifeboat. The forecast wind is from 290°, force 25 knots. The navigator's problem is to determine how far out his aircraft may search and still return safely with a one-hour fuel reserve.

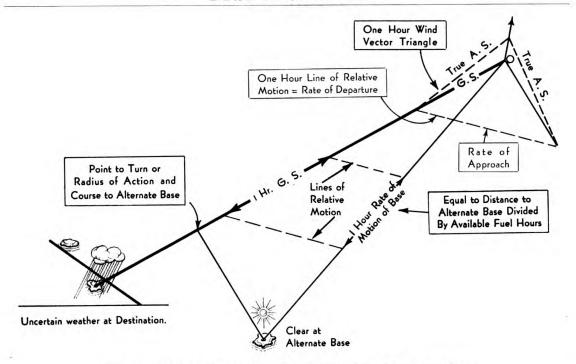


FIG 54-RADIUS OF ACTION TO ALTERNATE BASE: THEORY

Solution (Figure 53)

Given: Course out

Course return 230°

(reciprocal)

Fuel available 4 hours

(5 hours total, 1 hour reserve) True air speed 125 knots

50°

Estimated wind 290°/25 knots

Find: Distance out (radius of action)

Heading out Heading return Time to turn

Turning To An Alternate Base—This is primarily a safety problem and is employed to determine how far an aircraft can fly toward a desired destination and still return to an alternate base if necessary.

The problem is based on relative motion of the alternate base, which actually may be a moving base, such as an aircraft carrier, or a fixed base, which for purposes of the problem is considered to move. In either case, the aircraft and the alternate base are assumed to start at the same time, from the same position.

Each moves at its respective velocity for the same length of time—an amount equal to the number of available fuel hours—but on different tracks.

Figure 54 illustrates the tracks and relative motion of aircraft and alternate base.

Problem-A navigator of an aircraft containing sufficient fuel to fly seven hours at a true air speed of 150 knots leaves his base airport flying on a course of 250° toward a distant island. The forecast wind is from 200°, force 25 knots; however, the weather report shows a warm front approaching, making safe landing at the desired island uncertain. Weather conditions at an alternate island bearing 230° true and 55° nautical miles from his base airport are clear and expected to remain so. Therefore, since it is necessary to reach the distant island if at all possible, the captain decides to proceed, hoping to arrive before the front closes in. The navigator's problem is to determine how far they can proceed toward the desired island and still, if advised by radio it will be impossible to land, to turn off and reach the alternate island with a safe one and one-half hours of fuel in reserve.

AMERICAN AIR NAVIGATOR

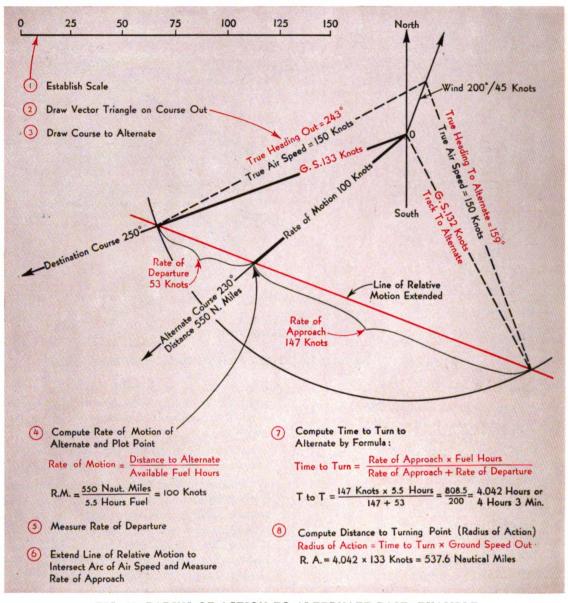


FIG. 55-RADIUS OF ACTION TO ALTERNATE BASE: EXAMPLE

Solution (Figure 55)

Given: Course to destination 250°

Course to alternate 230°

Distance to alternate 550

Distance to afternate

nautical miles

Fuel available $5\frac{1}{2}$ hrs. (7 total)

 $(1\frac{1}{2} \text{ reserve})$

True air speed 150 knots Estimated wind 200°/25 knots

Find: True heading out

True heading to alternate

Time to turn

Distance to turning point



PROBLEM WORK NO. 6

APPLYING COMPASS ERRORS

(Find missing values.)

No.	TRUE COURSE	VARIATION	MAGNETIC COURSE	DEVIATION	COMPASS
1	92°		82°	2°E	
2		14°E	256°	**************************************	259°
3	30°	6°E		1°E	
4		16°E	346°	0°	
5	165°		170°		175°
6	332°	11°W			339°
7	122°			3°W	125°
8		13°E		2°E	344°
9	1°		11°		10°
10	115°			4°E	96°
11		14°W	4	3°E	234°
12	225*		216°	3°W	
13		3°W	150°	4°W	
14	118°		129°		120°
15	322°	7°E	×		320°
16	187°	14°W		1°E	
17		16°E	296°		302°
18	334°			4°W	330°
19		14°E	349°	6°E	
20	96°	,	101°	1°E	

PROBLEM WORK NO. 7 TRACK AND HEADING

(Find missing values.)

	Track		Track	1-15-7	Heading		Hea	ding
No.	True	Var.	Magnetic	Drift	Magnetic	Dev.	Compass	True
1	117°	14°E		2°R		3°W		
2		16°W	247°		243°		241°	
3	47°		61°			3°W		51°
4	342°		332°		326°		326°	
5	96°	15°E			78°		71°	
6		16°W	292°		290°		299°	
7	111°	10°W		(4)		4°W		110°
8		14°E	228°		226°	3°E		
9	167°		151°	4°L			161*	
10		12°W		0°	221°		217*	
11		10°W		2°L	185°	0*		
12			182°		178°		183°	194°
13		17°W		7°R			120°	107°
14	356°		345°			2°E	344°	
15	6°		352°		353°	10°W		
16		16°E	284°	3°R			275°	
17	249°		261°	1°L		14°W		
18		14°W		4°R		5°W		218°
19				4°L	180°	10°W		204°
20		18° E	100°		96°		90*	

PROBLEM WORK NO. 8 TIME—SPEED—DISTANCE

(Find missing values. Use computer only for checking work.)

No.	TIME	SPEED (Knots)	DISTANCE (Nautical Miles)
1	1h27m	125	
2	1h34m	. 136	
3	2h02m	171	
4	0h44m	152	
5	4h13m	111	
6	2h16m	106	
7	3h57m	72	
8	0h52m	176	
9	2h02m		240
10	1h16m		200
11	6h26m		702
12	3h21m		476
13	2h14m		317
14	0h56m		173
15	4h03m		600
16		168	240
17		160	310
18		201	117
19		117	156
20		115	196

		Drift																				-
	-	Speed																				
	HEADING	Compass																				
	HEA	True																				
ots.)		Dev.																1°E	3°E	12°W	16°E	-
PROBLEM WORK NO. 9-A VECTOR DIAGRAMS eed—drift. All velocities in knots.)		Var.																2° E	S°W	7°E	2°W	
OBLEM WORK NO. 9 VECTOR DIAGRAMS —drift. All velocities in	ND ND	Vel.	30	40	25	35	20	50	25	20	25	40	34	29	18	28	16	24	19	21	25	
OBLEM VECTO] —drift. ≠	WIND	Dir.	320°	84。	230°	53°	304°	223°	°06	308°	117°	270°	48°	131°	355°	142°	°62	85°	286°	138°	251°	
PR nd speed-		C°.						+15°	+10°	- 5°	- 3°	+12°	-30°	+15°	- 5°	- 5°	+20°	+25°	+30°	-10°	+12°	
PROBLE) VECTO find: Heading—ground speed—drift.		Pressure Altitude						5000	10,000	,0009	25,000	4000′	14,000	10,000′	20,000	16,000	8000	4500	3000	5500	70007	
: Head		T.A.S.	06	110	95	120	140	-														
		C.A.S.						177	152	124	108	170										
riangles	Cali- bration	Correc- tion											8+	++	-3	4	9+	-5	7	7	+2	
ector to		I.A.S.											140	150	86	110	129	125	138	170	124	
(Draw vector triangles to		True	85°	173°	140°	300°	208°	148°	170°	240°	37°	0	350°	16°	100°	.09	330°	204°	31°	.92	190°	
		No.	1	2	3	4	2	9	7	00	6	10	11	12	13	14	15	16	17	18	19	-

			Drift																				
		WIND	Vel.(kts)																				
		W	Dir.																				
		E	C. C.											—10°	- 5°	- 7°	+ 3°	+18°	+22°	- 4°	+10°	-10°	-13°
			Altitude											3000'	2500	1900	20,000′	11,500	70007	6500	2000	3500	1000
			(knots)	144	110	128	118	106	145	115	128	162	144										
NO. 9-B	AMS		(knots)											103	153	116	92	92					
PROBLEM WORK NO. 9-B	VECTOR DIAGRAMS	Calibra- tion	Correc- tion											-					9	+7	4	9	+2
OBLEM	VECTOR		I.A.S. (m.p.h.)																130	139	105	142	136
PR			Var.						4°E	S°W	2°W	15°W	3°E	1°W	9° E	2° E	Z°W	0.0	15°W	12°E	1°E	7°W	14°W
	l drift.)		Dev.						2°W	7°E	3° E	2°E	4°E	M.9	2°W	10°E	12°E	Z°W	Z°W	8°E	3°E	11°E	2°F
	wind and drift.)	HEADING	True	75°	120°	280°	206°	\$															
	rles to find	HEAI	Compass						53°	87°	218°	176°	277°	290°	°29	94°	347°	37°	155°	12°	145°	141°	101
	(Draw vector triangles to find	Ground	Speed (knots)	130	93	110	121	101	138	119	162	178	147	109	157	143	66	1111	141	126	101	117	120
	Draw vec		True	85°	145°	290°	194°	30°	48°	95°	210°	176°	300°	275°	°09	118°	4°	17°	150°	10°	138°	141°	101 °
			No.	-	2	3	4	5	9	7	∞	6	10	11	12	13	14	15	16	17	18	19	20

PROBLEM WORK NO. 10 DOUBLE DRIFT

(Find wind by drawing "wind stars." All velocities in knots.)

		FIRST		SECOND		WI	ND
No.	T.A.S.	HEADING	DRIFT	HEADING	DRIFT	DIRECTION	VELOCITY
1	90	258°	7°R	348°	0°		
2	120	220°	10°L	130°	1°R		
3	160	260°	6°R	170°	1°R		
4	160	0°	13°L	90°	4°L		
5	150	270°	4°R	180°	8°R		
6	130	315°	11°L	15°	6°L		
7	110	0°	0°	270°	10°R		
8	175	90°	8°L	180°	2°L		
9	165	45°	5°R	135°	10°R		
10	145	55°	10°R	145°	2°R		
11	155	75°	5°R	34 5°	5°R		
12	160	85°	5°R	175°	0°		
13	180	120°	13°L	30°	5°L		
14	135	140°	5°R	230°	8°R		
15	150	160°	8°L	70°	2°L		
16	170	180°	5°R	80°	6°R		
17	130	190°	7°R	280°	3°R		
18	185	200°	10°L	110°	6°L		
19	140	240°	7°R	150°	2°R		
20	120	220°	10°R	310°	4°R		

		Time	Turn										
		Radius	ot Action										
		True Heading	In										
		True I	Out				7 1						
	SE	GCT	I ake-ott Time	06:30	10:20	14:20	. 16:30	10:30	07:10	06:40	15:15	01:24	00:45
. 11-A	RADIUS OF ACTION TO A FIXED BASE		Fuel Available										
PROBLEM WORK NO. 11-A	TO A	,	ruel Reserve	10%	8%	30т	2%	10%	30т	1h	1	25%	15%
SLEM ·W	ACTION	,	Fuel	9	4	8	10	4	4:30	6	S	80	7
PROF	OIUS OF		(knots)									i	
	RAI nd missing values.)	,	Pressure Altitude	,0009	4000	2000	10,000′	3000	8000	,0006	2000	10,000′	3000
	d missing		C.D.	+ 2°	- 3°	- 5	- 4°	+10°	20°	+10°	—10°	20°	.0
	ng pue su		(knots)	182	160	200	140	125	ııı	110	06	130	175
	(Draw vector diagrams and fi		Wind (knots)	50°/30	250°/30	280°/30	280°/30	30°/24	90°/36	270°/10	300°/30	270°/70	70°/44
	Oraw veci	True	Course	.28	310°	198°	250°	270°	200°	•09	40.	20.	135*
	2		No.	1	2	3	4	5	9	7	∞	6	10

Time Turn Distance Out TRUE HEADING TO Fuel Available Destination Alternate RADIUS OF ACTION TO ALTERNATE BASE PROBLEM WORK NO. 11-B 30 min. 30 min. Fuel Reserve 10% 10% %01 20% 1 1 1 1 Fuel S S S 9 2 4 T.A.S. (knots) 110 110 8 8 8 120 200 8 160 4 340°/15 170°/20 (Draw vector diagrams and find missing values.) 270°/30 180°/32 45°/30 210°/30 09/.08 270,740 30°/30 270°/31 Wind Distance to Alternate (Nautical Miles) 360 280 80 180 245 200 180 225 8 300 TRUE COURSE TO Destination Alternate .92 245° 170 345 230 .081 250 190 360° 200 270° 290 20. 240 300 130 350 200 110° <u>.</u> No. 2 9 2 œ 6 10

DEAD RECKONING

DEAD RECKONING REVIEW TEST

1. Define:

(a) Latitude

(d) Variation

(b) Longitude

(e) Rhumb Line

- (c) Great Circle
- 2. Draw diagrams showing the projection and development of the Mercator, Lambert, and gnomonic charts, and list advantages and disadvantages of each.
- Show how rhumb line track and great circle track appear on gnomonic chart and also on Mercator chart.
- 4. (a) Compass course is 302°, variation 10°W, deviation 4° E. What is magnetic course? What is true course?
 - (b) True heading is 210°, variation 16°E, drift 4° left, deviation 3°W. What is true track? Compass heading? Magnetic track?
 - (c) True course is 33°, variation 12°E, deviation 6°E, drift 4° right. What is true heading? Compass course? Magnetic course?
- 5. Pressure altitude is 8000 ft., indicated altitude 9000 ft., temperature +8°C. What is true altitude?
- 6. (a) Indicated air speed is 179 m.p.h., instrument correction +2 m.p.h., altitude 10,000 ft., temperature +10°C. What is calibrated air speed in knots? True air speed in knots?
 - (b) Calibrated air speed is 157 knots, altitude 12,000 ft., temperature 0°C. What is true air speed in knots?
- 7. San Diego to position "A" is 510 nautical miles. Aircraft's true air speed is 180 knots, wind directly astern at 19 knots, time of departure is 03:10 GCT.
 - (a) At what time will plane reach position "A"?
 - (b) If aircraft arrives at position "A" at 07:30 GCT, what is the ground speed?
 - (c) If ground speed is 115 knots and aircraft arrives at position "A" at 09:10 GCT, what is the distance to position "A"?
- 8. (a) True air speed is 150 knots, wind 30°/30 knots, course 272°. What will be the estimated ground speed? True heading? Drift?
 - (b) True heading is 60°, true air speed 100 knots, wind 350°/25 knots. What will be the estimated ground speed? Track? Drift?
 - (c) Track is 195°, true heading 210°, true air speed 190 knots, ground speed 210 knots. What is wind? Drift?
- 9. While on a true heading of 230°, true air speed 120 knots, a navigator decides to take a double drift to determine the wind. His first true heading is 275°, drift 8° right. His second true heading is 185°, drift 10° left. What is direction and force of wind?
- 10. With 6 hours of fuel available over the required reserve, how far can an aircraft fly on true course of 220°, at a true air speed of 180 knots, wind 300°/33 knots and still return to its starting point? If the aircraft leaves San Diego at 09:15 GCT, what time should it turn around?





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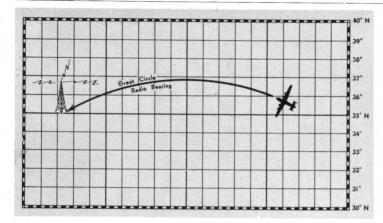
RADIO NAVIGATION

RADIO navigation is the method of determining an aircraft's position with relation to, or its direction from, known radio transmitting stations. To accomplish this orientation, advantage is taken of the directional characteristics of a loop antenna. However, because of interferences affecting transmission, and due to design limitations of present-day radio equipment, plus the fact that reception and use of radio waves are limited to the skill of the operator, radio navigation is not as accurate as celestial navigation or pilotage. Hence it should be used only as an aid to navigation in conjunction with all other available methods.

Radio Wave Characteristics—The radio bearing between a ground station and an air-

craft is a direct line over the surface of the earth; hence, it follows a great circle track (Figure 56). Drawn on a Mercator chart, the bearing would appear as a curved line bending toward the elevated pole (Figure 57).

The path of a radio wave, however, often is refracted, reflected, or otherwise caused to deviate from a great circle track by storms, by mountains, by passage over a coastline or by the phenomenon known as "night effect." Night effect is the change in reflection of the radio wave from the ionosphere, and is always encountered; however, the effect is more pronounced at sunrise and sunset (hence "night effect"), and may be recognized by a fluctuation in bearings. Night effect may be reduced



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FIG. 57—RADIO BEARING APPEARS AS CURVED LINE ON MERCATOR CHART

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somewhat by varying the altitude of the aircraft, by taking an average of the fluctuations, or by selecting a station of lower frequency.

Value of Radio—Even with present-day limitations and the difficulties inherent in wave transmission, radio is an invaluable aid to navigation. With the development of better equipment and the continual increase in the number of ground stations throughout the world, it will continue to assume more importance.

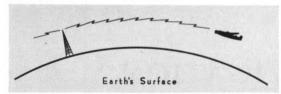


FIG. 56—RADIO BEARING FOLLOWS GREAT CIRCLE PATH

With radio, an aircraft can remain in constant communication with the ground as well as with other aircraft. By means of the radio direction finder (radio compass), bearings may be taken of a transmitting station, either on the ground or in another aircraft, with which the navigator can establish his position with relation to the transmitting station. By means of radio range stations, an aircraft's position can be determined so accurately that landings may be made even without visual contact with the ground.

RADIO COMPASS

Description—The radio compass is an instrument for receiving radio wave signals and measuring the *relative bearing* of the transmitting station from the aircraft's heading. The

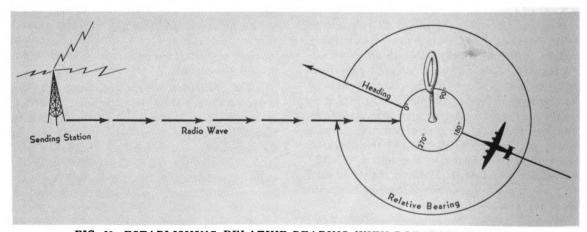


FIG. 58—ESTABLISHING RELATIVE BEARING WITH ROTATABLE LOOP

principle of operation involves the directional characteristics of a *loop antenna*. When the loop is at *right angles* to the direction of incoming radio waves, minimum signal volume is heard; maximum volume is heard when the loop is *parallel* to the incoming signal waves (Figure 58).

By use of the radio compass, direction of the transmitting station is established on an azimuth ring (Figure 59) by a pointer actuated by a rotatable loop antenna. The azimuth ring is graduated in a clockwise direction from 0° to 360°, the 0° and 180° points being aligned with the longitudinal axis of the aircraft. When the pointer is at 0°, the loop is at right angles to the longitudinal axis.

When the loop antenna is swung back and forth until the mean point of minimum volume is established, the azimuth dial then indicates the relative bearing of the transmitting station from the aircraft's heading. The point of minimum volume is used because, due to the antenna loop characteristics, that point is easier to detect than the point of maximum volume.

Loop antennas may be either manually or automatically operated.

Manually Operated Loop—The loop is rotated by a hand-operated crank. When the station signal received is at a minimum volume, the loop is at right angles to the radio wave received, indicating the station's relative bearing.



Courtesy Bandix Radio Division, Bendix Aviation Corporation FIG. 59—AZIMUTH DIAL



Courtesy Bendix Radio Division, Bendix Aviation Corporation

FIG. 60-CONTROL PANEL

Automatically Operated Loop—When the station is correctly tuned in, an electric motor automatically rotates the loop, keeping it at right angles to the station from which the radio wave is emanating.

Note: If the crank mechanism or motor fails, it is possible in some installations to rotate the loop by hand. In such a case, the loop should be turned perpendicular to the aircraft's longitudinal axis. With the loop in this position, the aircraft can be pointed toward the transmitting station by altering the heading until the signal wave is at minimum volume. The bearing of the transmitting station is then indicated on the magnetic compass, relative to compass North.

BENDIX RADIO COMPASS

The following is the general procedure for operating the Bendix radio compass equipment as it is used by the ocean aerial navigator for homing to a required destination, for taking bearings, and for fixing the aircraft's position. Other installations are similar, and procedures are practically the same.

Master Switch—The master switch on the control panel (Figure 60) has four contacts: OFF, COMP (Compass), REC ANT (Receive Antenna), REC LOOP (Receive Loop), which

control all radio compass functions other than tuning and adjustment of signal levels, as follows:

- OFF—No current is going through the set.
- 2. COMP—The equipment functions as a direction finding receiver connected to the loop and sense antenna, operating the *left-right indicator*.
- 3. REC ANT The equipment is connected to the non-directional vertical antenna. As such, it is used for aural radio range reception and for obtaining communication reception.
- 4. REC LOOP—The equipment functions as a communication receiver connected to the directional loop antenna. This contact is used for aural-null bearings, aural-null homing, and for obtaining communication reception or listening to radio range reception during conditions of severe static caused by rain or snow.

Left-Right Indicator (Figure 61) — The left-right indicator is an instrument having a pointer in the form of a small conventionalized figure of an airplane which visually indicates "null" radio bearings. The pointer is actuated by the phase relationship of incoming radio waves. Minimum volume causes the pointer to remain at the center of the instrument, thus indicating that the loop antenna is at right angles to the incoming radio wave. When the transmitting station is ahead, rotation of the



Courtesy Bendix Radio Division, Bendix Aviation Corporation FIG. 61—LEFT - RIGHT INDICATOR

azimuth dial or changes in aircraft's heading in one direction, will cause the left-right pointer to move in the opposite direction. If the pointer moves in the same direction, the station lies behind the aircraft.

Preliminary Operation

- a. Turn the master switch on.
- b. Carefully tune the receiver to the frequency of the desired radio station and adjust the *audio control volume*.
- c. Listen to the station's call sign, or identification signal, in order to make certain that the correct station has been tuned in.

HOMING

Procedure

- 1. FOR VISUAL HOMING (using left-right indicator).
 - a. Adjust master switch to COMP.
- b. Set azimuth dial to read zero. The needle of the left-right indicator now points in the general direction of the transmitting station
- c. Alter the heading of the aircraft to right or left so that the *indicator needle* is centered. The aircraft now will be pointing toward the desired station.
- d. If the needle is being continuously deflected right and left of the center, reduce the *compass control volume*, permitting the course to be followed more accurately.
- 2. FOR AURAL-NULL HOMING (using headphone)—This method of homing is used if the left-right indicator fails, or in case of severe rain static. It is called "flying a null course," and is identical with the method used in visual left-right homing, the only difference being that with this method an audible signal is received via the headphones, and the pilot alters the aircraft's heading to right or left to maintain the signal volume at a minimum.

If the signals are weak, turn the CW switch on.

Note: Homing is the easiest method of approaching a station on course. However, it should be used only when the aircraft is less than one hundred miles from the station. At greater distances, it would be more practical to plot radio compass bearings and establish compass headings to fly. This is true primarily

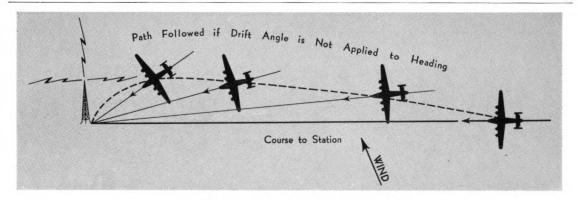


FIG. 62-EFFECT OF WIND IN HOMING

because of the effect of crosswind on the aircraft, for when homing with a strong beam wind blowing, the aircraft's heading has to be altered continuously into the wind in order to keep on the null course, or to keep the needle of the left-right indicator centered. Figure 62 illustrates the effect of wind in homing.

RELATIVE RADIO BEARINGS

Definition—A relative radio bearing is the angular direction of the transmitting station measured clockwise from the true heading of the aircraft.

Calibration Error—Practically all aircraft radio compass installations give definite errors in relative bearings. This error is called *calibration error and must be applied to all relative radio bearings in order to find the correct relative bearing.*

Calibration error is a result of the effect which the metallic fore and aft mass of the fuselage structure, athwartship mass of the wing structure, and other metallic masses in the aircraft have on the rotatable loop antenna. It is determined by a method similar to that used to find compass error, namely, by swinging the aircraft on a compass rose, or in the air, and recording the error found on each 15° heading throughout 360°. The 0° bearing, however, is obtained by heading the aircraft toward the transmitting station and taking the bearing over the nose of the ship. Hence the 0° point on the azimuth ring indicates the nose of the aircraft and not geographical North, as is the case with the magnetic compass.

From the data thus obtained, a calibration graph is drawn showing the amount of correction to be applied to any relative bearing.

Procedure

- 1. FOR VISUAL RELATIVE RADIO BEARING (using left-right indicator).
 - a. Adjust master switch to COMP.
- b. Rotate *loop* until *needle* of left-right indicator is centered.
- c. Read relative bearing on the azimuth dial and apply calibration error to obtain correct relative bearing.
- 2. FOR AURAL-NULL RELATIVE BEARINGS (using headphones).
- a. Adjust master switch to position of REC LOOP.
- b. Rotate *loop* until the headphone volume decreases to a minimum.
- c. Read relative bearing on the azimuth dial and apply calibration error to obtain correct relative bearing.

True Bearings — In converting relative bearing to true geographical bearing, employ the following procedure:

- a. Note the compass heading of the aircraft at the instant the relative bearing is read.
- b. Convert compass heading to true heading by applying variation and deviation.
- c. Add correct relative bearing and true heading. Since true heading is the direction of the aircraft's heading from true North and the relative radio bearing is the direction of the transmitting station from the aircraft's heading, the sum equals the true geographical great circle bearing of the transmitting station from the aircraft.



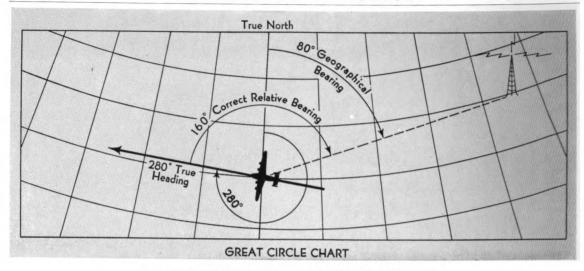


FIG. 63—DETERMINING GREAT CIRCLE BEARING

Note: If the sum of the relative bearing and true heading is over 360° , subtract 360° .

Example (Figure 63)

Compass heading	=	265°
Deviation	=	5°E
Magnetic heading	=	270°
Variation	=	10°E
True heading	=	280°
Relative radio bearing	=	155°
Calibration correction	=	$+5^{\circ}$
Correct relative bearing	=	160°
True heading	=	280°
Sum	=	440°
Less 360°	-	−360°
Great circle bearing	=	80°
Mercator correction	=	$+2^{\circ}$
Rhumb line bearing	=	82°

Mercator Correction — Since radio waves follow a great circle path which, on the Mercator chart appears as a curved line bending toward the elevated pole, a correction has to be applied to all radio bearings before they can be plotted as straight lines (rhumb lines) on the Mercator chart (Figure 65).

Correction Amount—The amount of correction to be applied in order to convert the great circle bearing into a rhumb line bearing varies with the *mid-latitude*, and the *difference of longitude* between the aircraft and the transmit-

ting station. This correction is gained by inspection of a radio bearing conversion table (Figure 64). The table should be part of the navigator's equipment and is in either tabular or graphic form.

Correction Sign—The sign of the correction is either plus or minus depending upon the position of the receiver with relation to the transmitting station. The sign of the correction for any position may be determined as shown in Figure 66. Thus, in Figure 64 or 66, when the receiver is West of the transmitting station (North latitude), the great circle bear-

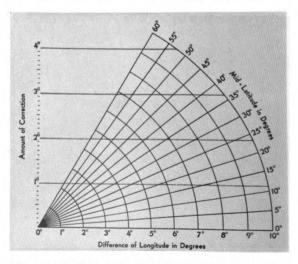


FIG. 64-MERCATOR CORRECTION DIAGRAM

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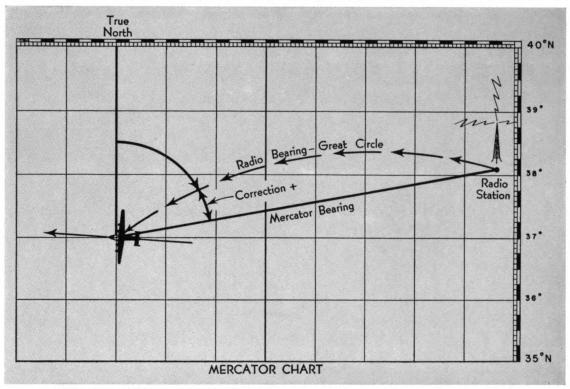


FIG. 65—CONVERTING GREAT CIRCLE BEARING TO MERCATOR BEARING

ing, which bends toward the poles, is less than the rhumb line bearing. Therefore, the correction is plus. In South latitude, the correction would be minus because the great circle there bends toward the South pole.

RADIO RANGES

Description—Radio range beacons are the safest and most widely-used form of directional guidance in the United States. Hundreds of radio range beacons mark every airway commercially flown in this country, and now, with

the establishment of island air bases, they aid the navigator throughout the world.

Radio range beacons transmit dot-dash (A) and dash-dot (N) signals in alternate quadrants. Neighboring quadrants overlap, forming a narrow beam identified by a continuous signal which is a result of the overlapping of the A and N signals. These narrow, wedge-shaped beams, or equisignal zones, indicate to the pilot that he is flying the safest on-course heading to approach or depart from the desired radio range station. The quadrant signals of

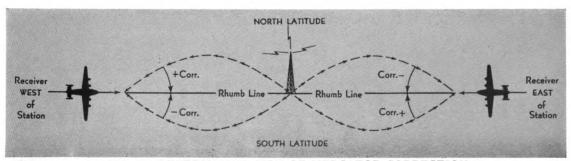


FIG. 66-DETERMINING SIGN OF MERCATOR CORRECTION

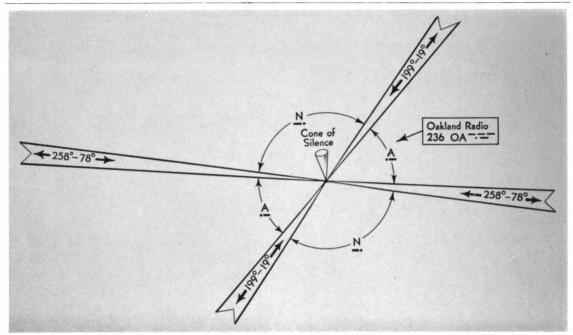


FIG. 67—TYPICAL RADIO RANGE

dot-dash and dash-dot (A and N) indicate to him the side of the equisignal zone from which he is approaching the station, or toward which he is drifting. When the radio compass is used for range reception, the master switch is on REC COMP. However, when the switch is on REC COMP, range reception is not entirely reliable. Therefore, the on-course range signal should be checked frequently by turning the switch to REC ANT, which is the best position for radio range reception.

Procedure—To follow a radio range course, it is necessary to have a chart (as illustrated in Figure 67) showing the radio range course and characteristics. The magnetic direction of the courses to and from the station are indicated, as are the locations of the A and N quadrants with relation to the various equisignal zones. The frequency and identification signals of the station also are noted. The procedure is as follows:

a. Adjust the master switch to REC ANT.

Note: In case of rain-static, adjust master switch to REC LOOP and rotate loop parallel to radio wave for maximum signal strength.

b. Turn aircraft so as to intercept the radio

range course. When *on-course*, the A and N signals will blend into a continuous dash, only interrupted by station identification.

c. As the aircraft approaches the station the volume increases, but on arrival over the station, a decrease in volume occurs as the plane passes over what is known as the "cone of silence." If the master switch is on REC LOOP, the cone of silence will not be "heard."

USE OF RADIO BEARINGS

Properties and Limitations—True radio bearings are very useful aids to the aerial navigator who thoroughly understands their properties and limitations. These may be summarized as follows:

- 1. A true radio bearing is the direction of the transmitting station from the receiver relative to true North. If the receiver is an aircraft, the reciprocal of the bearing would be plotted through the known geographical position of the transmitting station.
- 2. The bearing is a position line; that is, it establishes the aircraft's position as somewhere on the straight line passing through the transmitting station. It does not, however, indicate the aircraft's distance from the station.



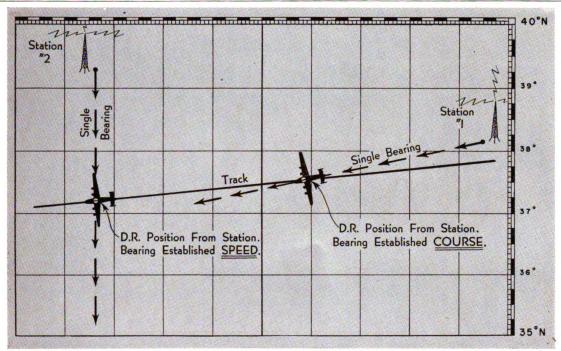


FIG. 68—POSITION DETERMINED BY SINGLE RADIO BEARING AND DEAD RECKONING

- 3. The bearing is a great circle, and if it is to be plotted on a Mercator chart, it must first be converted to a rhumb line bearing.
 - 4. The bearing may not be absolutely ac-

curate; therefore, the navigator should analyze it carefully to determine the most likely position of the aircraft, allowing for any estimated errors.

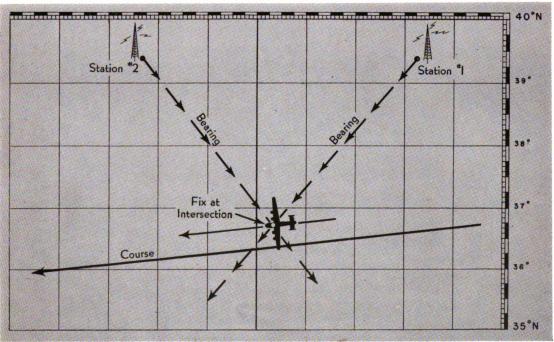


FIG. 69-POSITION DETERMINED BY INTERSECTION OF TWO RADIO BEARINGS

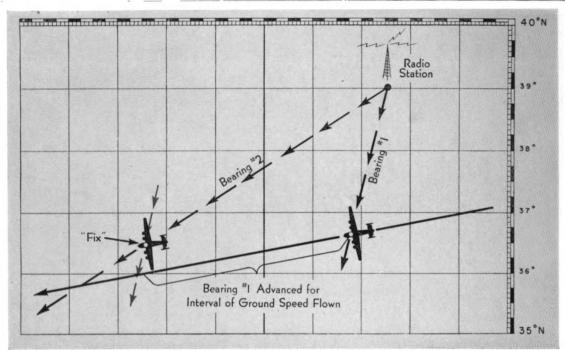


FIG. 70-POSITION DETERMINED BY TWO BEARINGS ON SAME STATION

Obtaining Fix—Methods most often used to determine the aircraft's position by use of radio bearing lines are as follows:

1. Single Bearing and Dead Reckoning

(Figure 68)—With only a single radio bearing the navigator may, by reasoning and deduction, estimate the aircraft's most probable dead reckoning position on the radio position line.

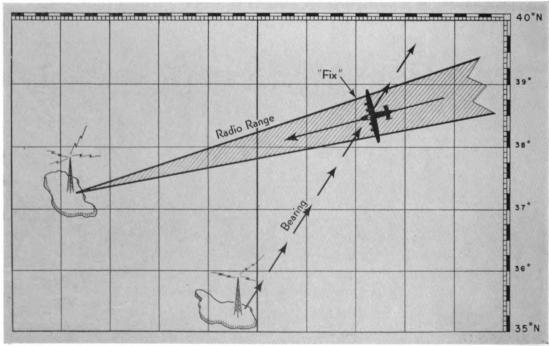


FIG. 71—POSITION DETERMINED BY RADIO BEARING AND ON-COURSE RANGE SIGNAL

If the bearing is parallel to the track, it will serve to check the aircraft's track. If the bearing is at right angles to the track it will serve to check the aircraft's speed.

- 2. Two or More Bearings of Different Stations (Figure 69)—A single radio bearing establishes the aircraft's position as being somewhere on the bearing line. But when two or more bearings are taken of different stations at the same time, the only position possible to the aircraft is at the intersection of these bearing lines, hence its exact location is determined (assuming no errors).
- 3. Running Fix (two bearings of same station) (Figure 70)—With the track (or course) and ground speed of the aircraft known, a position fix can be determined by taking two bearings of the same station, allowing an in-
- terval of time between bearings. During this time interval the bearing of the station will alter due to the change of position of the aircraft. And because the aircraft was located somewhere on each bearing line (at the instant the bearing was taken), the first bearing line can be advanced along the track a distance equal to the product of ground speed and time interval between bearings. The intersection of bearings establishes the aircraft's position.
- 4. Bearings Intersecting Range Courses (Figure 71) Bearings intersecting range courses establish position of the aircraft in the same way as do two or more bearings taken of different stations. The radio range establishes the course of the aircraft, and a bearing taken on another station will intersect the range course, establishing the aircraft's position from the range station.



PROBLEM WORK

- No. 12 Draw relative radio bearing diagram.
- No. 13 Draw diagram showing how sign of Mercator correction is determined.

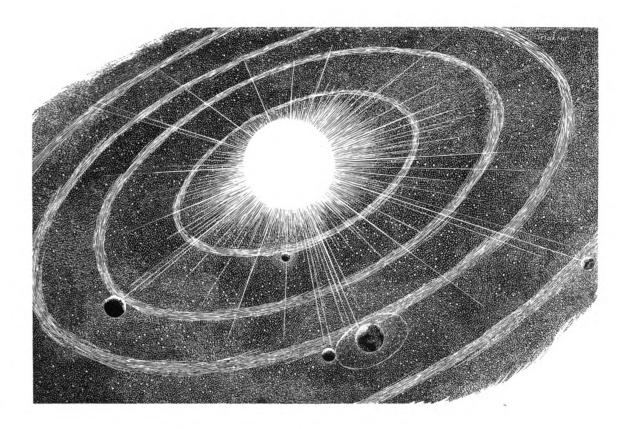


PROBLEM WORK NO. 14

RADIO BEARINGS

(Convert relative radio bearing to true Mercator bearing.)

No.	Relative Bearing	Calibration Correction	Corrected Relative Bearing	Compass Heading	Var.	Dev.	True Heading	True Great Circle Bearing	Mer- cator Correc- tion	Mercato Bearing From Station
1	330°	—10°		270°	5°E	0°			-1°	
2	200°	+10°		310°	7°E	2°E			-1°	
3	25°	+10°		45°	15°W	1°W			-4 °	
4	45°	+15°		185°	18°W	4°E			+1°	
5	100°	- 5°		140°	10°E	1°E			+3°	
6	360°	0°		77°	7°W	7°W			+4"	
7	180°	0°		295°	14°E	4°W			0°	
8	10°	+ 5°		315°	0°	3°E			+2°	
9	90°	0°	,	70°	5°E	2°W			0°	
10	270°	0°		360°	11°W	10°E			_2°	
11	350°	— 5°		100°	17°E	4°E			+4°	
12	20°	+ 7°		340°	13°W	6°W			_3°	
13	70°	+ 5°		50°	4°E	2°E			0°	
14	30°	+10°		210°	9°E	3°W			+2°	
15	320°	—15°		17°	11°W	2°W			—3°	
16	15°	+ 6°		289°	16°E	5°E			-1°	
17	105°	—11°		73°	10°E	6°E			-4°	
18	210°	+12°		359°	4°W	4°W			_3°	
19	50°	+ 7°		178°	11°E	2°W			-1°	
20	170°	- 6°		46°	1°E	1°W			+1*	



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CELESTIAL SPHERE

WHEN surface features of the earth are visible, the position of an aircraft can be determined very accurately by pilotage (navigation with reference to prominent landmarks). Two other methods of determining the position of an aircraft—radio navigation and dead reckoning navigation—have been described in preceding chapters.

Each of these methods of navigation, however, is subject to certain limitations. In dead reckoning, for example, the direction and velocity of the wind seldom are accurately known, and as a consequence an element of error always is present in the determination of a DR position. This error is *cumulative*, that is, it becomes progressively larger the farther the DR position is from a known position or fix. In long-range ocean flying it usually is impossible to check DR positions by reference to land-marks, such landmarks seldom being available. This fact makes navigation by DR unreliable, and navigation by pilotage impossible. Finally, mechanical factors and atmospheric conditions can cause radio bearings to be in error.

Thus it is apparent that any one, or all three of these methods of navigation might prove unreliable at any given time. Therefore, it is essential that the navigator preparing for long-range ocean flying learn still another method of determining his position—celestial

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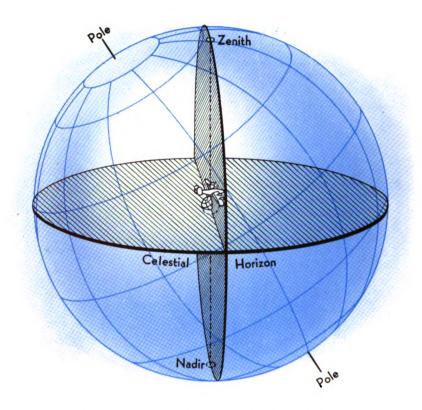


FIG. 72—ZENITH, NADIR, CELESTIAL HORIZON

navigation. Equipped with a knowledge of all four of these basic methods of navigation, he then can feel confident in flight over water or land, under any conditions.

The transition from navigation with reference to the earth to navigation with reference to celestial bodies is, in a sense, like stepping from solid earth into space. In "celestial," as the term is abbreviated, the navigator must acquire new mental habits. His vocabulary becomes enlarged with the addition of many new words and phrases. Even more important, his concept of the world and the universe undergoes a striking change. In learning celestial, the navigator must begin to reason in terms of infinity because, as pointed out earlier, the entire universe becomes his workshop. He learns to call the stars and planets by name, and to regard them as his assistants.

Though it appears complex at first glance, celestial navigation is, in reality, simplicity

itself. As in DR, a thorough working knowledge of the language of celestial is essential to a firm foundation in this method of navigation. The following terms, therefore, should be studied carefully and conscientiously, and it is strongly recommended they be memorized. It is not suggested that the navigator necessarily memorize the definitions as stated herewith, but that—more importantly—their meaning be committed to memory.

TERMS

Celestial Sphere—The celestial sphere is a vast globe of infinite radius, the center of which is considered to be located at the center of the earth, and upon which the celestial bodies are projected.

Actually, such a globe does not exist, but to an observer on the earth's surface looking up toward heavenly bodies whose distances from him are infinitely great, the universe ap-



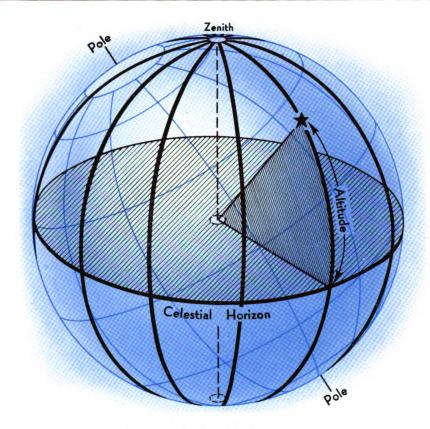


FIG. 73-VERTICAL CIRCLES, ALTITUDE

pears to be contained in a vast hollow sphere. The distances of these bodies from the earth do not interest the navigator, since their relative directions, not their distances, determine the observer's position.

Zenith—The zenith is that point on the celestial sphere directly above the observer (Figure 72). It is apparent, therefore, that as the observer changes position, his zenith moves with him. This is a most important concept, as upon it largely depends the navigator's ability to locate himself by reference to the celestial sphere.

Nadir—The nadir is that point on the celestial sphere directly beneath the observer (Figure 72). Since, like the zenith, this point is established by the observer's position, it too will move with him as he changes his position.

Celestial Horizon—The celestial horizon is a great circle on the celestial sphere whose plane passes through the center of the earth at right angles to a line joining the zenith and nadir (Figure 72). It serves as a reference circle from which the altitude of a celestial body is measured, and along which the body's East-West position may be determined with reference to an observer.

Vertical Circle—Vertical circles are great circles on the celestial sphere passing through the zenith and nadir. These serve as reference circles *along which* the *altitude* of celestial bodies is measured, and hence are sometimes called circles of altitude (Figure 73).

The Prime Vertical is the vertical circle that passes through the East and West points of the celestial horizon (Figure 74).

Altitude—The altitude of a celestial body is the angular distance from the celestial horizon to the body, as measured upon the vertical circle passing through the body. (Figures 73, 74). It is one of two coordinates (known as the horizon coordinates) by means of which the po-



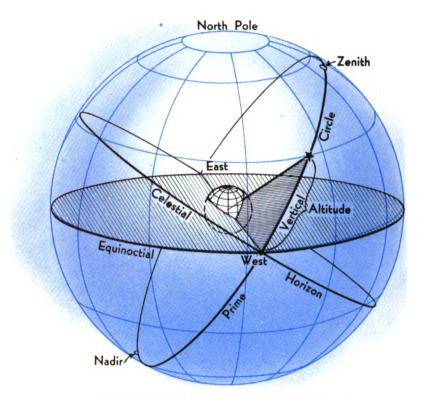


FIG. 74—EQUINOCTIAL, PRIME VERTICAL

sition of a celestial body may be located with reference to the observer's position.

Equinoctial, or Celestial Equator — The equinoctial, or celestial equator, is the great circle on the celestial sphere formed by extending the plane of the earth's equator to the sphere (Figure 74). It serves as a reference circle from which the North-South position of a celestial body is measured.

The equinoctial intersects the horizon at its East and West points.

Hour Circles—Hour circles are great circles on the celestial sphere passing through the North and South celestial poles. They serve as reference circles along which the declination of celestial bodies is measured, hence are sometimes called circles of declination (Figure 75).

Declination (dec.)—Declination of a celestial body is its angular distance from the equinoctial measured on the hour circle passing

through the body (Figure 75). It is named North or South according to its direction from the equinoctial. It is one of two coordinates (known as the *equinoctial coordinates*) by means of which the position of a celestial body may be located in space with reference to fixed points. Declination corresponds to latitude on the earth.

Celestial Coordinates—Coordinates of any kind are simply a means of locating an object with respect to two reference lines at right angles to each other. A familiar example of this is the locating of a house in a city. If a house is at the corner of 7th Street and 3rd Avenue, then its coordinates are 7 and 3. That is, it is 7 blocks North or South of the street used for North-South reference, and 3 blocks East or West of the avenue used for East-West reference. The house might also be located geographically by stating its latitude (North or South) and longitude (East or West). In



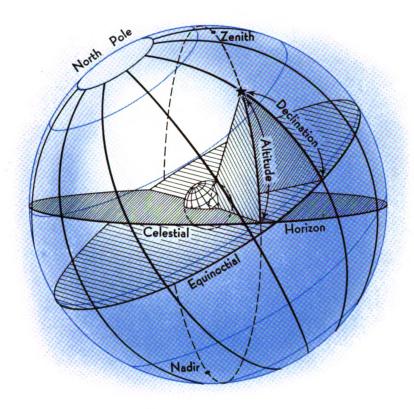


FIG. 75—HOUR CIRCLES, DECLINATION

the latter case, a different set of coordinates and reference lines would be employed than those used to establish position of the house in the city. There is a close parallel between the reference means used in the foregoing example, and those used to locate a celestial body in the sky.

For purposes of celestial navigation, two sets of coordinates, together with their reference circles, are used. The name of the primary reference circle used, in each case, gives rise to the name of the coordinate system. Thus, there is the horizon system of coordinates, and the equinoctial system.

The horizon system is established, basically, with relation to the observer's zenith. And since, as already explained (see definition of zenith), the zenith moves with the ob-

server, the horizon coordinates of a celestial body (altitude and azimuth) change as his position changes.

The equinoctial system, on the other hand, since it is derived from fixed points on the earth which are merely projected to the celestial sphere, constitutes a fixed system of coordinates. Hence the equinoctial coordinates (declination and hour angle), do not change with a change in the observer's position, but have definite values for any given instant of time. This makes possible the calculation of these values in advance, hence they can be tabulated for the navigator's use. (See Air Almanac, Chapter VI.) Using these tabulated values, the navigator can compute the horizon coordinates, which in turn make it possible for him to fix his position.



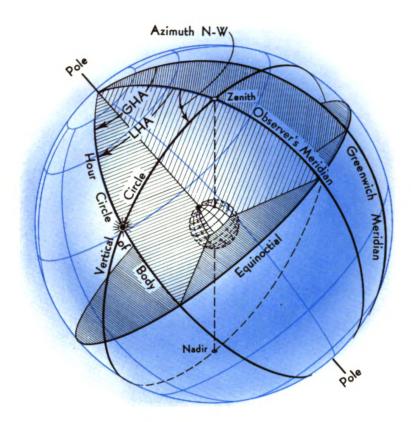


FIG. 76-AZIMUTH, LOCAL AND GREENWICH HOUR ANGLE

Azimuth (Az)—Azimuth is the bearing of a celestial body at the observer (Figure 76). It is the angle at the zenith between the celestial meridian of the observer and the vertical circle passing through the celestial body. It is measured from the elevated pole (North in North latitude, South in South latitude) and to the East or West through 180° (East when the celestial body is rising, and West when it is setting). Azimuth is the second of the two horizon coordinates by means of which a celestial body is located with reference to an observer.

Local Hour Angle (LHA)—The local hour angle of a celestial body is an arc of the equinoctial measured from the upper branch of the observer's meridian over West through 360° to the hour circle passing through the body (Figure 76). It also may be defined as the angle at the pole between the meridian of the observer

and the hour circle passing through the body. It is the second of the two equinoctial coordinates used to locate a body with relation to fixed points.

Greenwich Hour Angle (GHA) — The Greenwich hour angle of a celestial body is an arc of the equinoctial measured from the Greenwich meridian over West through 360° to the hour circle passing through the body (Figure 76). It also may be defined as the angle at the pole between the Greenwich meridian and the hour circle passing through the body. GHA corresponds to longitude on the earth.

Ecliptic—The ecliptic is the great circle path on the celestial sphere that the sun appears to follow due to the annual revolution of the earth (Figure 77). It is inclined to the equinoctial at an angle of approximately

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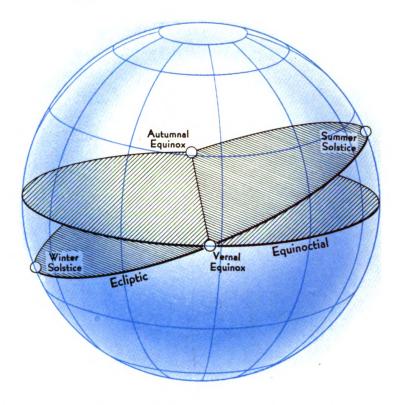


FIG. 77—ECLIPTIC, EQUINOXES, SOLSTICES

23°27′30″. This inclination is called the obliquity of the ecliptic.

Equinoxes—The equinoxes are the points in the celestial sphere where the ecliptic intersects the equinoctial (Figure 77).

- 1. Vernal Equinox [called First Point of Aries (Υ)] is that point on the equinoctial which the sun passes in changing from South declination to North declination. It occurs about March 21st and marks the beginning of spring in the Northern hemisphere.
- 2. Autumnal Equinox (called First Point of Libra) is that point on the equinoctial which the sun passes in changing from North declination to South declination. It occurs about September 21st and marks the beginning of autumn in the Northern hemisphere.

Solstices—The solstices are the points on the ecliptic where the sun attains maximum declination, Northerly or Southerly (Figure 77). The point of maximum Northerly declination is termed Summer Solstice (about June 21st). The point of maximum Southerly declination is termed Winter Solstice (about December 21st). The occurrence of the summer solstice results in the longest period of daylight in one day throughout the year, and conversely the winter solstice brings the shortest period of daylight in one day.

Thus the position of the earth along the ecliptic (or apparent position of the sun) determines the seasons of the year. The reason for this is evident when it is realized that the seasons depend primarily on the amount of heat which the earth receives from the sun, and in turn, the amount of heat received depends upon the position of the earth relative to the sun. The earth's axis, it will be remembered, is inclined at an angle to the ecliptic, hence when the North pole is tilted towards the sun, the Northern hemisphere receives a maximum



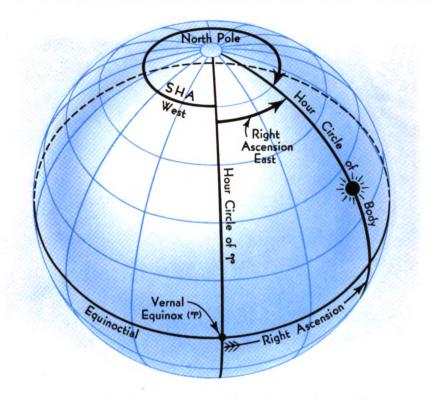


FIG. 78-RIGHT ASCENSION, SIDEREAL HOUR ANGLE

amount of heat per unit area and so experiences summer. When the North pole is inclined away from the sun, the Northern hemisphere receives a minimum amount of heat per unit area and so experiences winter.

Right Ascension (RA)—Right ascension is the angle at the pole between the hour circle of the First Point of Aries and the hour circle passing through the body, measured to the East through 24 hours or 360° (Figure 78). It also may be described as the arc of the equinoctial intercepted between these hour circles. Right ascension seldom is used in aerial navigation due to the convenience of modern air almanacs, which are tabulated in sidereal hour angle.

Sidereal Hour Angle (SHA) — Sidereal hour angle is related to right ascension in that SHA equals 360° minus RA (Figure 78). Stated as an equation:

$$SHA + RA = 360^{\circ}$$

It is the angle at the pole (measured to the West through 360°) between the hour circle of

the First Point of Aries and the hour circle passing through the body. Sidereal hour angle is used to find GHA of all star sights in aerial navigation.

Astronomical Triangle—The intersections of the observer's (celestial) meridian, the hour circle passing through a celestial body, and the vertical circle passing through a celestial body form a spherical triangle on the celestial sphere known as the astronomical triangle (Figure 79). The sides and angles of this triangle represent the relationship existing between the observer's position, and the horizon coordinates and equinoctial coordinates of a celestial body. If the approximate latitude of the observer is known, together with the hour angle and declination of the celestial body, then the altitude and azimuth of the body can be computed. The values thus obtained can then be used to determine the observer's position by methods to be discussed in later chapters.

The solution of the astronomical triangle, then, is the navigator's fundamental problem



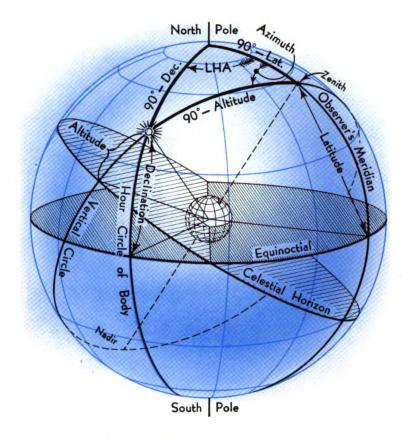


FIG. 79—ASTRONOMICAL TRIANGLE

in celestial navigation. This solution is based on formulas of spherical trigonometry. It is not necessary for the aerial navigator to know these formulas, however, except for his own interest, as the various possible solutions of the astronomical triangle have been worked out for him and compiled into tables of precomputed altitude and azimuth. From these, the desired information may be obtained by inspection.

The aerial navigator should learn how to draw the astronomical triangle, and should know its component parts, as this knowledge will help him to become familiar with the terminology of celestial navigation. In this triangle, the local hour angle (which is the angle at the pole) is the most important angle, as it determines the observer's longitude.

In drawing this triangle, remember that it is formed by three great circles:

- 1. Hour circle passing through the body.
- Celestial meridian passing through the zenith.
- 3. Vertical circle passing through the body.



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PROBLEM WORK NO. 15

CELESTIAL SPHERE

(Show the following information.)

- 1. Observer's meridian
- 2. Greenwich meridian
- 3. Hour circle
- 4. Celestial poles
- 5. Zenith

- 6. Equinoctial
- 7. Ecliptic
- 8. Vernal equinox
- 9. Longitude of observer
- 10. Latitude

- 11. GHA
- 12. LHA
- 13. Declination
- 14. SHA
- 15. Solstices
- 16. Right ascension

PROBLEM WORK NO. 16

ASTRONOMICAL TRIANGLE

(Show the following information.)

- 1. Celestial poles
- 2. Zenith and nadir
- 3. Equinoctial
- 4. Celestial horizon
- 5. Astronomical triangle
- 6. Latitude

- 7. Zenith distance
- 8. LHA
- 9. Azimuth
- 10. Altitude
- 11. Declination
- 12. Polar distance



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AIR ALMANAC

THE American Air Almanac is one of the aerial navigator's principal tools and, therefore, is deserving of careful study. The navigator should understand this indispensable volume thoroughly, because it provides him with the astronomical data required for aerial navigation. (See Appendix for sample Air Almanac pages.)

As compared with the Nautical Almanac, the information in the Air Almanac contains a certain amount of error. However, the average error is only about 0'.5, which is so slight as to be considered negligible. This error has been allowed in order to permit presentation of the information in a more condensed and convenient form, thus making possible faster solution

of celestial navigation problems, the most important being the solution of the astronomical triangle.

As explained in the previous chapter, in order to solve the astronomical triangle, the navigator must know the equinoctial coordinates (GHA and declination) of a body (Figure 80). These have been precomputed and tabulated for him in the Air Almanac. Government astronomers are assigned to the important work of predetermining, for any given instant of GCT, the exact location of all heavenly bodies useful to navigators. The findings of these astronomers are published in advance in the Air Almanac, which is printed three times annually. All in-

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formation needed for any given day's navigation is printed on front and back sides of a single page of the Almanac.

Note: To avoid the possibility of using day-old data by mistake, it is advisable to tear out each daily page as soon as it becomes obsolete.

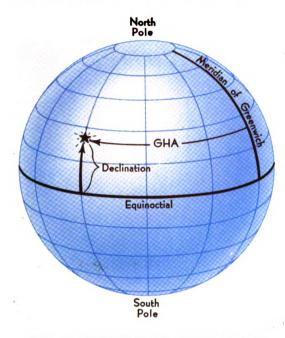


FIG. 80-EQUINOCTIAL COORDINATES

GHA AND DEC

Greenwich Hour Angle (GHA) and Declination (Dec.) of Sun, Moon, and Planets—On the daily page of the Air Almanac are listed the GHA of the sun, moon, and planets (most suitable for observation). Declination of the sun and planets is given in hourly intervals, while declination of the moon is tabulated in ten-minute intervals of GCT throughout 24 hours.

In taking this data from the Almanac, the correct declination will be the nearest tabulated value for any given instant of GCT. To obtain the correct GHA, however, it is necessary, first, to find the value listed for the preceding ten-minute interval of GCT, and then to add to it an interpolated amount of GHA for the additional minutes and seconds. These interpolation values may in turn be obtained directly from tables printed on the inside of the

front cover and also on the back of the star chart.

The moon has an interpolation table separate from the other celestial bodies due to its proximity to the earth and its relatively rapid movement.

GHA and Declination of a Star (Figure 81) -In navigation the stars are considered to be fixed bodies in space. Therefore, their relative positions are always the same. This fact is used to advantage in the Air Almanac. Instead of giving the GHA of each individual star, the Almanac lists the daily positions of the First Point of Aries or vernal equinox, as measured by its Greenwich hour angle. On the inside of the back cover, the sidereal hour angles (SHA) of the 55 brightest stars are listed, and the SHA of an additional nine stars are listed on the opposite page. SHA, as explained earlier, is the position of a star with reference to the First Point of Aries, measured to the West from the First Point of Aries.

Hence:

$$GHA (star) = GHA (Aries) + SHA (star)$$

The change in declination of a star for the four-months period which the Air Almanac covers is practically negligible. Therefore, declination is listed opposite the SHA on the in-

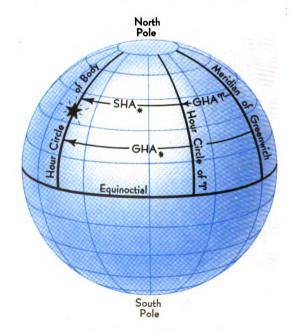


FIG. 81—GHA* = GHA γ + SHA*

side back cover, and it may be read directly for any given star.

Examples:

Jan. 1, 1943, GCT 10h12m22s. Find GHA and declination.

	Sun
GCT 10h10mGHA	331°41′
+ for 02 ^m 22 ^s Corr.	
GHA for 10h12m22s	
Declination	
	Saturn
GCT 10h10mGHA	187°27′
+ for 02 ^m 22 ^s Corr.	36'
GHA for 10h12m22s	188°03′
Declination	
	Moon
GCT 10h10mGHA	42°52′
+ for 02 ^m 22 ^s Corr.	
GHA for 10h12m22s	
Declination	
	Star
GCT 10h10mGHA γ	252°41′
+ for 03 ^m 22 ^s Corr.	36'
SHA* (Sirius)	259°21′
GHA*	412°38′
	—360°
GHA for 10h12m22s	152°38′
Declination	

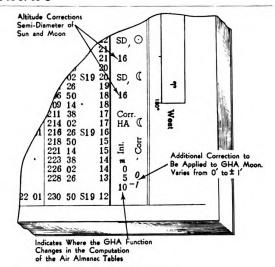


FIG. 82

Note: In lower right corner of the A. M. side of the daily page is the notation shown in Figure 82.

HOUR ANGLE DIAGRAMS

Description—The hour angle diagram is a graphic method of illustrating the relationship between the meridian of Greenwich, meridian of the observer, and the hour circle of a body. It is important because it aids the navigator in visualizing GHA, LHA, and longitude.

This relationship may be illustrated on a globe (Figure 83).

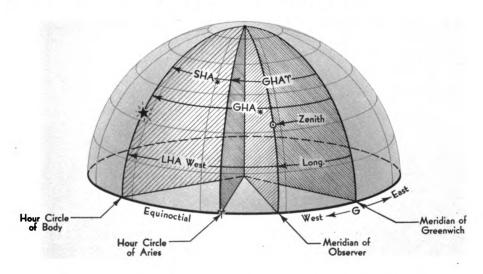


FIG. 83—RELATIONSHIP BETWEEN OBSERVER'S MERIDIAN, GREENWICH MERIDIAN AND HOUR CIRCLE OF BODY

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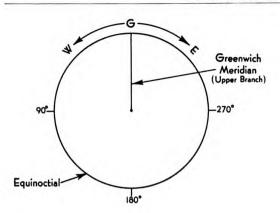


FIG. 84-BASIC HOUR ANGLE DIAGRAM

The easiest method of drawing hour angle diagrams, however, is on the plane of the equinoctial, in which case the globe is considered to be viewed from the South pole. The equinoctial thus appears as a circle, and the meridians or hour circles appear as straight lines radiating from the center. The meridian of Greenwich is drawn from the top of the circle to the center, and directions measured to the left are named West, and those measured to the right are named East (Figure 84). This diagram can be used to indicate any relationship of hour angle and longitude.

Examples:

As Used for Sun (Figure 85)

Given: Long. 160° East

GHA 125° West

Indicate: LHA of Sun

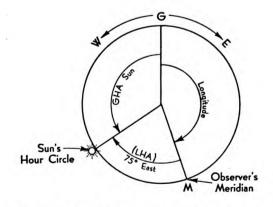


FIG. 85-HOUR ANGLE DIAGRAM FOR SUN

As Used for Star (Figure 86)

Given: Long. 170° West GHA T 120° West

SHA* 150° West

Indicate: LHA of Star

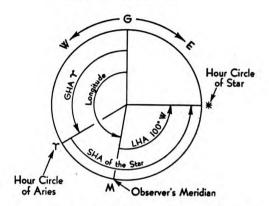


FIG. 86-HOUR ANGLE DIAGRAM FOR STAR

DEFINITIONS OF ALTITUDE

True Altitude (H_O)—True altitude is the arc of the vertical circle between the celestial horizon and the center of the celestial body. It is also the angle, measured at the center of the earth, between the celestial horizon and the center of the celestial body (see Figure 89).

Sextant Altitude (H_S)—Sextant altitude is the altitude of the celestial body as read on the sextant or octant.

Computed Altitude (H_C)—Computed altitude is the true altitude of a celestial body as calculated for an assumed position of the observer.

SEXTANT ALTITUDE CORRECTIONS

Instrument Correction (I.C.)—Instrument correction is the correction which must be applied to sextant readings because of mechanical errors in the instrument. (To be discussed more fully in Chapter IX).

Refraction (Ref.)—It is a proved principle of physics that light passing from one medium into another of different density is bent from a straight path.

When viewing a distant celestial body, the observer is in reality seeing a ray of light from that body. This ray of light follows a curved path through the earth's atmosphere due to the increasing density of the atmosphere near the

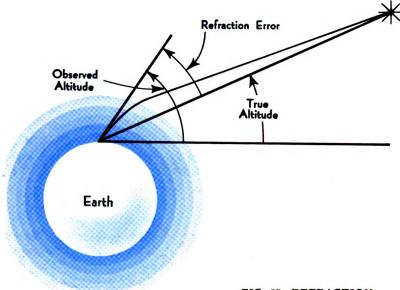
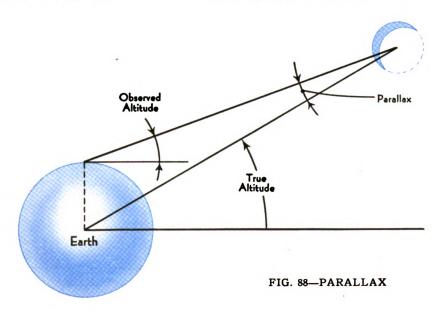


FIG. 87—REFRACTION

surface. In measuring the altitude of a celestial body the observer actually measures the altitude of a line tangent to this curve, and the difference between the last direction of the ray and its direction on entering the earth's atmosphere is the correction angle called refraction. Refraction causes the observed altitude (H_0) , as shown in Figure 87.

Correction for refraction is, therefore, always *minus*. The higher the body, the less the refraction. When the body is directly overhead, refraction is zero. The amount of this correction is tabulated on the back outside cover of the Air Almanac.

Parallax (Figure 88)—Parallax may be defined as the angle at the celestial body subtended by the earth's radius.



All navigation tables are computed on the assumption that altitude is measured from the center of the earth to the center of the celestial body. However, since the navigator measures the body's altitude from the earth's surface, theoretically a parallax correction must be applied in order to make the true altitude read as though the observer measured it from the center of the earth.

Actually, the moon is the only celestial body whose proximity to the earth makes a parallax correction necessary, all other bodies being so far distant as to make such a correction insignificant for air navigation purposes.

From examination of Figure 88 it is apparent that octant altitude always is less than true altitude. Therefore, correction for parallax always is plus. The amount of correction for various altitudes of the moon may be obtained by inspection from the A.M. side of Air Almanac daily pages. The greater the moon's

altitude, the smaller the parallax. When the moon is at zenith, parallax is zero.

Semidiameter and Dip (Figure 89)—Semidiameter and dip are altitude corrections seldom applied in aerial navigation, since they are encountered only when using the sea horizon as the horizontal reference plane. They only need to be considered, therefore, when using the marine sextant, or when using an aircraft octant to measure altitude above the sea horizon.

1. Semidiameter is the angle at the eye of the observer subtended by the radius of the celestial body. In using the sea horizon the navigator adjusts his octant to cause the upper or lower limb (outside edge) of the reflected image of the sun or moon to just touch (be tangent to) the visible sea horizon. Since the outside edge of the sun or moon is then being used to measure the altitude of the body, instead of the center of the body as required for true a'titude, it is necessary to

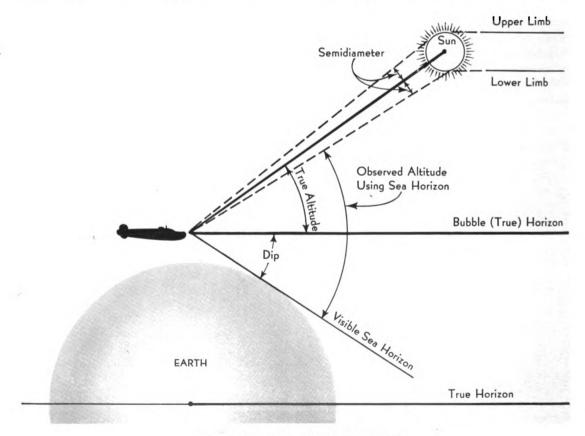


FIG. 89-DIP AND SEMIDIAMETER

apply a correction equal to half the body's diameter.

The Air Almanac gives the semidiameter correction of the sun or moon on the A.M. side of the daily page. This correction is either plus or minus, depending upon which limb of the body is used to measure the altitude. If the upper limb is used, the correction is minus. If the lower limb is used, the correction is plus.

2. Dip is the angle, at the eye of the observer, between the visible sea horizon and the true (celestial) horizon. In Figure 89, it is apparent that the altitude reading, using the visible sea horizon, is always greater than the true altitude; therefore, dip correction is always minus. The amount of correction is tabulated on the back cover of the Air Almanac.

Examples of Altitude Correction—On January 1, 1943, the following altitudes were measured with reference to the horizon while flying at an altitude of 8000 feet:

		PLANET	STAR	
	SUN	VENUS	ALTAIR	MOON
Observed Altitude	30°20′	60°15′	20°12′	28°35′
Refraction	- 01'	00'	— 02 ′	- 01'
Parallax				— 51'
CORRECTED ALTITUDE	30°19′	60°15′	20°10′	29°25′

On January 7, 1943, the following altitudes were measured with reference to the sea horizon while flying at an altitude of 200 feet:

	(Lower Lim	b) PLANET	STAR	(Upper Limb)
	SUN	JUPITER	RIGEL	MOON
Observed Altitude	15°45′	60°19′	30°55′	40°50′
Refraction	— 04'	— 01'	- 02'	— 01'
Parallax				+ 44'
Semidiameter	+ 16'			— 16'
Dip	— 14′	14'	— 14'	— 14 ′
CORRECTED ALTITUDE	15°43′	69°04′	30°39′	41°03′

POSITIONS OF PLANETS AND STARS ALONG THE ECLIPTIC

The ecliptic has been defined as the apparent path of the sun on the celestial sphere. Since all of the planets revolve around the sun, it is evident that the path of the planets across the celestial sphere also will follow, very nearly, the ecliptic. Actually, their paths never vary more than eight degrees on either side of the ecliptic.

In the Air Almanac, the diagram on the A.M. side of the daily page represents this path of the sun and planets in the celestial sphere. The sun is shown in the center, and through 180° on either side of the sun are shown the relative positions of the moon, the five planets Mercury, Venus, Mars, Jupiter, and Saturn, and the four bright stars Aldebaran, Antares, Spica, and Regulus (except when they are within five degrees of the sun).

This diagram is useful to the navigator in ascertaining positions of the planets at a glance. For instance, on January 1, 1943, Aldebaran and Saturn are shown in proximity. Recognizing Aldebaran in the sky, the navigator would know that the bright celestial body nearby was Saturn.

SUNRISE, SUNSET, MOONRISE AND MOONSET

On the P.M. side of the daily page are given tables for finding the times of sunrise, sunset, moonrise and moonset. These are tabulated in terms of local civil time and depend upon the latitude of the observer for correct interpretation.

With the nearest whole degree of the observer's latitude as an argument, the *LCT values* shown opposite the *two nearest tabulated latitudes* are noted and their difference obtained by



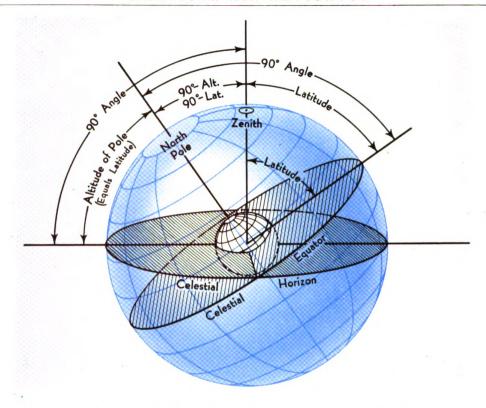


FIG. 90—ALTITUDE OF ELEVATED POLE EQUALS LATITUDE

subtracting the smaller from the greater. The exact LCT of the required rising or setting can then be obtained for the observer's latitude by interpolation.

If the GCT is desired (as is usually the case), it can be had by applying the observer's longitude (converted from degrees and minutes of arc to hours and minutes of time) to the LCT.

LATITUDE BY POLARIS

As shown in Figure 90, the altitude of the elevated pole above the celestial horizon is equal to the observer's latitude. This may be reasoned as follows:

- Angle between zenith and equinoctial = Latitude.
 - Since angle between equinoctial and pole = 90° , and angle between zenith and horizon = 90° , then
- 2. Angle between zenith and pole = 90° minus alt. pole, or 90° minus latitude.
- 3. Hence, altitude pole = latitude.

From the diagram in Figure 90, it is apparent that the altitude of a star at the pole would be equal to the latitude. Polaris is known

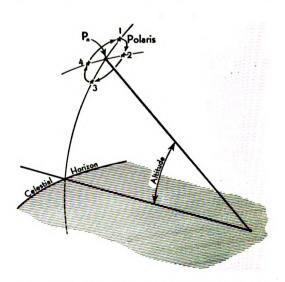


FIG. 91-POLARIS NOT EXACTLY AT Pn

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as the North Star. However, it is not located exactly at the pole (P_n) , but approximately one degree or sixty minutes away. As the earth revolves, the star Polaris appears to revolve around P_n (Figure 91).

When Polaris is in position No. 1 (Figure 90), the altitude of Polaris would be greater than the true altitude of P_n . When Polaris is in position No. 2 or No. 4, the altitude of Polaris would be equal to the altitude of P_n . With Polaris in any position other than No. 2 or No.

4—such as No. 1 or No. 3—a correction would have to be applied to the true altitude of Polaris to obtain the true altitude of P_n , hence the latitude.

The Polaris table in the Air Almanac (located on the back of the star chart) gives the amount of correction to apply to the true altitude of Polaris, in order to find latitude. The tables are computed to give the correction with relation to the local hour angle of the First Point of Aries (LHA Υ) from 0° to 360°, measured to the West.

Example: On January 1, 1943, at GCT 11^h20^m20^s, in longitude 145°18' West, the observed altitude of Polaris—using a bubble horizon—was 32°15', and the height of aircraft 5000 feet.

GCT 11 ^h 20 ^m GHA Υ	270°14′	$H_{\mathbf{S}}$	32°15′
+ For 00 ^m 20 ^s Corr.	05′	Ref.	— 01 ′
GCT 11 ^h 20 ^m 20 ^s GHA γ	270°19′	H_{0}	32°14′
Longitude	145°18' West	LHAT Corr.	+ 10'
LHAT	125°01' West	LATITUDE	32°24′N



PROBLEM WORK NO. 17 GHA AND DECLINATION

(Find GHA and declination See Appendix for extracts from Air Almanac.)

No.	DATE	CELESTIAL BODY	GCT	GHA	DECLINATION
1	5- 1-43	SUN	00:17:10		
2	5- 5-43	SUN	22:08:07		
3	5-10-43	SUN	01:00:07		
4	5-15-43	SUN	00:51:17		
5	5-20-43	SUN	17:01:07		
6	5-30-43	JUPITER	18:01:07		
7	5-15-43	JUPITER	14:20:10		
8	5- 1-43	JUPITER	16:20:07		
9	5-10-43	JUPITER	13:24:10		
10	5-20-43	JUPITER	18:08:12		
11	5-30-43	MOON	22:48:30		
12	5- 1-43	MOON	23:00:07		
13	5-15-43	MOON	00:02:07		
14	5- 5-43	MARS	10:06:09		
15	5-15-43	MARS	12:05:00		
16	5- 1-43	FOMALHAUT	09:08:07		
17	5-10-43	BETELGEUX	13:39:07		
18	5-20-43	ARCTURUS	14:17:10		
19	5-15-43	DENEB	08:22:10		
20	5-30-43	ALTAIR	09:05:07		

PROBLEM WORK NO. 18 HOUR ANGLE DIAGRAMS

(Find GHA and LHA of the celestial body. Draw hour angle diagrams.)

No.	DATE	LONGITUDE	CELESTIAL BODY	GCT	GHA ARIES	SHA	GHA BODY	LHA
1	****	45°22′W	SUN	***			300°20′	
2	5-30-43	104°15′W	SUN	10:00:00				
3	5-15-43	40°00′E	SUN	16:23:00				
4	5-15-43	170°00′E	MOON	04:27:23				
5	5-10-43	117°11′W	MOON	08:20:00		(1)		
6	5- 5-43	105°30′E	MOON	19:24:00				
7	5- 1-43	5°30′E	JUPITER	18:42:30				
8	5-10-43	90°00′W	VENUS	22:24:00				
9	5-30-43	137°27′W	MARS	06:52:00				
10	****	15°00′W	DENEB	****	260°00′			
11	5- 1-43	178°50'E	SIRIUS	04:20:00				
12	5-15-43	70°30′W	ALTAIR	10:20:00				
13	5- 5-43	90°05′E	ALDEBARAN	23:00:00				
14	5-30-43	120°23′W	ANTARES	14:30:00				
15	5-10-43	20°15′E	FOMALHAUT	22:49:00				
16	5-15-43	2°15′W	PROCYON	16:05:00				
17	5- 1-43	29°39′E	NUNKI	02:08:00				
18	5-30-43	95°15′W	SPICA	09:41:00				



PROBLEM WORK NO. 19 OCTANT ALTITUDE CORRECTIONS

[Correct sextant altitude (H_S) to true altitude (H_O). Bubble horizon used except where sea horizon is indicated.]

		CELESTIAL			H _s CORRECTIONS				
No.	DATE	BODY	Hs	ALTITUDE	Ref.	Par.	SD	DIP	Ho
1	5- 5-43	SUN	49°12′	5000′					
2	5-10-43	SUN	57°49′	8000′					
3	5-15-43	SUN	36°18′	12,000′					
4	5-20-43	SUN	52°42′	6000′					
5	5-25-43	MOON	38°16′	8000					
6	5-10-43	MOON	33°38′	12,000					
7	5- 1-43	MOON	29°59′	10,000′					
8	5- 5-43	MOON	37°23′	9000					
9	5-20-43	RIGEL	23°19′	11,500′					
10	5-25-43	CANOPUS	39°42′	2000′					
11	5- 1-43	SIRIUS	41°15′	4500′					
12	5-20-43	CAPELLA	27°29′	2000					
13	5-10-43	JUPITER	42°39′	8500′					
14	5-15-43	SATURN	35°23′	14,500′					
15	5-25-43	VENUS	28°52'	8600′					
16	5-30-43	JUPITER	39°17′	11,000′					
17	5- 1-43	Lower-Limb SUN	30°42′	sea horizon 600'					
18	5-30-43	Upper-Limb MOON	45°12′	sea horizon 800					
19	5-30-43	ALTAIR	42°21′	sea horizon 500'					
20	5-20-43	SATURN	41°38′	sea horizon 100'					

PROBLEM WORK NO. 20

LATITUDE BY POLARIS

(Find latitude.)

No.	DATE	GCT	Hs	I.C.	ALTITUDE	LONGITUDE	LATITUDE
1	5- 1-43	19:33:48	33°48′	—15'	14,000′	11 7°22′ W	
2	5- 5-43	08:00:12	38°00′	— 8 ′	14,000′	133°42′W	
3	5-10-43	18:32:10	36°34′	-23'	14,000′	85°23′E	
4	5-15-43	03:40:00	38°43′	+ 3'	6000′	90°00′W	
5	5-20-43	17:30:14	30°06′	- 2'	10,000′	114°00′E	
6	5- 1-43	11:13:40	36°28′	– 8 ′	5000′	178°00′E	
7	5- 5-43	09:30:14	42°20′	+ 1'	12,000′	118°12′W	
8	5-10-43	23:30:00	25°00′	– 3 ′	5000′	152°40′E	
9	5-15-43	02:43:19	31°14′	– 7'	6000′	20°28′W	•
10	5-20-43	17:14:42	24°19′	+ 1'	10,000	114°26′E	
11	5- 1-43	02:10:30	33°58′	- 5'	8000′	117°11′W	
12	5- 5-43	06:25:10	25°42′	+ 5'	5000′	122°14′W′	
13	5-10-43	03:26:14	44°07′	+ 8'	10,000′	121°14′E	
14	5-15-43	22:12:30	29°56′	+ 1'	6000′	94°10′W	
15	5-20-43	20:34:21	45°10′	- 1'	14,000′	176°41′E	
16	5- 1-43	14:31:00	3 6°54′	— 7 ′	9000'	69°00′E	
17	5- 5-43	19:11:23	28°04′	+11'	8000	119°32′E	
18	5-10-43	05:16:13	43°11′	+ 3'	7000	110°11′W	
19	5-15-43	11:02:00	33°02′	– 9 ′	11,000′	143°21′W	
20	5-20-43	19:51:29	39°55′	- 4°	9000	178°21′E	



CELESTIAL REVIEW EXAMINATION NO. 1

1. Define:

- (a) Altitude
- (b) Equinoctial
- (c) Local Hour Angle
- (d) Azimuth
- (e) Sidereal Hour Angle

- (f) Declination
- (g) Vertical Circle
- (h) First Point of Aries
- (i) Ecliptic
- (j) Sphere

2. Prove with the aid of diagram:

- (a) LHA = GHA Longitude West
- (b) $GHA* = GHA \Upsilon + SHA*$
- 3. Find LHA to nearest whole degree; show solution and diagram.
 - (a) May 1, 1943

Sun

GCT 08:21:14

Long. 75°E

(d) May 5, 1943

Vega

GCT 04:12:10

Long. 23°30'W

(b) May 10, 1943

Jupiter

GCT 20:03:04

Long. 126°10'W

(e) May 15, 1943

Deneb

GCT 01:19:43

Long. 100°E

(c) May 20, 1943

Moon

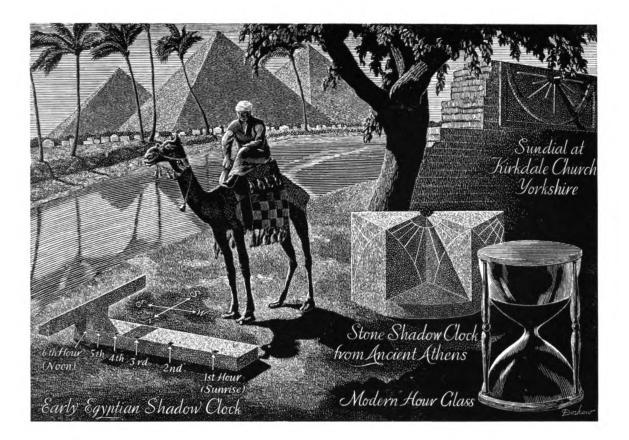
GCT 17:50:00

Long. 117°12'E

- 4. Draw the Celestial Sphere showing the following:
 - (a) Zenith
 - (b) Nadir
 - (c) Horizon Coordinates
 - (d) Celestial Poles

- (e) Equinoctial Coordinates
- (f) Astronomical Triangle
- (g) Ecliptic
- (h) Vernal Equinox





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TIME

THE navigator's concept of time differs radically from that held by the average citizen. To the man on the street, time affords a method of determining the beginning and end of a working day, or aids him in keeping an appointment. To be "on time" means, to the citizen, to arrive at his destination within a few minutes of the predetermined moment.

But the navigator has a deeper respect for time. "On time" to him means, literally, on time to the very second if possible, for a variance of seconds in his timekeeping will result in a miscalculation—perhaps a dangerous one—of his position.

Celestial navigation involves knowing, at any instant, the exact location in the celestial

sphere of all important celestial bodies with relation to the prime meridian of Greenwich. Lacking the exact time, the navigator would be unable to determine the exact location of these bodies. It follows, then, that he would be unable to determine the exact location of his aircraft, for his location is determined by reference to the position of these celestial bodies.

Definition—Time may be defined as a measure of duration, or the elapsed interval between two events.

Measurement of Time—A measure of time is afforded in the daily rotation of the earth on its axis, by observing the elapsed interval between two successive apparent transits of the sun or a star over a given terrestrial meridian

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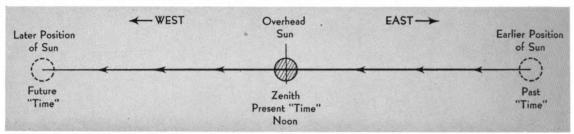


FIG. 92-APPARENT MOVEMENT OF SUN AFFORDS MEASURE OF TIME

(Figure 92). Although any meridian may be used, by international agreement the meridian through the Naval Observatory at Greenwich, England, was chosen as the prime meridian from which to reckon time.

Transit Instrument—Time is recorded at the observatory by a transit instrument. Basically, this instrument is a tube, the longitudinal axis of which is aligned with the meridian and the upper end of which contains a series of threads, parallel to the meridian. The lower end contains photographic equipment, which automatically photographs, on a moving plate, the exact instant that the celestial body chosen crosses the meridian (Figure 93).

Note: 1. The location of a celestial body West of Greenwich is determined by Greenwich hour angle.

- 2. The location of an observer either East or West of Greenwich is determined by longitude.
- 3. The location of a celestial body in relation to the observer is determined by local hourangle.

Relationship of Time, Hour Angle and Longitude (Figure 94)—GHA, LHA, and longitude are measured in degrees of arc along the equinoctial or equator, which are great circles equal to 360° of arc.

Time also may be converted into degrees of arc, because the unit of time (one day) is generated by the apparent movement of a body, in a circle of 360° of arc, around the earth. Therefore, time, hour angle, and longitude are related directly to each other.

Time may be converted into degrees of arc (hour angle or longitude), or arc (hour angle or longitude) may be converted into time by division or multiplication.

Conversion of Time Into Arc—The unit of time (one day) is divided into 24 hours of 60 minutes each, and each minute equals 60 seconds.

Since one day of 24 hours equals 360° of arc, the division of 360° by 24 hours proves that one hour equals 15° of arc.

Thus: One minute = $\frac{1}{4}^{\circ}$ (or 15') of arc. Four minutes = 1° of arc. One second = $\frac{1}{4}$ ' (or 15") of arc. Four seconds = 1' of arc.

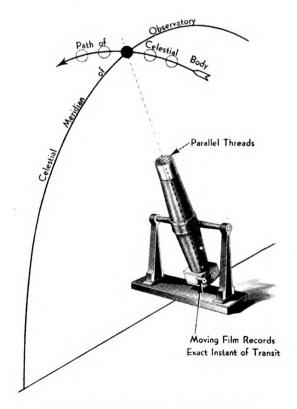


FIG. 93—OPERATION OF TRANSIT INSTRUMENT

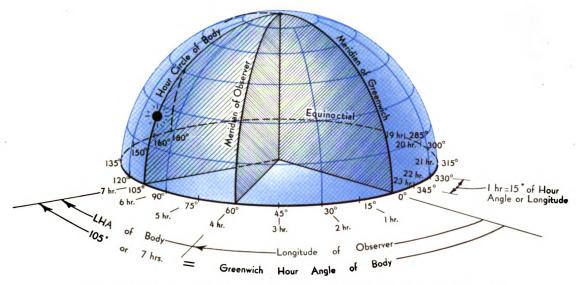


FIG. 94—RELATIONSHIP OF TIME, HOUR ANGLE, AND LONGITUDE

Three Kinds of Time—In addition to its daily rotation on its own axis, the earth also is describing a yearly revolution around the sun. The path it follows in this revolution is known as the earth's orbit. This real movement of the earth gives rise to an apparent movement of the sun. But since the earth does not move at a constant rate along its orbit, the apparent motion of the sun is not uniform, nor does it correspond exactly to the apparent movement of the stars. This variation in apparent movement gives rise to three kinds of time:

- 1. Apparent solar time, the unit of which is one apparent day.
- 2. Mean time or civil time, the unit of which is one civil day.
- 3. Sidereal time, the unit of which is one sidereal day.

APPARENT SOLAR TIME

Measurement — Apparent solar time is measured by the daily motion of the true sun.

The Unit — One apparent day is the interval of time between two successive lower transits of the sun over the same meridian. Obviously, the sun actually would have to be over the upper branch of the observer's meridian in order to measure the exact instant of transit. However, the unit, one day, containing twenty-four hours, is considered to have commenced

twelve hours earlier, or at the instant the sun crossed the lower branch of the meridian, at midnight. What actually is measured is *apparent noon* (Figure 95). Thus, time and hour angle differ by twelve hours, as hour angle is measured from the *upper* branch of the meridian.

Variation in Apparent Time—Clocks cannot be regulated to apparent solar time because the unit, one solar day, varies in length from day to day. This unequal rate is due to the obliquity of the ecliptic, and the lack of uniformity of motion of the earth in its orbit.

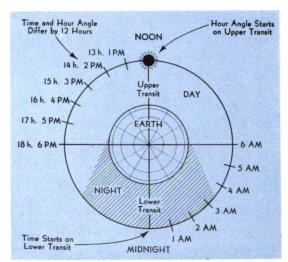


FIG. 95—UPPER AND LOWER TRANSITS OF SUN

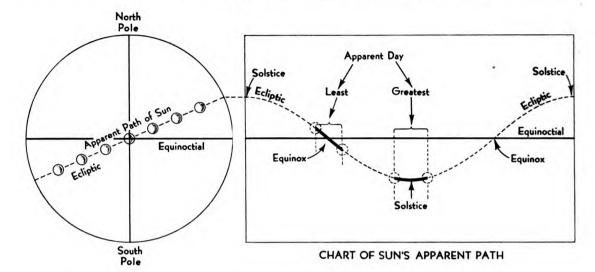


FIG. 96—VARIATION IN LENGTH OF APPARENT DAY DUE TO OBLIQUITY OF ECLIPTIC

Obliquity of the Ecliptic — Uniform time and hour angle are measured on the equinoctial. However, the apparent path of the sun is along the ecliptic, which is inclined at an angle of 23°27′30″ to the equinoctial. Hence, when the sun's motion is translated to the equinoctial, each apparent day varies in length (Figure 96).

Because of the angle of the apparent sun's path on crossing the equinoctial, the apparent day intercepts a smaller arc of equinoctial at the equinoxes than at the solstices, where the apparent path is parallel to the equinoctial.

Lack of Uniformity of Motion of the Earth in Its Orbit—In its yearly movement around the sun, the earth describes an ellipse.

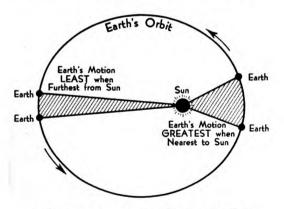


FIG. 97—EARTH'S RATE OF MOTION NOT UNIFORM

It has been demonstrated by Kepler's second law that in December, when the earth is closest to the sun (91,300,000 miles), the earth travels at a greater rate than when farthest away in July (94,000,000 miles). This uneven rate of travel of the earth causes the apparent motion of the sun to vary (Figure 97).

CIVIL TIME OR MEAN SOLAR TIME

Description—Civil life is mainly dependent on the hours of daylight. Therefore, the sun is the most logical reference point for measuring civil time. But since clocks cannot be regulated to the apparent sun's motion, a fictitious body called the mean sun is assumed to move along the equinoctial at a uniform daily rate, equal to the average rate of the true sun along the ecliptic.

Measurement—Civil time, or mean time, is measured by the daily motion of the mean sun.

Unit—One civil day is the interval of time between two successive lower transits of the mean sun over the same meridian. Clocks are regulated to civil time because it is uniform. Clocks used in civil life usually divide the day of 24 hours into two parts of 12 hours each. The 12-hour period measured from the instant of lower transit of the mean sun is called A. M. time, and the 12-hour period measured from the instant of upper transit is called P. M. time.



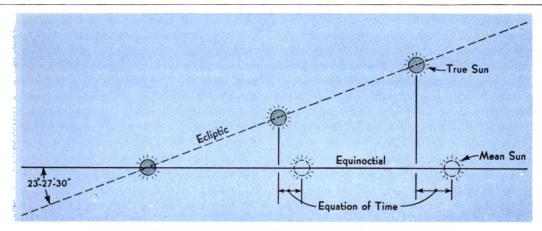


FIG. 98-RELATIONSHIP OF MEAN TIME TO SOLAR TIME

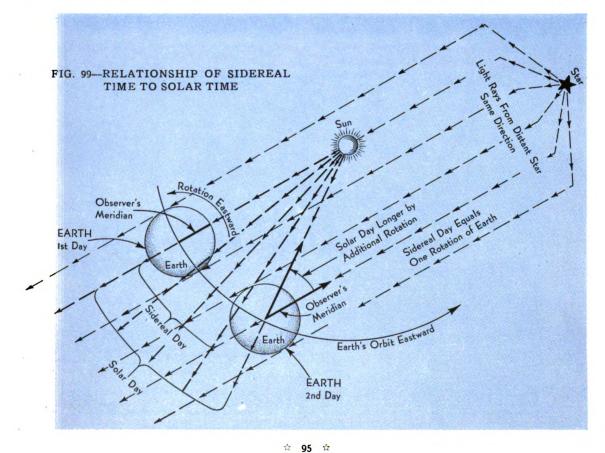
Chronometers used in navigation, however, usually are equipped with a 24-hour dial.

Equation of Time—The equation of time is the difference in hour angle between the hour circle of the true sun and the hour circle of the mean sun (Figure 98). The true sun sometimes is ahead and sometimes behind the mean sun by an amount which varies from zero to about 16 minutes.

SIDEREAL TIME

Measurement — Sidereal time is derived from the apparent movement of the stars.

Unit-One sidereal day is the interval of



time between two successive upper transits of the First Point of Aries over the same meridian. (The First Point of Aries, as previously defined, is one of two points of intersection of the ecliptic and equinoctial. Although it is a computed point in the celestial sphere invisible to an observer, it was selected as the point of origin for sidereal time because, in theory, it moves along the equinoctial at a uniform rate.)

Since the sidereal day starts at the instant the First Point of Aries crosses the upper branch of a meridian, sidereal time and the hour angle of the First Point of Aries are equivalent.

Difference Between Sidereal and Solar Time (Figure 99)—Units of sidereal time are of less duration than corresponding units of solar time because the sidereal day is measured from a star, whose distance is so infinitely great it may be considered a fixed point in space. By comparison, the solar day is measured from the sun, which appears to move due to the earth's yearly revolution around the sun.

Since stars are fixed, the sidereal day is generated solely by the earth's rotation, which is equal to approximately 23^h56^m of a mean

solar day. A mean solar day is nearly four minutes greater than a sidereal day because each day the earth moves in its orbit approximately 4° around the sun. Therefore, before two successive transits of the sun can be observed, the meridian of the observer will have to perform more than one complete rotation, corresponding to the apparent daily change in the sun's position.

The complete orbit covered by the sun is a mere pin point in comparison with the infinite distance of the nearest star. Therefore, the direction of a star is the same for any position of the earth in its orbit.

ZONE TIME

Description—The civil day for any position on the earth starts at the instant the mean sun crosses the lower branch of the meridian of that place. Therefore, *civil time* varies with the longitude of the place.

For convenience, and also in order to avoid endless confusion when traveling or in every-day business life, the entire region—as near as practical—extending $7\frac{1}{2}^{\circ}$ of longitude on either side of a designated standard meridian

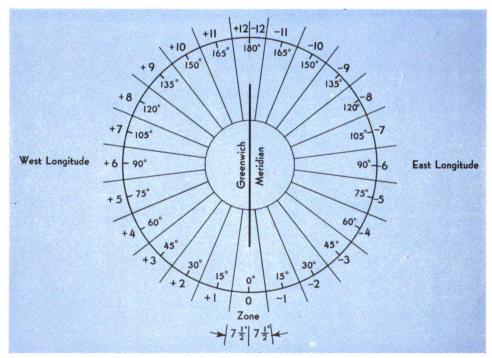


FIG. 100—DERIVATION OF ZONE DESCRIPTIONS

keeps its watches set to the time of the standard meridian. This time is called zone time.

The 7½° of longitude on either side of the standard meridian form a zone 15° wide which equals the number of degrees of longitude the mean sun appears to travel in one hour. In order to develop zone time, the surface of the earth is considered to be divided into 24 of these one-hour zones, and the 24 standard meridians (15° of longitude apart) commence with the meridian of Greenwich as the prime meridian for reckoning time and longitude.

Zone Description (ZD) (Figure 100)— Zone description, abbreviated ZD, is the number of hours the zone is located East or West of the prime meridian of Greenwich. The twelve zones west of Greenwich are considered plus, and the twelve zones East of Greenwich, minus.

The zones in West longitude are called plus zones because, when an aircraft is in West longitude, the Greenwich civil time is greater than the local zone time, hence the ZD must be added to the zone time to find the GCT. This is due to the apparent westward movement of the

sun. When the sun is on the Greenwich meridian it has not yet crossed the meridians West of Greenwich, but it already has crossed the meridians East of Greenwich. As a result, when an aircraft is in East longitude, the Greenwich civil time is less than the local zone time and the zones are called minus zones, which means that the ZD must be subtracted from zone time to get the GCT (Figure 100).

International Date Line—The lower branch of the Greenwich meridian is known as the International Date Line, because an observer crossing this meridian will experience a date change.

Since zones extending to the West of Greenwich increase progressively to plus 12 hours, and zones East of Greenwich to minus 12 hours, obviously where they meet (at the lower branch of the Greenwich meridian) there exists an accumulated time difference of 24 hours or one day. An observer crossing from the plus 12 (West) zone into the minus 12 (East) zone would, therefore, gain one day. Conversely, crossing from East to West, he would lose one day.

Zone Time Conversion—If either the zone time or the Greenwich civil time is known, the other is easily computed by the following jingle:

Longitude West—Greenwich Time Best. Longitude East—Greenwich Time Least.

Example No. 1

May 1, Longitude 75° West, Zone Time 10:20 A. M.

Find: GCT.

Longitude 75° West
$$\frac{15^{\circ} \text{ (one hour longitude)}}{15^{\circ} \text{ (one hour longitude)}} = +5 \text{ hours} = \text{Zone Description}$$
Zone Time = 10:20 A. M.
$$ZD = +5:00$$
GCT 15:20 (Greenwich Time Best)

Example No. 2

May 1, Longitude 90° East, GCT 20h30m00s

Find: Zone Time.

$$\frac{\text{Longitude }90^{\circ} \text{ East}}{15^{\circ}} = -6 \text{ hours} = \text{Zone Description}$$

$$\frac{\text{GCT}}{\text{CD}} = 20:30:00 \quad \text{(Greenwich Time Least; there-}$$

$$\frac{-6:00:00}{26:30:00} \quad \text{fore, ZD} - 6 \text{ hours is added}$$

$$\frac{26:30:00}{-24:00:00} \quad \text{to GCT)}$$

$$\frac{-24:00:00}{2:30 \text{ A.M. May 2}}$$

LCT-GCT Relationship-As discussed previously, civil time is time based on the apparent passage of the mean sun over the lower branch of a meridian on the earth. If the Greenwich meridian is used, the result is GCT. If any meridian other than the Greenwich meridian is used, the result is known as local civil time. Since the relationship between any meridian on the earth and the Greenwich meridian is determined by longitude, it is logical to assume—as is actually the case-that LCT and GCT also are related by longitude. In other words, the local civil time for any meridian, at any given instant of time, differs from Greenwich civil time by the longitude of that meridian. This may be expressed as follows:

Conversely,

$$LCT = GCT - West Longitude, or + East Longitude.$$

The above formulas may be used to determine either LCT or GCT if one of them, and the longitude, is known. Or, if both the LCT and GCT are known, then it is possible to solve for the longitude. Obviously, however, consistent terms must be used. If solving for time, then longitude must be converted from arc to time; if solving for longitude, then the difference between LCT and GCT must be converted to degrees of arc.

It is important to recognize that zone time is, in reality, no more than a special case of local civil time, the distinction being that in zone time, the entire area lying $7\frac{1}{2}^{\circ}$ on either side of a standard meridian uses the local civil time of that standard meridian as its time. Actually, every point within the area has its own local civil time. Thus the zone time of a place whose longitude is 16° is one hour different than the GCT, whereas its LCT differs from the GCT by one hour and four minutes, which represents the exact longitude of the place converted from arc to time.

Examples of LCT and GCT Problems:

Example No. 1

May 1, Longitude $83^{\circ}30'$ West, LCT = 6:32 A. M.

Find: GCT.

Longitude 83°30' West, converted to time = 5h34m

$$\frac{(75^{\circ})}{(15)} = 5^{\circ}$$
) + $(8^{\circ} \times 4^{\circ} = 32^{\circ})$ + $(30' \times 4^{\circ} = 120^{\circ} \text{ or } 2^{\circ}) = 5^{\circ}34^{\circ}$
LCT = $6^{\circ}32^{\circ}$
Longitude = $5^{\circ}34^{\circ}$ West
GCT = $12^{\circ}06^{\circ}$ (Longitude West—GCT Best)

Example No. 2

May 1, Longitude 83°30' East, GCT = 16h20m10s

Find: LCT.

Longitude 83°30' East, converted to time = 5h34m

GCT = $16^{h}20^{m}10^{s}$ Long. $5^{\circ}34'00''$ East LCT = $21^{h}54^{m}10^{s}$ or $9^{h}54^{m}10^{s}$ P. M. (Longitude East —GCT Least)



PROBLEM WORK NO. 21

LOCAL ZONE TIME

(Find arrival time and date in GCT and local zone time.)

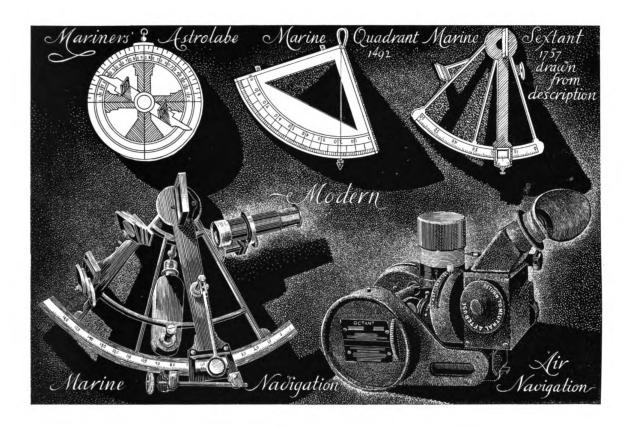
		102.	DEPARTURE	FLYING	ARRIVAL TIME AND DATE		
No.	FROM	то	(GCT)	TIME	GCT	ZONE TIME	
1	San Francisco	Honolulu	10:00 May 1	12h00m			
2	Canton	Honolulu	21:00 May 5	9h00m			
3	Christmas	Fiji	14:00 May 10	7h00m			
4	New Caledonia	Brisbane	11:00 May 15	6h30m			
5	Brisbane	New Caledonia	23:00 May 20	6h00m			
6	Fiji	Canton	10:30 May 25	8h15m			
7	Honolulu	San Francisco	23:00 May 30	13h00m			
8	Honolulu	Christmas	14:15 May 15	10h00m		X =	
9	Christmas	Fiji	15:00 May 1	7h00m			
10	Fiji	New Caledonia	16:30 May 10	6h00m			
11	New Caledonia	Brisbane	09:00 May 5	6h30m			
12	Brisbane	New Caledonia	06:30 May 20	5h30m			
13	New Caledonia	Fiji	17:15 May 25	7h00m			
14	Fiji	Canton	16:00 May 15	7h00m			
15	Canton	Honolulu	07:00 May 30	11h00m			
16	Honolulu	San Francisco	14:30 May 1	13h00m			
17	San Diego	Honolulu	05:13 May 5	13h41m			
18	San Francisco	San Diego	22:00 May 10	3h00m			
		ESCRIPTION ar Time)	San Francisco Honolulu	10 + 7 + 9½ +10½	Christmas Is. Fiji Islands New Caledonia San Diego	+10½ -12 -11 + 7	

PROBLEM WORK NO. 22

LCT-GCT

(Find missing LCT or GCT, and date to nearest second.)

		GCT		LCT	
No.	LONGITUDE	TIME	DATE	TIME	DATE
1	90° \V	22:30:20	May 1		
2	15°E	04.16:00	May 5		
3	110°15′W	05:55:00	May 10		
4	178°30′E	23:45:30	May 15		
5	117°11′W	16:43:04	May 20		
6	3°15′E	09:20:20	May 25		
7	145°30′W	08:25:30	May 30		
8	90°15′E	18:29:00	May 10		
9	170°16′E	09:05:06	May 1		
10	116°14′E	18:42:00	May 15		
11	173°40′W			06:40 P. M.	May 5
12	162°10′E			05:10 P. M.	May 1
13	93°20′E			12:42 P. M.	May 10
14	46°30′E			10:00 A. M.	May 15
15	73°40′W			07:56 P. M	May 20
16	117°11′W			04:53 P. M.	May 25
17	173°20′E			12:00 Noon	May 30
18	45°00′W			02:16 P. M.	May 15
19	168°10′W			11:41 P. M.	May 5
20	101°11′E			01:32 A. M.	May 20



\$8 \$

AIRCRAFT OCTANT

LIKE the modern aircraft compass, which is an up-to-date version of the medieval mariners' lodestone, today's aircraft octant is essentially a refinement of the early altitude-measuring devices used by such famed navigators as Columbus and Vasco de Gama. Columbus knew little of the science of celestial navigation as it is practiced today. History indicates that he relied almost exclusively upon dead reckoning, at which he was unusually proficient considering the crudeness of methods employed.

According to historians, the common quadrant was the only instrument of celestial navigation Columbus ever used. This primitive device was a quarter-circle of wood with sights

along one edge. A weight, swung from the apex of the instrument by a silk cord, caused the cord to give an altitude reading on the 90° scale when the sights were lined up on the heavenly body observed. It is easy to imagine the difficulties these early navigators encountered when trying to use such a device on their small, rolling, pitching ships. In fact, it is thought that Columbus never employed the quadrant for navigation, using it solely in attempts to determine the position of islands and other areas discovered in his journeys. Vasco de Gama, too, was equipped with some sort of altitude-measuring device, thought to be an astrolabe, and it is said that he always disem-

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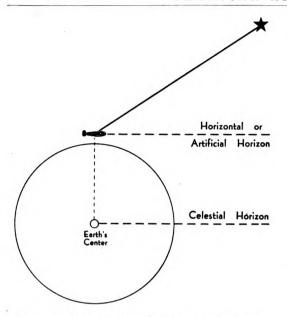


FIG. 101—OCTANT EMPLOYS ARTIFICIAL HORIZON

barked and hung the instrument on a tree in order to secure a steady rest when taking altitude sights.

The term "sextant" (sixth of a circle) first was applied to an optical instrument for measuring angular distances, invented by John Hadley in 1731. Hadley's device actually was an octant (eighth of a circle), but his instrument was enlarged by a Capt. Campbell in 1757 to one-sixth of a circle to meet the needs of navigation.

The marine sextant used for navigation of surface vessels is, generally speaking, not practical for aerial navigation since it relies upon a visible horizon from which to measure the altitude of a celestial body. Such a horizon seldom is available to the aerial navigator, and he must, therefore, use an instrument which contains its own horizon. For this reason the bubble octant was developed. Conversely, the

bubble octant is seldom useful on surface vessels because results obtained with it are not considered sufficiently accurate for surface navigation purposes.

OCTANT OR SEXTANT

The aircraft octant, or sextant, is an instrument for measuring the angle between any two visible objects. The principal use of the octant in aerial navigation is for measuring the altitude of a celestial body above an artificial horizon (a horizontal plane parallel to the celestial horizon) and in some cases, the altitude of a body above sea horizon (See Figure 101).

The terms "octant" and "sextant" are derived from the size of the angle such instruments are capable of measuring (Figure 102).

An octant measures angles up to 90°.

A sextant measures angles up to 120°.

A quintant measures angles up to 144°.

A quadrant measures angles up to 180°.

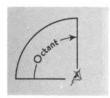
Most aircraft instruments are of the octant type, as the aerial navigator seldom has reason to measure an angle over 90°. A few, however, are of the sextant type.

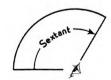
ACCURACY OF AIRCRAFT OCTANTS

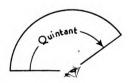
Obviously, it is impossible to measure exactly the altitude of a celestial body. The accuracy of measurement depends upon the refinement of the measuring instrument.

The theodolite, a high-precision instrument used in surveying, can measure angles as small as 1/1000th of a minute of arc.

A marine sextant, using the visible sea horizon, will measure altitude accurately to within tenths of a minute. Aircraft octants, however, which are made light and compact for easy handling, can be relied upon only to measure an altitude, from the sea horizon, to within one or two minutes, and when the artificial horizon is used, measurements may contain inaccuracies of from four to eight minutes or more.







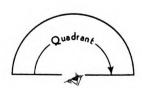
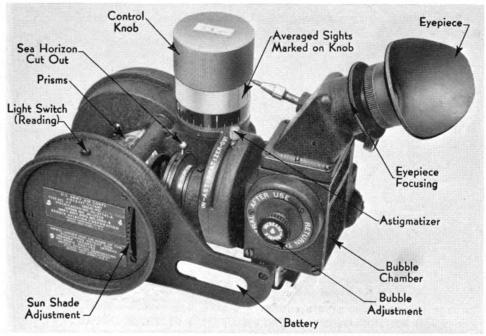


FIG. 102—ALTITUDE RANGE DETERMINES NAME OF INSTRUMENT



Courtesy Eclipse Pioneer Division Bendix Aviation Corporation

FIG. 103-BUBBLE OCTANT (Pioneer averaging type)

TYPES OF OCTANTS

Reasons for Different Types of Octants— The ideal aircraft octant would be one which could be used to measure, with consistent accuracy, the altitude of a celestial body with a single observation.

This ideal is nearly accomplished when the altitude of a celestial body is measured with reference to the sea horizon. However, the sea horizon seldom is visible to the aerial navigator, and even when it is, it can be used only if the aircraft is at a very low altitude. Hence it is necessary, in aerial navigation, to employ an instrument which will measure the altitude of celestial bodies above an artificial horizon parallel to the true or celestial horizon.

The necessity of using an instrument which will measure accurately the altitude of a celestial body above an artificial horizon presents the main problem in present-day aerial navigation, and is the reason why so many different types of aircraft octant have been developed. Principal types which thus far have been developed are the gyro, pendulus, and bubble octants. Each of these utilizes the gravitational pull of the earth on a gyro, pen-

dulum or bubble in order to produce artificially a true horizon.

Gyroscopic Octant — The gyroscopic-type octant produces a true horizontal by means of a rotating gyro. This instrument appears to have possibilities of attaining the "single observation" ideal, but thus far no such instrument has been developed for aerial navigation which is adaptable from the standpoint of size, weight, and structural ruggedness.

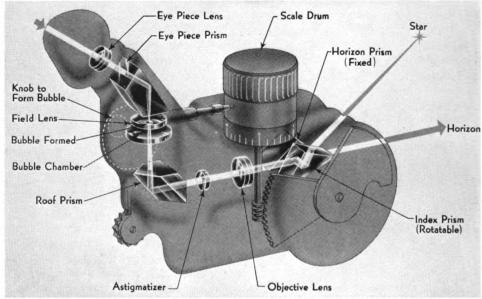
Pendulus Octant—The pendulus-type octant produces a horizontal by means of a pendulum. No octant of this type has yet been developed suitable for aerial navigation.

Bubble Octant (Figure 103)—The bubbletype octant produces a horizontal by means of the gravitational pull on an air bubble, which is either permanently formed, or formed prior to use, in an enclosed chamber of liquid.

Nearly all aircraft octants are of the bubble horizon type, principally because of their simple and rugged construction, and ease of handling.

There are many bubble-type octants in use, and the aerial navigator should become familiar with as many of them as possible. Nearly all





Courtesy Eclipse Pioneer Division Bendix Aviation Corporation.

FIG. 104-OPTICAL SYSTEM OF THE PIONEER OCTANT

types now available are reliable when used correctly and handled with care. In choosing an octant, the navigator should ascertain if the instrument is constructed strongly enough to give consistently accurate readings under normal handling conditions. He also should consider the reliability of its bubble horizon, size and weight of the instrument, and most importantly, the ease with which it can be used to determine altitudes. The best type octants incorporate a simple and accurate averaging device, and allow a clear view of the sky so that the navigator can be certain he has the correct star in his field of vision. Another important consideration in the octant is the ease with which any error in the instrument can be determined and eliminated. An added help in the instrument is a means of observing the sea horizon, to permit check of index error while in flight (the procedure for which is explained later in this chapter).

OPTICAL PRINCIPLE OF OCTANTS

The principle underlying the operation of all altitude-measuring devices is essentially the same. A law of physics states that when a ray of light is reflected from a plane surface, the "angle of incidence" is equal to the "angle of reflection."

In the octant, the angle between a celestial body and the horizon (either the sea horizon or a self-contained artificial horizon) is measured by bringing into coincidence, at the eye of the observer (by means of an optical system consisting of prisms, lenses, and mirrors), the rays of light received directly from one, and by reflection from the other. The angle between the celestial body and horizon (altitude) then is read on a graduated scale by means of a counter (indicator), actuated by the movement of the reflecting surfaces.

Figure 104 illustrates the principle of the Pioneer Octant. The index prism reflects a ray of light to the observer's eye. The horizon prism is fixed and through it the horizon may be viewed directly. Normally, however, an artificial horizon, indicated by the bubble, is used. In this type of bubble octant the image of a celestial body is made to coincide with the bubble. In some instruments, however, the celestial body is viewed directly and the image of the bubble is made to coincide with the body.

DESCRIPTION OF BUBBLE HORIZON

Forming the Bubble—The bubble is formed beneath a concave lens, the plane of which is horizontal when the instrument is held vertically upright. Then, by means of prisms, the



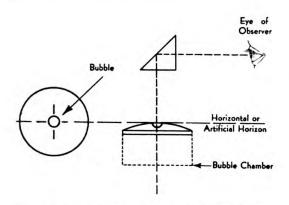


FIG. 105—BUBBLE'S INDICATION OF HORIZONTAL

eye views the bubble vertically through the bubble chamber (Figure 105).

The various type octants employ artificial bubble horizons which are either permanent, semi-permanent, or "make and break" type.

Permanent—The bubble is formed at the factory by adjusting the amount of liquid in the chamber. In this type of bubble horizon, temperature changes sometimes cause the bubble to disappear entirely. The bubble chamber, however, is usually a separate, interchangeable unit, and several chambers containing bubbles of various sizes are available in the carrying case.

Semi-Permanent — The bubble already is formed and may be enlarged or reduced as desired by a special adjusting mechanism.

"Make and Break" Type of Bubble—This is a very good type of bubble once the navigator has become accustomed to using it. The bubble must be formed before each observation, however, and as the size of the bubble tends to vary with temperature it is sometimes necessary to make adjustments during observation of a celestial body. The author used this type of bubble for over two years with excellent results, but a beginner should not attempt to form the bubble or change its size until he understands thoroughly the various characteristics of the bubble cell.

In this type of bubble arrangement there are two chambers completely filled with liquid: a bubble chamber with glass top and bottom which forms part of the optical system of the

telescope, and a diaphragm chamber with a small connecting passageway between the two. A control nut pulls the diaphragm out to form the bubble (see Figure 103).

Frequently there is formed in the diaphragm chamber a bubble too large to pass through the connecting passage into the bubble chamber, independent of the fact that there may or may not be another bubble visible in the bubble chamber. When this occurs, rotation of the control nut to form a bubble only increases the size of the bubble present in the diaphragm chamber, making it impossible for it to pass into the bubble chamber.

The presence of the bubble in the diaphragm chamber can be detected by the reaction of the diaphragm to rotation of the control nut. Thus when a bubble is visible in the bubble chamber, rotation of the control nut will alter the size of the visible bubble more slowly than when no bubble is present in the diaphragm chamber. This is due to the fact that change in pressure acts to alter the size of the bubble in the diaphragm chamber as well.

It is also noticeable that when there is no bubble visible in the bubble chamber, resistance felt when rotating the nut to form a bubble builds up gradually, as contrasted with a sudden building up of the resistance when another bubble is present.

Therefore, to properly form a bubble, the first step should always be (even though the bubble is visible) to hold the octant with the control nut downward at an angle of about 45° from the vertical and rotate the nut so as to put pressure on the liquid. If a bubble exists in the diaphragm chamber this will reduce its size, permitting it to pass into the bubble chamber. Sometimes when the bubble exists in the diaphragm chamber, it may be necessary to hold the instrument at this angle for a minute or two, shaking the octant from time to time until the bubble becomes small enough to pass into the bubble chamber.

Next, if no bubble has appeared, with the octant still in the inclined position rotate the control nut just far enough to overcome the resistance of the diaphragm, which should build up suddenly. When the bubble forms it will usually be accompanied by a sharp click, which can be felt on the control nut as the resisting force



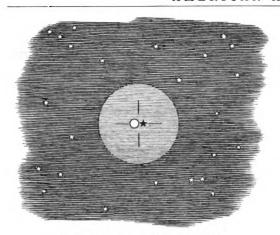


FIG. 106-OCTANT "FIELD"

is released. Then, immediately rotate the nut in the opposite direction in order to apply some pressure on the liquid. This will prevent the formation of too large a bubble and also reduce the size of any bubbles present in the diaphragm chamber so they can pass into the bubble chamber. Rotation of the control nut back and forth several times, each time releasing the suction on the liquid, will speed up the removal of all bubbles from the piston chamber. The control nut now may be set to produce a bubble of the proper size.

Collimation and Field—The bubble octant is so designed that when the image of the celestial body is caused to coincide, or match, with the center of the bubble, the angle as read on the octant will be the observed altitude of the celestial body. "Collimation" is the name given the condition of bubble and celestial body in coincidence.

The "field" of the octant is the small section of the celestial sphere which is visible in the octant's eyepiece (Figure 106). The larger the field of view, the easier it is for the navi-

gator to bring the image of the correct celestial body and the bubble into collimation.

Position of Bubble With Relation to Celestial Body—The optics of the bubble octant are such that collimation need not necessarily take place in the middle of the field, although the center is most desirable.

In Figure 107 the bubble and sun are shown in collimation in various parts of the field.

In No. 1 is shown the best position in the field.

In No. 2, error will be practically zero when collimation occurs anywhere on a vertical line passing through the center of the field.

In No. 3, large errors (about 5') will occur if collimation is effected anywhere in the field except on the vertical passing through the center. This appears contrary to reason, but actually, when collimation occurs along the vertical passing through the center of the field, the octant is aligned with the *vertical circle* passing through the celestial body. Collimation anywhere else indicates that the octant is being held in such a way as to increase the angle of altitude (Figure 108).

OCTANT ERRORS

Description—Aircraft octants are subject, basically, to two types of error: Instrument error and bubble acceleration error. Instrument error may be classed as a fixed calibration error, as it is caused by improper alignment of the measuring mechanism. It is fixed because it is an error which may be eliminated or, if not eliminated, accurately determined and recorded as Instrument Correction (I. C.) to be applied to each observation. Bubble acceleration error, however, is an observation error which is not fixed but varies with each observation taken.

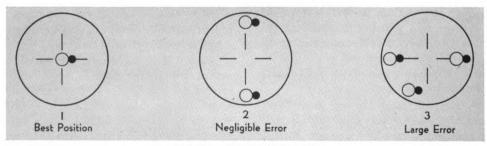


FIG. 107—COLLIMATION

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The bubble is freely suspended in liquid in order that the gravitational attraction of the earth will cause it to indicate the horizontal. But, unfortunately, the bubble also responds to the acceleration of the aircraft which frequently causes it to indicate a false horizon.

Instrument Error—Instrument error may be due to *index* or *bubble error*, or to a combination of both.

1. Index Error—Index error results when movements of the index prism or mirror are improperly recorded on the graduated scale. When the index prism, which actuates the counter, is in proper alignment (i.e., parallel to the horizon prism), the counter should read zero. If it does not, there is index error present.

To check for index error, a celestial body or distant object on the earth, such as the sea horizon, is viewed directly through the horizon prism. The reflected image of this object, as seen in the index prism, is brought into coincidence with the object itself. This will cause the two prisms to be placed in true alignment, and the counter should read zero. If it does not, the counter or index prism may be adjusted. However, in most octants this requires extremely accurate handling. Most navigators prefer to record the amount of error, and to apply this correction to each observation.

For example, if the counter read 5' off the scale (less than zero), all altitudes as read on the octant would underread 5'. Therefore a 5' correction should be *added* to all observations. On the other hand, if the counter read 5' on the scale (greater than zero), a 5' correction should be *subtracted* from all observations.

2. **Bubble Error**—Instrument bubble error results when the bubble chamber is out of line with the optics of the instrument, which causes the bubble to indicate a false horizontal when the acceleration of gravity alone is influencing it.

Bubble error may be determined by mounting the octant on a steady surface, selecting some distant point on the same level as the sextant (either a point determined by a surveyor's level or the sea horizon) and causing the reflected image of such a point to coincide with the bubble's center. Counter should then indicate zero. If it does not, the error may be elim-

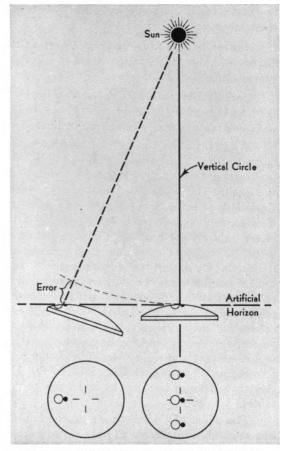


FIG. 108—DEVIATION FROM VERTICAL CAUSES ERROR

inated by adjusting the zero reference line of the scale, by realigning the bubble chamber, or by adjusting the mirrors.

Note: If the sea horizon is used, the dip correction must be taken into consideration.

Since the primary purpose of the octant is to measure the altitudes of celestial bodies from the bubble horizon, most navigators prefer to know the total instrument error. Total instrument error can best be determined by plotting a pre-computed curve showing the exact altitude of a celestial body for a period of several hours. The octant is then placed on a rigid support and the altitude of the body measured about every 15 minutes. The amount by which the octant reading differs from the true altitude as shown on the curve is, therefore, the amount of instrument error which, if not eliminated by adjusting the zero reference line of the scale,



will have to be applied to all future observations taken.

Bubble Acceleration Error or Observation Error — Bubble acceleration error is of two types: Coriolis and Transient.

Coriolis Error — A level bubble indicates the true vertical only when the bubble is at rest or is moving uniformly in a straight line.

When the bubble is moving uniformly in a curved path, the zenith indicated by the bubble is displaced toward the center of curvature of the path. The physicist Coriolis, for whom Coriolis type error is named, proved that even if a surface vessel (and hence an aircraft) steered a constant heading, the path followed would be slightly curved due to the rotation of the earth. Hence, altitudes measured with the bubble octant would be slightly in error, and the resultant lines of position displaced toward the center of curvature. In the Northern hemisphere the curvature is always toward the left side of the course, and in the Southern hemisphere toward the right side. The amount of this correction is compiled in tables in the Air Almanac and may be noted by inspection of the tables.

The effect of Coriolis error on the bubble octant as used in present day aerial navigation is, however, almost negligible. And since practical air navigation is not yet an exact science, the navigator need not be overly concerned with finding the exact Coriolis correction to apply to each line of position. With the development of faster long-range aircraft, and especially when flying in higher latitudes, it probably will prove necessary to apply Coriolis correction.

Transient Error—Transient error is error caused by accelerations or sluggish movement of the bubble due to slipping, skidding, varying airspeed and turning of the aircraft. This error is always present when observations are taken in the air, and is the principal reason why determining the true altitude of a celestial body is the most difficult and least accurate step in celestial navigation.

Transient errors in a single observation are frequently as great as 1° or 2° (60 to 120 miles). In order to reduce these errors to a minimum several precautions may be taken:

First, observation should be taken as nearly as possible from the center of gravity of the aircraft.

Second, the bubble should be adjusted to correct size, which is about twice the size of the sun as seen through the eyepiece. If the bubble is too large it will bounce around rapidly from one part of the field to another, making it very difficult to bring the body and bubble into coincidence in the center of the field. If the bubble is too small it will tend to lag, thus indicating a false horizon.

Third, averaging a number of readings taken over a period of time will give the mean of all possible horizontals the bubble indicated during the course of observation. Hence accuracy of the mean altitude increases in direct proportion to the time and number of sights taken; however, much depends upon the condition of the air and the skill of the navigator. With skill, 10 sights taken over a period of two minutes will give very good results.

HANDLING THE OCTANT

The aircraft octant is of rugged construction for aircraft use, but it should be remembered that it is a delicate instrument and should be handled with extreme care at all times. Intelligent use of most aircraft octants requires extensive practice (at least 50 observations) before a navigator begins to acquire a confident "feel" of the instrument. With practice, and by exercising all care humanly possible in taking an observation, he will consistently obtain good results.

The navigator should know all the parts of his octant, how they work and why, and before beginning an observation be sure they are all functioning properly. Prisms, mirrors, and eyepiece should be kept clean, and the eyepiece focused correctly. Also, the bubble should be adjusted to correct size. If a night sight is to be taken, the sun shades should be clear of the field of view, the batteries adjusted, and the light in perfect working order. The procedure in taking a sight is substantially as follows:

1. Scan the sky and select the stars to be "shot," choosing them so that the resulting position lines will intersect to provide a clear idea of the ship's position.





FIG. 109-AIRCRAFT OCTANT IN USE

Note: Selection of a star for purposes of a fix is important. Will it provide a speed line, course line, or check on other lines? Stars which are dim and hard to see, or stars which are obscured by occasional clouds should be shot first, as this will lessen the time between sights. If the sky is clear it is usually best to shoot the course line star first, then check line star, and the speed line star last.

- 2. Set the approximate altitude of the star on the octant and then make sure you have the right star in the field of view. Check by moving the field of view slightly to see relation of the star to other stars nearby, or check it by lining it up with the ribs in cockpit which hold the glass panes.
- 3. Select a position in the plane as near the center of gravity as possible from which the celestial bodies will be easily visible.
- 4. When ready to shoot, notify the captain, so that he may concentrate on holding the plane on as constant and steady a heading as possible.
- 5. Start shooting. It is best always to take three different star observations whenever possible. Establish a system and always shoot the same way thereafter in order to gain proficiency. Speed is desirable, but not essential. Never compromise accuracy for speed.

The author's system when using a non-averaging instrument, is as follows:

1. With the approximate altitude set, check the time on the chronometer, which is fastened to the octant.

- 2. Note the even minute, and when the second hand comes around to it, start shooting.
- 3. Record the observed altitude once every 15 seconds for two minutes and 15 seconds, each time causing the body to move out of coincidence a distance of several bubble diameters (up or down) and then realigning them. Thus ten sights are obtained, the mean altitude being found by adding up the minutes of altitude and then moving the decimal point over one digit. The mean time is obtained by adding one minute, seven seconds to the starting time.

Example:

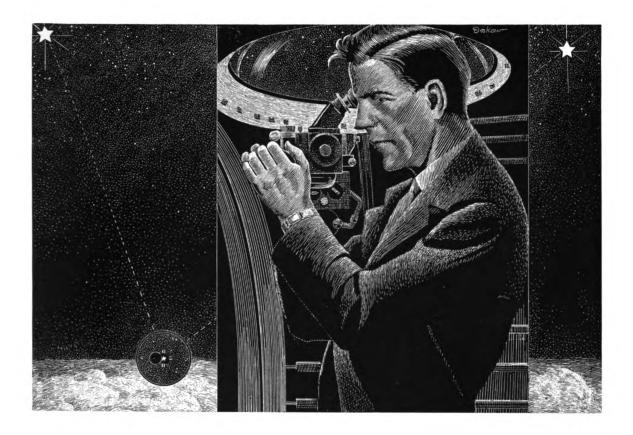
Arcturus	3	Α	ltitude
Time Start = 23	:46:00	4	17°30′
Add =	01:07		.25'
Mean Time = 23	:47:07		25'
			15'
			30'
			25'
			10'
			25'
			25'
-			35'
			24.5'
	Index	Error =	+5'
		$H_S = 47$	°29.5′
		Ref.	—1′
		$H_0 = 47$	°28.5′

When using an averaging octant the procedure is somewhat simpler. Note the time and start shooting on the even minute. While keeping the body and bubble in continuous coincidence, move the recording lever at regular intervals of two or three seconds for a period of two minutes. At the end of this time the average altitude is found by adjusting the index control so that the middle point of the marks left by the recorder is opposite the recorder point (usually a pencil lead) or other reference mark. The altitude is then read directly from the scale. The average time will be the starting time plus one minute.

In addition to the aforementioned methods of averaging sights there are devices which provide sight averages automatically. Several makes of octants feature various types of automatic averagers. One such averager is the socalled "cone" type, on which a constantly moving stylus records the altitude of the celestial body on a small sleeve of graph paper which slips over a cone-shaped holder, mounted on the altitude control knob. While the observer keeps the body and bubble in collimation over a two-minute period, the stylus records a curve on the graph paper. Examination of this curve provides the body's average altitude.

Another automatic averager records on a speedometer type dial the instantaneous average altitude of a celestial body for a period of two minutes. At the end of this time a shutter closes, indicating termination of the two-minute period. The final reading on the averager represents the average altitude of the sight for the period. This is usually a very accurate average as it actually represents an average of 120 sights (one per second for two minutes).





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POSITION LINES

As WAS stated in the preceding chapter, the development of the sextant marked an important milestone in the science of navigation. Though the instrument made it possible to measure the altitude of a celestial body more accurately, mariners still were able to determine only their approximate position, and then only after performing much tedious computation.

Like many a mariner who had sailed before him, Capt. Thomas H. Sumner, an American shipmaster, was acutely aware of the fact that the altitude of heavenly bodies could help men find their positions on the surface of the earth. In December, 1837, Capt. Sumner finally made a discovery which launched the science of navigation into its most important era. This discovery is known as the "line of position," though in honor of its discoverer, it is often referred to as the Sumner line. It has been termed by one authority "the most important principle in modern navigation."

Though Sumner's contribution was a vital one, it remained for a French naval officer, Marcq Saint-Hilaire, to combine the solution of the astronomical triangle with his DR position and so obtain a line of position faster and more directly. His contribution is generally considered the cornerstone of celestial navigation as it is practiced today.

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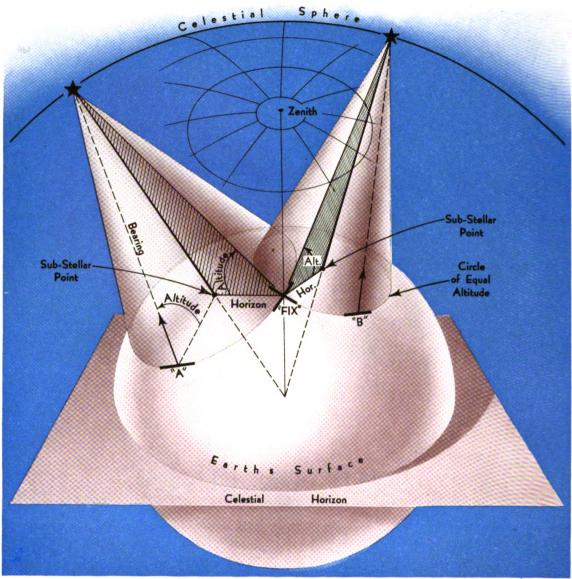


FIG. 110—CIRCLES OF EQUAL ALTITUDE

THEORY

Circle of Equal Altitude—A circle of equal altitude (Figure 110) is a small circle on the earth's surface, from any point of which (at the same instant of time) the altitude of a celestial body would be the same.

A Line of Position is a small segment of a circle of equal altitude. Being a portion of a circle, it is actually a curved line. However, since the circle is usually very large, for purposes of navigation this segment is considered

a straight line perpendicular to the azimuth, (bearing of the celestial body), as illustrated in Figure 110 at positions "A," "B," and at "Fix."

Position Line Fix—As will be noted in Figure 110, the true altitude of a celestial body determines the radius of the circle of equal altitude, or the observer's position with relation to the *geographical position*. It also will be noted that the observer could be located anywhere on this circle, such as at position "A" or

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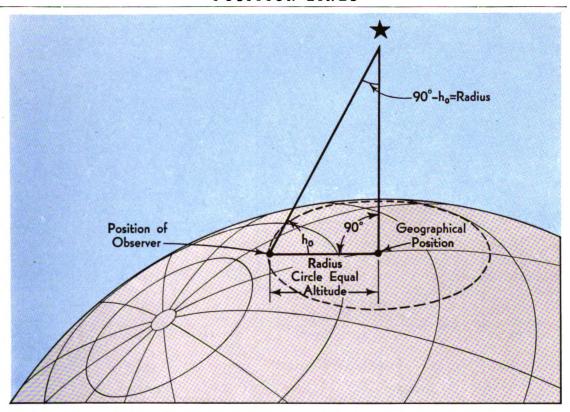


FIG. 111—RADIUS CIRCLE OF EQUAL ALTITUDE = 90° - ho

at the fix. If the altitudes of two or more celestial bodies are measured, since the observer's position is somewhere on each circle of equal altitude, he can only be located at one of the intersections of these circles. And though these circles will cross at two points, only one of these intersections may logically be the navigator's position, the other usually being so remote that it can be disregarded. The point of intersection at which the observer is located, when plotted on the chart, is called a "fix," or known position of the aircraft for the time of sight.

The Geographical Position (G.P.) is that point on the earth's surface directly beneath a celestial body and is, therefore, the center of the circle of equal altitude (Figure 110). It is sometimes called the sub-solar, sub-lunar or sub-stellar position to indicate sun, moon or star as the celestial body used.

Since declination is celestial latitude and

Greenwich hour angle is celestial longitude (both contained in the Air Almanac for any instant of time), the geographical position of a celestial body may be located exactly on the earth's surface, using declination as latitude and GHA as longitude.

Observer's Relation to Geographical Position — Since the geographical position is directly beneath the celestial body, a right triangle is formed between the observer's position, the geographical position, and the celestial body itself. And since the three angles of a triangle total 180°, the radius of a circle of equal altitude is equal to 90° minus the altitude of the celestial body (Figure 111).

On the earth's surface, one degree (60 minutes) of arc of a great circle is equal to 60 nautical miles. Therefore, the angle at a celestial body (converted into minutes) equals the radius of the circle of equal altitude in nautical miles, or the distance of the observer from the

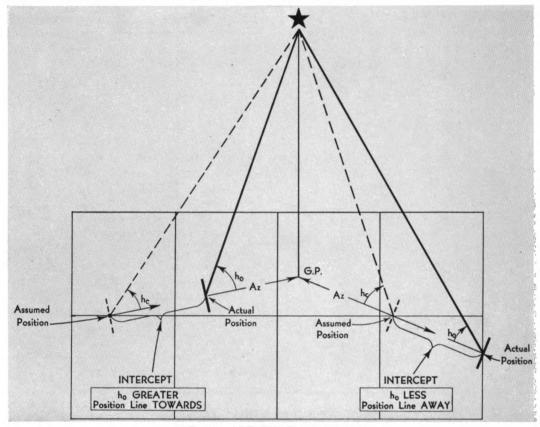


FIG. 112-ALTITUDE INTERCEPT

geographical position. The observer's position is determined then as somewhere on the small segment of the circle of equal altitude perpendicular to the azimuth line, such as at "A," "Fix," and "B" (Figure 110).

For a celestial body near the zenith, the circle of equal altitude would be small and could be plotted directly on the chart. However, for each minute the altitude decreases the observer's distance (radius of circle of equal altitude) increases one nautical mile. As a result, for the majority of sights the circle of equal altitude is too great for convenient plotting. Moreover, the azimuth cannot be measured closely enough for accurate navigation.

For these reasons the astronomical triangle is solved, and the observer's position relative to the celestial body's geographical position is computed by reference to tables of pre-computed altitude and azimuth. These tables give the navigator the true altitude and azimuth of any celestial body, at any instant, for any given position on the earth's surface. Tables of this type have been printed in many different forms, each striving to minimize the amount of work involved. However, results obtained by any one of several accepted methods will be similar.

General Procedure of computing a line of position is as follows:

- a. The navigator measures the altitude of a celestial body with his octant, and at the same instant notes the GCT. The observed altitude (H_S) , when corrected for sextant and altitude errors, becomes the *true altitude* (H_O) of the celestial body from the aircraft's actual position at the exact time of observation.
- b. The GCT, by reference to the Air Almanac, gives the *GHA* and *declination* of the body, thus locating its geographical position for that instant of time.
- c. Next, by reference to a table of pre-computed altitude and azimuth, the navigator determines the true altitude and azimuth, at the time of

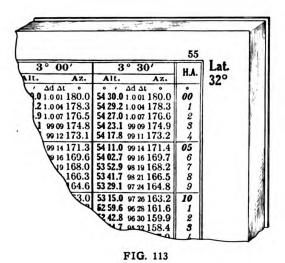


sight, for his assumed or dead reckoning position, which is estimated as near to the actual position of the aircraft as possible.

d. Comparing the two altitudes (Figure 112), if both the observed true altitude (H_O) and the computed altitude (H_C) are equal, the aircraft is somewhere on the line of position passing through the assumed or dead reckoning position. For each minute that true altitude (H_O) is greater than computed altitude (H_C), the line of position of the aircraft is one nautical mile toward the geographical position, measured from the assumed position. Conversely, for each minute that true altitude (H_O) is less than computed altitude (H_C), the line of position of the aircraft is one nautical mile away from the geographical position, measured from the assumed position.

This distance of the aircraft's actual line of position toward or away from the geographical position is called the altitude intercept ("a").

H.O. 214—"H.O. 214" is the designation for a group of books published by the U. S. Hydrographic Office (H.O.). These contain tabulated solutions of the astronomical triangle, so arranged as to yield to the navigator his computed altitude and azimuth by inspection. The books are rather large in size, and because each book covers only ten degrees of latitude, the navigator is required to take several volumes on an average flight. However, these tables are widely used because they require little computation, and thus reduce the chance of mathe-



matical error. This is very important to the long range aerial navigator, because, after flying several hours at high altitudes, he is apt to make mistakes due to fatigue.

Note: A newer method, known as H.O. 218, and developed by the British, also is very popular. The tables are similar to H.O. 214; however, they are a little easier to use because of the fact that the declinations of 22 stars have been included, eliminating the necessity of interpolation of declination for these stars. Otherwise, H.O. 218 is essentially the same as H.O. 214 for solutions of any celestial body whose declination is from 0° to 28°.

Use of Tables—The H.O. 214 tables may be used to find the true altitude and azimuth of a body for an aircraft's estimated dead reckoning position; however, in order to reduce the amount of interpolation required, they are generally used to find the altitude and azimuth for an assumed position. The assumed position is found by taking the nearest whole degree of dead reckoning latitude and the value of dead reckoning longitude which will yield a whole degree of local hour angle.

Arguments to Enter the Tables—The arguments necessary to enter the tables are:

- 1. Nearest whole degree of latitude.
- Nearest whole or half degree of declination.
- Nearest whole degree of local hour angle.

The values obtained are altitude, azimuth, and $\triangle d$ ("delta d"). The information is arranged in the following order: Altitude— $\triangle d$ — $\triangle t$ —azimuth (see Figure 113).

 Δ t is disregarded, as it represents the change in altitude for a change of one minute of arc of hour angle, whereas in using assumed position the hour angle employed is a whole degree. Δ t is used in obtaining altitude when working from a DR rather than an assumed position.

 \triangle d, however, represents the change in altitude for a change of one minute of arc of declination, and since the exact declination of a celestial body usually will differ from the tabulated declination, the \triangle d value is multiplied by the number of minutes of declination difference to obtain the correction to altitude. (This correction may be had by inspection from

the multiplication table arranged on the inside back cover of the volume or, with a little practice, it may be easily computed).

The application of this correction is determined by examination of the tabulated altitudes. If the values of altitude are increasing as the tabulated value used approaches the exact declination, the correction is added (indicated by a plus sign); if the values of altitude are decreasing, the correction should be subtracted (indicated by a minus sign). The altitude thus obtained is the computed altitude (H_C) for the assumed position.

Procedure to obtain line of position by H.O. 214 is as follows:

- a. Find the true altitude (H₀) by correcting the observed altitude (H_s) for octant errors (I.C.) and altitude errors.
- b. Find Greenwich hour angle and declination for the instant of Greenwich civil time of sight from the Air Almanac.
- c. Assume value of longitude nearest to dead reckoning position that will yield a whole degree of local hour angle. Note direction of LHA, East or West, as this determines whether the body is rising or setting, and is used to name the azimuth.

LHA has been described as the angular distance of the celestial body from the observer.

It is easily determined by simple arithmetic and the hour angle diagram, or by use of the following formula:

Note: The above formulas will result in values of LHA to 360°. However, in using H.O. 214 (or any other method of solving the astronomical triangle), LHA is measured only to 180° and named East or West with reference to the observer. Thus, if the value obtained by use of the formulas is less than 180°, it is named West; if, on the other hand, the value obtained is greater than 180°, it must be subtracted from 360° and then named East.

Note also that in West longitude LHA is always found by subtraction. Hence, the minutes of assumed longitude must equal the minutes of GHA in order for the LHA to come out in whole degrees.

In East longitude, the LHA is always found by addition, hence the minutes of assumed longitude when added to the minutes of GHA must total 60 minutes or one degree for the LHA to come out in whole degrees.

The following examples show how LHA is obtained.

Example No. 1 (Figure 114)

Longitude 117°23′ West
$$GHA = 93°19′$$
Assumed Long. = $117°19′$ West
$$LHA = 24° East$$

$$-or-$$

$$GHA = 93°19′$$

$$+360°$$

$$453°19′$$
Assumed Long. = $117°19′$ West

DR Position = Latitude 30°12' North

LHA =
$$336^{\circ}00'$$
 West
from 360°
LHA = 424° East

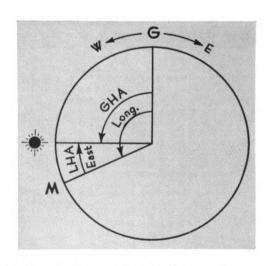


FIG. 114—LHA = GHA — WEST LONGITUDE

Example No. 2 (Figure 115)

DR Position = Latitude 33°20′ North
Longitude 160°15′ East
GHA = 269°28′
Assumed Long = 160°32′ Fast

Assumed Long. =
$$160^{\circ}32'$$
 East $430^{\circ}00'$ -360° LHA = 70° West

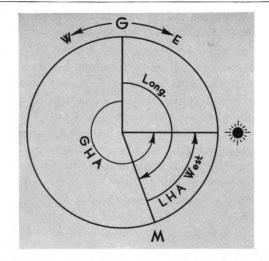


FIG. 115—LHA = GHA + EAST LONGITUDE

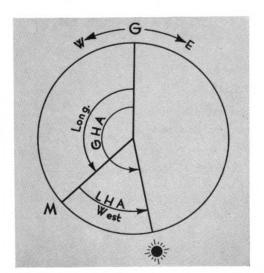


FIG. 116—LHA = GHA — WEST LONGITUDE

Example No. 4 (Figure 117)

DR Position = Latitude 31°45′ North Longitude 120°50′ East

> from 360° LHA = 80° East

Example No. 3 (Figure 116)

DR Position = Latitude 34°36′ North Longitude 132°00′ West

 $GHA = 190^{\circ}51'$

Assumed Long. $= 131^{\circ}51'$ West

 $LHA = \overline{59^{\circ}}$ West

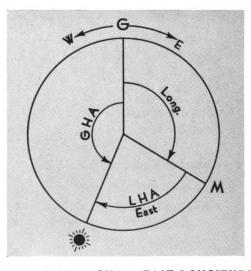


FIG. 117—LHA = GHA + EAST LONGITUDE

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- d. To continue procedure, assume latitude, nearest whole degree to DR position.
- e. Enter proper volume of H.O. 214 and find assumed latitude. Note whether declination is same name as latitude or contrary to latitude. Find column of nearest whole or half degree of declination as shown at top of page (according to whether declination is same or contrary name to latitude), obtain values for altitude, $\triangle d$, and azimuth opposite the proper LHA found at side of page.
- f. Name azimuth according to latitude and LHA.
- g. Multiply $\triangle d$ by number of minutes of declination difference and apply correction to

tabulated altitude in order to obtain computed altitude (H_C) for assumed position.

h. Compare $H_{\mathbf{C}}$ with $H_{\mathbf{O}}$ and mark altitude intercept *toward* or *away* depending on whether $H_{\mathbf{O}}$ is greater or less than $H_{\mathbf{C}}$.

Caution—The most important factor in computing lines of position is accuracy. Therefore:

- 1. Write all work legibly.
- 2. Establish some such form as used in the following problems, and use it consistently.
- 3. Underline assumed longitude, assumed latitude, azimuth, and intercept, as these values are used to plot the line of position.
- 4. Name latitude and declination to insure use of the correct table.

SAMPLE PROBLEMS

The following problems illustrate the use of H.O. 214. In each example the navigator measured the altitude of the celestial body with a bubble octant while flying at an altitude of 5000 ft.

Example No. 1

May 1, 1943, GCT $18^h10^m12^s$, H_S sun $63^\circ32'$, I.C. +1', DR latitude $30^\circ12'$ North, DR longitude $117^\circ23'$ West.

SUN
 Hs
 = 63°32′

 GCT
$$18^h10^m12^s$$
 I. C. = +1′
 Ref. = 0

 GHA for 18^h10^m = 93°14′
 Enter H.O. 214
 Ref. = 0

 + for 00^m12^s = 03′
 Enter H.O. 214
 Ho = 63°33′

 GHA = 93°17′
 Same name (Same name)
 Hc = 63°18.6′

 Assumed Long. = $117^\circ17'W$
 Lat. 30°N
 Lat. 30°N

 LHA 24°N
 Lat. 30°N
 Dec. 15°N

 Dec. 15°N
 H = 63°19.8′

 Ad corr. -1.2′
 Hc = 63°18.6′

 Az = N 118.9°E

POSITION LINES

Example No. 2

May 1, 1943, GCT 05h55m00s, H_S sun 24°30′, I.C. —3′, DR latitude 33°20′ North, DR longitude 160°15′ East.

SUN		$H_S = 24^{\circ}30'$
GCT 05h55m00s		I. C. $= -3'$
GHA for $05^{h}50^{m} = 268^{\circ}13'$		Ref. $=$ $-2'$
$+ \text{ for } 05^{\text{m}}00^{\text{s}} = 1^{\circ}15'$	Enter H.O. 214	$H_0 = \overline{24^{\circ}25'}$
$GHA = 269^{\circ}28'$	(Same name)	$H_{c} = 24^{\circ}37.2'$
Assumed Long. = $160^{\circ}32'E$	LHA 70°W	a = 12.2' away
430°	Lat. 33°N	$\triangle d = .50 (x 11' = 5.5')$
—360°	Dec. 15°N	$H = 24^{\circ}42.7'$
$LHA = 70^{\circ} W$		$\triangle d$ corr. —5.5'
Assumed Lat. $= 33^{\circ}$ N		$II_{\mathbf{c}} = \overline{24^{\circ}37.2'}$
$Dec = 14^{\circ}49'N$		$Az = N 87.7^{\circ}W$

Example No. 3

May 1, 1943, GCT $0^h40^m35^s$, H_s sun $33^\circ40'$, I.C. +5', DR latitude $34^\circ36'$ North, DR longitude $132^\circ00'$ West.

SUN GCT 0h40m35s		$H_s = 33^{\circ}40'$ I.C. = $+5'$	
GHA for $0^{h}40^{m} = 190^{\circ}42'$		Ref. = -1'	
$+ \text{ for } 00^{\text{m}}35^{\text{s}} = 09'$ $GHA = 190^{\circ}51'$	Enter H.O. 214 (Same name)	$H_{\mathbf{c}} = 33^{\circ}44'$ $H_{\mathbf{c}} = 33^{\circ}38.5'$	
Assumed Long. = $131^{\circ}51'W$	LHA 59°W	a = 5.5' toward	3
$LHA = 59^{\circ} W$ Assumed Lat. = 35° N	Lat. 35°N Dec. 15°N	$\triangle d = .54 \text{ (x } 15' = 8.1')$ 11 = 33°46.6')
$Dec. = 14^{\circ}45'N$		$\begin{array}{ccc} \triangle d \text{ corr.} & -8.1' \\ H_{\mathbf{C}} & = 33^{\circ}38.5' \\ Az & = \mathbf{N} \ 95.1^{\circ}\mathbf{W} \end{array}$	

Example No. 4

May 1, 1943, GCT $22^h32^m10^s$, H_S sun $16^\circ12'$, I.C. -6', DR latitude $31^\circ45'$ North, DR longitude $120^\circ50'$ East.

SUN		$H_{S} = 16^{\circ}12'$
GCT 22h32m10s		I. C. $= -6'$
GHA for $22^{h}32^{m} = 158^{\circ}14'$		Ref. $=$ $-3'$
$+ \text{ for } 02^{m}10^{s} = 33'$	Enter H.O. 214	$II_0 = \overline{16^{\circ}03'}$
$GHA = 158^{\circ}47'$	(Same name)	$H_c = 16^{\circ}14.4'$
Assumed Long. = 121°13′E	LHA 80°E	a = 11.4' away
280°00′	Lat. 32°N	$\triangle d = .50 (x 2' = 1.0')$
from 360°	Dec. 15°N	$H = 16^{\circ}13.4'$
$LHA = 80^{\circ} E$		$\triangle d$ corr. $+1.0'$
Assumed Lat. $= 32^{\circ}$ N		$H_{c} = \overline{16^{\circ}14.4'}$
$Dec. = 15^{\circ}02'N$		$Az = N 82.2^{\circ}E$

AMERICAN AIR NAVIGATOR

Example No. 5

May 1, 1943, GCT 21^h13^m10^s, H_S moon 35°02′, I.C. = 0, DR latitude 30°15′ South, DR longitude 120°30′ West.

MOON		Hs	$= 35^{\circ}02'$
GCT 21h13m10s		I. C.	= 0
		Par.	= +48'
GHA for $21^{h}10^{m} = 166^{\circ}20'$	Enter H.O. 214	Ref.	= -1'
$+ \text{ for } 3^{m}10^{s} = 46'$	(Contrary name)	Ho	$= 35^{\circ}49'$
$GHA = 167^{\circ}06'$	(contrary name)	IIc	$= 36^{\circ}00.9'$
Assumed Long. = $120^{\circ}06'W$	LHA 47°W	a	= 11.9' away
$LHA = 47^{\circ} W$	Lat. 30°S Dec. 0°N	△d	= .62 (x 18' = 11.2')
Assumed Lat. $= 30^{\circ}$ S	Dec. O IV	H	$= 36^{\circ}12.1'$
$Dec. = 0^{\circ}18'N$		∆d cor	rr. —11.2'
		IIc	$= 36^{\circ}00.9'$
		Az	= S 115.0°W

Example No. 6

May 1, 1943, GCT 11^h12^m20^s, H_S star Rigel 14°01′, I. C. —2′, DR latitude 32°20′, South, DR longitude 130°20′ East.

STAR RIGEL GCT 11 ^h 12 ^m 20 ^s GHA for 11 ^h 10 ^m = 26°01'		II _s = $14^{\circ}01'$ I. C. = $-2'$ Ref. = $-3'$
$+ \text{ for } 2^{m}20^{s} = 35'$ SHA Rigel = $282^{\circ}03'$	Enter H.O. 214 (Same name)	$ H_{\mathbf{c}} = \overline{13^{\circ}56'} $ $ H_{\mathbf{c}} = \underline{13^{\circ}40.2'} $
Assumed GHA = $308^{\circ}39'$ Long. = $130^{\circ}21'E$ $439^{\circ}00'$	LHA 79°W Lat. 32°S Dec. 8°S	$ \begin{array}{ccc} $
$LHA = \frac{-360^{\circ}00'}{79^{\circ} \text{ W}}$ Assumed Lat. = 32° S $Dec. = 8^{\circ}16'S$		$\triangle d \text{ corr.} \qquad \frac{+8.3'}{13^{\circ}40.2'}$ Az = S 88.9°W

Example No. 7

May 1, 1943, GCT $17^h53^m10^s$, H_{S} Mars $33^\circ50'$, I. C. +4', DR latitude $34^\circ50'$ South, DR longitude $160^\circ30'$ East.

MARS		$H_{\mathbf{S}}$	$= 33^{\circ}50'$
GCT 17h53m10s		I. C.	= +4'
GHA for $17^{h}50^{m} = 143^{\circ}25'$		Ref.	= $-1'$
$+ \text{ for } 3^{m}10^{s} = 48'$	Enter H.O. 214	H_{0}	$= 33^{\circ}53'$
$GHA = 144^{\circ}13'$	(Same name)	Hc	$= 33^{\circ}35.8'$
Assumed Long. = 160°47′E	LHA 55°E	a	= 17.2' toward
305°00′	Lat. 35°S	$\triangle \mathbf{d}$	=.59 (x 3' = 1.8')
from 360°	Dec. 9°S	H	$= 33^{\circ}37.6'$
$LHA = 55^{\circ} E$		∆d co	orr. —1.8'
Assumed Lat. = 35° S		Hc	$= 33^{\circ}35.8'$
$Dec. = 8^{\circ}57'S$		Az	= S 103.7°E

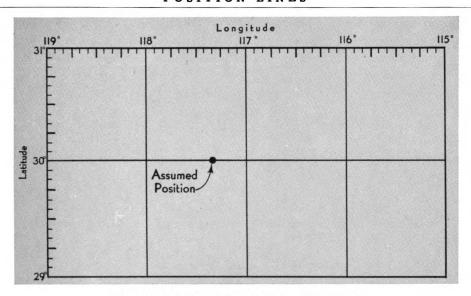


FIG. 118—PLOTTING ASSUMED POSITION

PLOTTING LINES OF POSITION

Step One — Plotting Assumed Position — Since the solution of the astronomical triangle by altitude-azimuth tables locates the small segment of the circle of equal altitude (line of position) with relation to an assumed position, the first step in plotting the line of position (L.O.P.) is to locate on the chart the assumed

position used in the solution. Thus, if the assumed latitude = 30° North and the assumed longitude = 117°20′ West, this position would be plotted as shown in Figure 118.

Step Two—*Plotting Az*—The second step is to plot the azimuth, or bearing of the body, through the assumed position as shown in Figure 119.

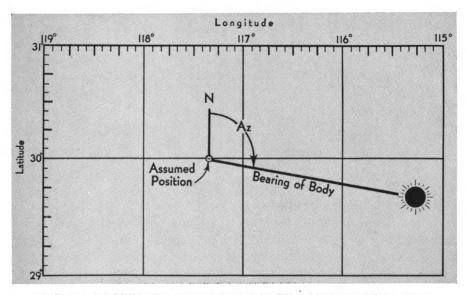


FIG. 119—PLOTTING AZIMUTH THROUGH ASSUMED POSITION

☆ 121 ☆



Note: Bearings usually are measured from North (0°) through 360°. Such bearings are called true bearings $(Z_{\mathbf{n}})$. However, precomputed bearings of celestial bodies (as found in H.O. 214), are generally tabulated in terms

With this in mind, the navigator should pay particular attention to the azimuth direction, because plotting azimuth incorrectly is the most frequent error made by navigators in plotting a line of position. One of the most

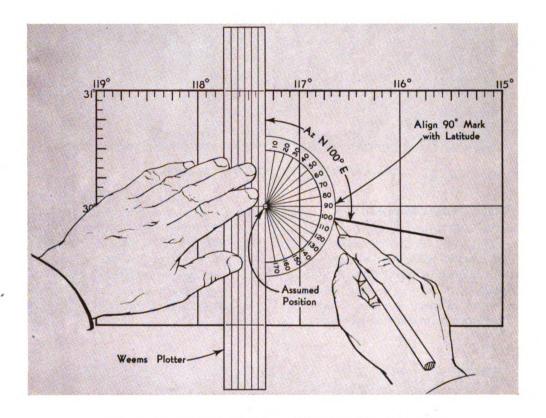


FIG. 120—PLOTTING AZIMUTH WITH WEEMS PLOTTER

of azimuth, thus greatly simplifying the tables and eliminating much unnecessary compilation work. When azimuth is so employed, the bearing of a body is measured from the *elevated* pole towards the East or West through 180°. If the observer is in North latitude, the elevated pole is the North pole; if he is in South latitude, the elevated pole is the South pole. Azimuth is measured to the East if the body is rising, or to the West if it is setting.

practical methods which the author has yet found is to use a Weems plotter, which has an azimuth scale graduated to read from 0° to 180° .

As illustrated in Figure 120, the center of the Weems plotter is placed over the assumed position with the 0° mark pointed toward the elevated pole. Azimuth is then easily measured East or West according to the LHA of the body.



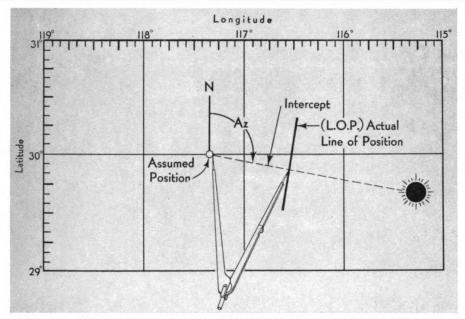


FIG. 121-MEASURING ALTITUDE INTERCEPT AND PLOTTING L.O.P.

Step Three—Plotting Actual Line of Position (Figure 121)—The third step is to plot the actual line of position. With the dividers set

at a distance equal to the altitude intercept, locate a point on the azimuth line a distance from the assumed position equal to altitude

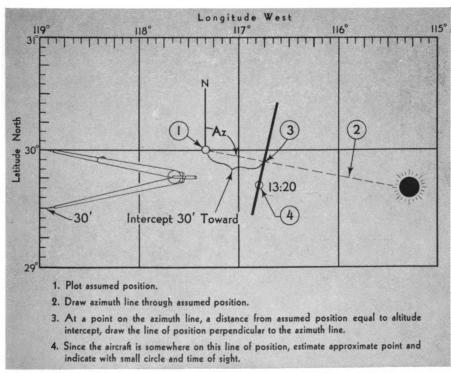


FIG. 122

☆ 123 ☆

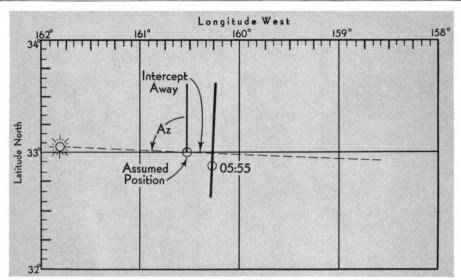


FIG. 123

intercept, and through this point erect the actual line of position perpendicular to the azimuth line.

Sample Problems—The following examples show how lines of position are plotted, using H. O. 214.

Example No. 1 Sun (Figure 122)
Time of sight........GCT 13h20m
Assumed position...Latitude 30° North
Longitude 117°20' West
AzimuthN 100°E
Altitude Intercept....30 miles toward

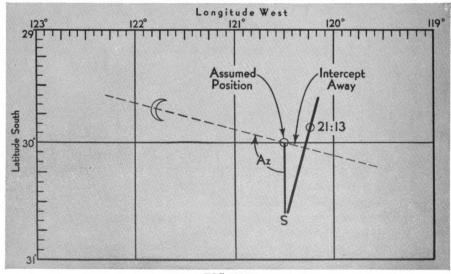


FIG. 124

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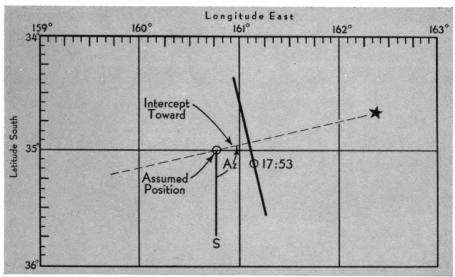


FIG. 125

Example No. 4 Planet (Figure 125)

Time of sight.......GCT 17h53m10s
Assumed position....Latitude 35° South
Longitude 160°47′ East
AzimuthS 103.7°E
Altitude Intercept....17.1 miles toward

SINGLE LINE OF POSITION

The single line of position, although it definitely locates the aircraft's position in one direction only, can be very useful to the navigator who understands its value and correctly interprets the information which it gives him.

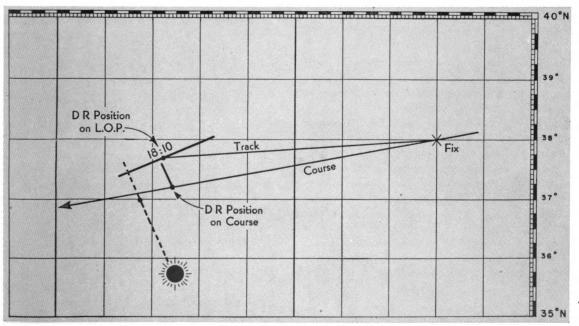


FIG. 126-SINGLE L.O.P. PARALLEL TO COURSE PROVES TRACK

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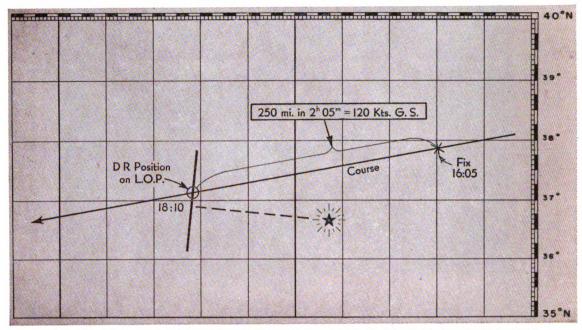


FIG. 127—SINGLE L.O.P. PERPENDICULAR TO COURSE PROVES GROUND SPEED

Determining Track—If the single line of position is parallel to the aircraft's course, it will indicate the amount of drift and the track being made good. (Figure 126)

Determining Ground Speed—If the single line of position is perpendicular to the aircraft's course, it will indicate the ground speed being made good. (Figure 127)

Advancing Lines of Position-The navigator, having plotted a line of position for the instant of observation, quite often finds it advisable to advance or retard the line to a different time. This is possible because, since the aircraft is known to be somewhere on the line of position at the instant of observation, it may be assumed that all points on the line of position are moving as the aircraft moves and at a common rate along the same course, much as would a row of aircraft whose wings were joined together. Therefore, if the line of position is advanced or retarded along the course to a dead reckoning position, all the points of the original line of position move in the same direction, and through the same distance. (Figure 128)

Hence to advance (or retard) a line of position to a different time, move the point where it intersects the course line along the course a distance equal to the minutes of ground speed flown, and through this advanced (or retarded) point draw a new line of position parallel to the original line. (Figure 129)

The accuracy of the advanced line of position depends on how accurately the ground speed and track are known. For lines of position advanced or retarded from three to twenty minutes, errors involved are negligible, and the new line may be considered as accurate as the original line of position. However, if the line is advanced more than one hour it may contain appreciable error due to the fact that the dead reckoning ground speed is based upon an estimated wind. Hence, such lines should be used with appreciation of all possible errors of the dead reckoning course and ground speed.

POSITION FIXES

Fix by Two Sun Lines—Often the aerial navigator must depend solely on single position lines (such as sun lines) in order to fix his position. In this procedure, the navigator shoots the sun and obtains single position lines at elapsed intervals which should not be more than one hour apart. During this elapsed interval the sun's azimuth is changing continuously,



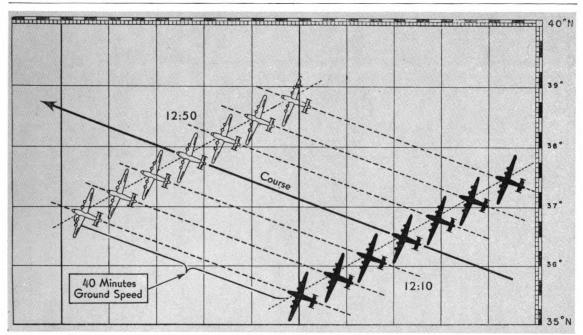


FIG. 128-ALL POINTS ON L.O.P. MOVE PARALLEL TO COURSE

which likewise causes the direction of the position line to change. Therefore, by advancing the previous position line to the latest position line, a cross of lines will be obtained which will thus fix the aircraft's position. (Figure 130)

For such a fix to be of any value, the navigator must carefully analyze all possible errors in the track and ground speed used to advance the line of position, because the azimuth change usually is very slight. This type fix is most reliable when the azimuth change is rapid, such

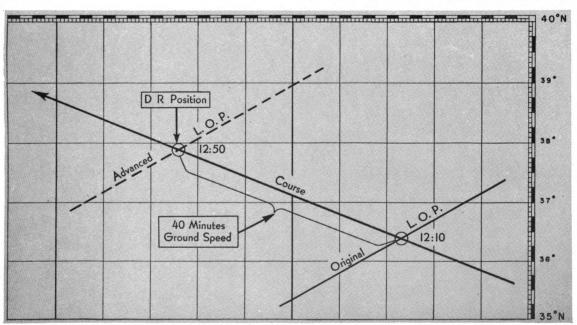


FIG. 129-ADVANCED L.O.P. DRAWN PARALLEL TO ORIGINAL L.O.P.

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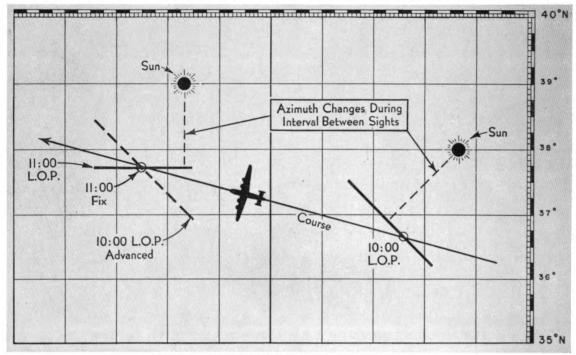


FIG. 130-RUNNING FIX BY TWO SUN LINES

as when the body is near the observer's celestial meridian. When this occurs, the body may be observed at shorter intervals and the resultant angle of "cut" of position lines will be greater. Fix by Any Two Position Lines — Any bearing, such as a visual bearing of a mountain peak or a radio bearing, also provides a position line since it definitely locates the aircraft's po-

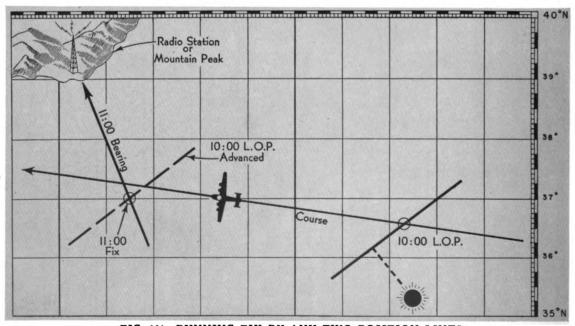
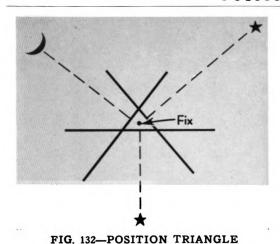


FIG. 131-RUNNING FIX BY ANY TWO POSITION LINES

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sition in one direction (i.e. somewhere on the bearing line). Therefore, bearings may be advanced to celestial position lines, or celestial position lines may be advanced to bearings in order to obtain a fix. (Figure 131)

Three Star Fixes—The three star fix is by far the most desirable and most accurate method of celestial navigation.

To obtain a fix, three celestial bodies whose

azimuths differ (by at least 60° if possible) are observed, and the resultant position lines, when plotted on the chart, should intersect at a point or small triangle which definitely locates the aircraft's position. (Figure 132).

Since it is physically impossible to take three sights simultaneously, the observations are taken with as little time interval between as possible. The lines of position are then plotted, and advanced or retarded to a common time. (Figure 133)

In actual practice, as illustrated in Figure 134, the last line of position (11:00) is usually plotted on the chart first. Then, since only the common time fix (11:00) is desired, the earlier lines of position (10:40 and 10:50) are only lightly indicated at their origin, to facilitate their advance to the common time (11:00).

Track and Ground Speed Between Fixes—A fix, whether it is a celestial fix or a visual fix, determines the location of the aircraft at the time of the fix. Therefore, when fixes are taken at intervals, the track, ground speed, drift, and wind between the fixes may be easily and accurately determined.

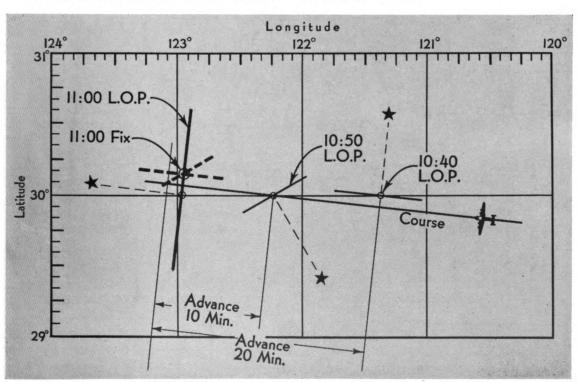


FIG. 133-THREE STAR RUNNING FIX

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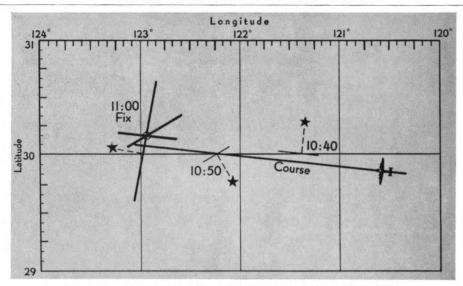


FIG. 134—PRACTICAL PLOTTING OF THREE STAR FIX

The track is determined by a straight line connecting two successive fixes. The ground speed is found by dividing the distance between fixes by the time interval flown.

The wind is then the resultant vector component between the track and ground speed

and the true heading and true air speed. (Figure 135)

In actual practice, the track and distance flown between fixes are measured on the chart.

The ground speed, drift, and wind are usually solved on the computer.

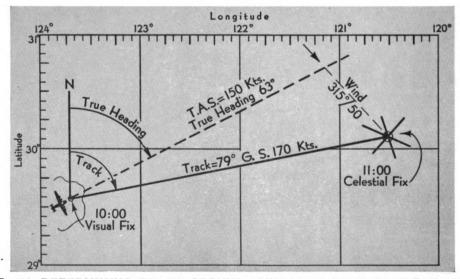


FIG. 135—DETERMINING TRACK, GROUND SPEED AND WIND BETWEEN FIXES



PROBLEM WORK

No. 26-Plot Problem Work No. 25.

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PROBLEM WORK NO. 23 ASSUMED POSITION—LHA—DECLINATION

(Find assumed position, LHA and declination.)

		DR PC	SITION		CELESTIAL	ASSUME	POSITION		
No.	DATE	Lat.	Long.	GCT	BODY	Lat.	Long.	LHA	Dec
1	5- 1-43	34°10′N	110°32′E	22:22:00	ARCTURUS				
2	5- 5-43	23°15′S	172°14′W	22:14:00	SUN				
3	5-10-43	14°21′N	117°42′W	20:19:00	JUPITER				
4 .	5-15-43	22°18′N	178°31′E	02:19:32	SUN				
5	5-20-43	11°01′S	124°19′E	19:37:07	RIGIL KENT.				
6	5-30-43	14°36′N	117°51′E	12:38:00	PROCYON				
7	5- 1-43	32°51′N	168°41′W	00:31:14	SUN				
8	5- 5-43	18°13′S	104°32′E	10:52:00	VENUS				
9	5-10-43	15°14′S	168°14′E	12:15:00	NUNKI				
10	5-15-43	32°08′S	114°39′W	23:19:00	MOON			Į.	
11	5-20-43	18°54′N	127°27′W	03:16:00	SPICA				
12	5-30-43	7°15′S	92°00′W	00:10:00	ALDEBARAN				
13	5- 1-43	19°43′N	116°37′W	05:36:00	BETELGEUX				
14	5- 5-43	4°04′N	152°19′W	21:50:00	RIGEL				
15	5-10-43	16°31′S	86°49′E	05:16:00	CANOPUS				
16	5-15-43	31°19′S	178°19′W	02:16:20	SUN				
17	5-20-43	20°14′N	117°22′W	02:50:00	BELLATRIX				
18	5-30-43	17°51′S	172°15′E	23:18:45	SUN				
19	5- 1-43	14°19′S	179°12′W	03:50:00	RIGIL KENT				
20	5-10-43	23°31′N	162°14′W	06:53:19	PROCYON				

PROBLEM WORK NO. 24 ALTITUDE AND AZIMUTH (H. O. 214)

[Find altitude (Hc) and azimuth. Use volume IV, H. O. 214.]

No.	LATITUDE	DECLINATION	LHA	Нc	AZIMUTH
1	33°N	13°48′N	65°W		
2	36° N	23°06′N	48° E		
3	39° N	11°20′S	61°E		
4	38° N	22°40′N	35°W		
5	34° N	16°24′N	41°W		
6	38°S	57°32′S	29°W		
7	31°N	8°43′N	51°E		
8	35°N	26°18′S	40°W		
9	31°N	19°29′N	30° E		
10	38° N	7°24′N	38°W		
11	31°N	· 45°57′N	26°E		
12	32°N	45°05′N	42°W		
13	31°S	29°56′S	19°E		-
14	36°S	28°10′N	29°W		
15	35°N	5°22′N	43°E		
16	32°S	12°15′N	39° E		
17	33°S	8°16′S	40°W		
18	31°N	16°38′S	27°E		
19	39° N	10°52′S	46°W		
20	32° N	38°44′N	28° E		

PROBLEM WORK NO. 25 ASSUMED POSITION—INTERCEPT—AZIMUTH

(Find assumed position, altitude intercept and azimuth by H. O. 214.)

	CELESTIAL				DR PO	SITION	ASSUMED		3.5
No.	BODY	DATE	GCT	Ho	Lat.	Long.	POSITION	Int.	Az.
1	NUNKI	5-1-43	12:18:30	19°40′	35°02′S	156°03′E			
2	CANOPUS	5-5-43	05:44:13	71°49′	35°10′S	153°29′E			
3	MOON	5-10-43	03:01:35	18°31′	35°25′S	154°15′E			
4	SUN	5-15-43	02:58:00	29°58′	29°50′N	160°00′W			
5	JUPITER	5-20-43	23:58:36	58°02′	30°01'N	158°15′W			
6	ANTARES	5-20-43	10:19:10	31°00′	30°25′N	161°12′W			
7	VENUS	5-10-43	06:11:18	65°42′	39°20′N	152°28′E			
8	CAPELLA	5-1-43	04:34:35	83°04′	38°45′N	151°25′E			
9	SUŅ	5-15-43	02:15:58	69°12′	39°12′N	151°12′E			
10	SUN	5-5-43	15:38:38	17°17′	32°40′N	135°45′W			
11	MOON	5-20-43	11:58:31	30°09′	33°05′N	136°00′W			
12	MARS	5-15-43	20:32:29	27°30′	33°15′N	136°12′W			
13	JUPITER	5-1-43	05:05:05	20°43′	36°25′S	145°20′W			
14	MOON	5-10-43	02:24:00	34°58′	36°05′S	146°12′W			
15	SUN	5-5-43	19:35:39	30°00′	35°45′S	146°50′W			
16	MOON	5-20-43	11:06:00	45°30′	31°40′S	155°20′E			
17	PROCYON	5-15-43	08:19:39	36°38′	31°58′S	157°01′E			
18	SUN	5-1-43	01:08:00	42°39′	32°12′S	156°18′E			
19	MOON	5-10-43	03:32:56	25°50′	37°45′S	133°20′W			
20	JUPITER	5-25-43	00:56:38	29°59′	38°01′S	135°02′W			

PROBLEM WORK NO. 27 ADVANCING SINGLE LINES OF POSITION

Plot single line of position and advance required number of minutes or to GCT indicated.)

			CELESTIAL		DR PC	POSITION			Ground		ADVANCE	E LO.P
No.	DATE	GCT	BODY	Но	Lat.	Long.	Az	Intercept	Speed	Track	Time	N.M.
_	5- 1-43	00:00:90	SUN	49°35′	30°44'N	49°09′E			180	270°	5 Min.	
2	5- 5-43	13:10:20	SUN	32°17′	35°14'S	11°49′E			66	135°	20 Min.	
3	5-10-43	02:32:06	SUN	23°15′	37°52'S	178°40'W			177	32°	45 Min.	
4	5-15-43	18:45:26	SUN	67°30′	33°09'N	82°03'W			110	°09	45 Min.	
r.	5-20-43	15:14:05	SUN	34°50′	35°17'S	56°32′W			198	253°	15:30:00	
9	5-30-43	09:21-17	SUN	30°05′	34°57'S	17°18′E			164	350°	00:30:00	
7	5- 1-43	08:27:13	SUN	45°01′	39°05'N	8°27′E			120	°621	08:30:00	
~	5- 1-43	03:30:00	MOON	26°03′	33°15'S	29°52'E			107	°66	10 Min.	
6	5- 5-43	21:14:30	MOON	63°01′	32°49'N	98°10'W			154	177°	21:30:00	
10	5-10-43	02:57:05	MOON	23°32'	37°14'S	117°05′W			114	240°	03:00:00	
11	5-20-43	23:45:01	MOON	28°18′	35°51'N	10°30'W			202	38°	24:00:00	
12	5-30-43	03:05:50	MARS	33°01′	34°51'S	117°10'E			107	260°	03:10:00	
13	5- 1-43	02:00:47	VENUS	42°16′	35°21'N	117°57'W			68	45°	02:10:00	
14	5- 5-43	10:10:00	JUPITER	41°03′	33°12'N	150°40′E			180	355°	10:30:00	
15	5-10-43	09:31:10	MARS	27°01′	37°05'N	70°15′W			160	180°	09:40:00	
16	5-20-43	15:36:40	POLARIS	36°05′	35°50'N	152°21'W			119	180°	15:40:00	
17	5-30-43	18:23:07	ARCTURUS	54°01′	36°05'N	14°07′E			148	°06	18:30:00	
18	5- 1-43	08:42:50	VEGA	54°09′	38°44'N	117°05′W			89	270°	08:50:00	
19	5- 5-43	21:00:58	ALTAIR	26°30′	32°57'S	169°40'E			107	901	21:06:00	
20	5 10 43	00 /				-			-			

PROBLEM WORK NO. 28 THREE STAR FIXES

GROUND SPEED 180 knots—TRACK 242°

(Find line of position for each star. Advance lines of position to obtain "FIX" for time of third star in each group.)

No.	DATE	GCT	CELESTIAL BODY	Ho	DR POSITION	FIX
1	5- 1-43	01:04:20	VEGA	46°39′	5.6	
		01:10:00	DENEB	26°28′	LAT. 32°10'N LONG. 8°41'W	
		01:15:12	ALPHECCA	83°04′	ZONG. UNIW	
2	5- 5-43	04:13:41	RIGEL	62°31′		
		04:19:30	CANOPUS	59°10′	LAT. 32°14'S LONG. 137°14'E	
		04:26:30	ALDEBARAN	41°25′		
3	5-10-43	15:40:00	CAPELLA	56°39′		
		15:50:00	POLARIS	35°15′	LAT. 35°09'N LONG. 17°14'E	
		16:00:00	ALDEBARAN	36°39′		
4	5-15-43	21:50:00	RUCHBAH	61°34′		
		21:52:00	MARS	44°47′	LAT. 31°17′N LONG. 180°00′	
		21:55:00	ENIF	33°28′		
5	5-20-43	09:51:40	ARCTURUS	69°31′		
		09:58:35	DUBHE	54°17′	LAT. 39°21′N LONG. 175°43′W	
		10:07:37	REGULUS	29°02′	201.01.110.1011	
6	5- 5-43	17:01:59	DENEB	50°24′		
		17:03:06	FOMALHAUT	25°58′	LAT. 32°19'N LONG. 120°05'W	
		17:05:02	ALTAIR	27°47′		
7	5-20-43	14:31:48	DUBHE	47°08′		
		14:37:00	SPICA	38°37′	LAT. 35°51'N LONG. 125°11'E	
		14:40:55	DENEBOLA	43°25.5′		
8	5-10-43	04:11:41	CAPELLA	33°30′	3-01-50-03-1	
		04:16:50	POLLUX	58°14′	LAT. 31°17′N LONG. 140°02′W	
		04:19:50	PROCYON	45°27′	201.0. 110 02 11	



PROBLEM WORK NO. 29

TRACK AND GROUND SPEED BETWEEN FIXES

C.A.S. = 157 knots, ALTITUDE = 7000', TEMPERATURE = +10°C, T.A.S. =?

(Plot star sights on a small scale chart, I.C. = 0°. Advance or retard lines of position to obtain fix for time of third sight listed in each group.)

FIND TRACK AND GROUND SPEED MADE GOOD FROM PREVIOUS FIX.

CALCULATE DRIFT AND WIND BETWEEN FIXES.

ALTER TRUE COURSE AS INDICATED.

ESTIMATE TRUE HEADING USING PREVIOUS WIND, GIVEN OR CALCULATED.

		TYPE	PO	SITION		GROUND		3012002	TRUE
No.	GCT	OF FIX	Lat.	Long.	TRACK	SPEED	DRIFT	WIND	HEADIN
1	TRUE	COURSE	242°						
	07:05	Visual	37°50′N	122°29′W	242°		0°	0°	242°
2	TRUE	COURSE	242°	3	Star sight	s taken:			
				KOCHAB	GCT	08:32:00	H _s 50°34′		
				ALPHECCA	GCT	08:36:00	H _s 76°31′		
				VEGA	GCT	08:40:00	H _s 44°30′		
	08:40	Celestial							
3 '	TRUE	COURSE	247°		Star sight	ts taken:			
				ANTARES	GCT	09.27:00	Hs 28°15′		
				RASALAGUE	GCT	09:34:00	H _s 54°37′		
				ARCTURUS	GCT	09:30:00	H _s 69°00′		
	09:30	Celestial							
4	TRUE	COURSE	249°		Star sight	ts taken:			
				POLARIS	GCT	10:13:00	Hs 32°46′		
				ALTAIR	GCT	10:16:00	Hs 31°24'		
				DENEB	GCT	10:20:00	H _s 36°14′		
	10:20	Celestial							
5	TRUE	COURSE	232°		Star sight	ts taken:			
				SABIK	GCT	11:32:00	Hs 42°44′		
				ALIOTH	GCT	11:38:00	Hs 40°27′		
				SPICA	GCT	11:35:00	H _s 22°35′		
	11:35	Celestial							

CELESTIAL REVIEW EXAMINATION NO. 2

- 1. Draw Celestial Sphere. Show all parts you know.
- 2. Define:
 - (a) Vertical Circle
 - (b) Hour Circle
 - (c) Azimuth
 - (d) Equinoctial
 - (e) Declination

- (f) Altitude
- (g) Local Hour Angle
- (h) Ecliptic
- (i) Sidereal Hour Angle
- (j) Geographical Position
- 3. Show the following by hour angle diagrams:
 - (a) GHA Sun 120° Long. 40° East
 - LHA Sun

(b) GHA Aries 60° SHA Star 180° Long. 80° East GHA Star LHA Star

- 4. Solve:
 - (a) On January 2nd at Long. 120° West, the LCT is 18:31. What is the time and date in Greenwich?
 - (b) On July 15, when GCT is 22:16, what is the Local Civil Time and date at Long. 118° East?
- 5. Honolulu
- $ZD = + 9\frac{1}{2}$
- Canton
- $ZD = +10\frac{1}{2}$
- Fiji
- ZD = -12
- (a) An aircraft leaves Honolulu at ZT 10:00 A. M., August 3rd, arriving at Canton 9 hours and 30 minutes later. What is local time and date of arrival?
- (b) An aircraft leaves Canton at ZT 12:00 noon, January 5th, arriving at Fiji 6 hours later. What is the local zone time and date of arrival?
- 6. May 1, 1943, GCT 11h20m22s: Find GHA and declination of Sun, Moon and Sirius.
- 7. The following altitudes were obtained with a bubble sextant of I.C.—6', at height of 8000 ft., May 10, 1943:

Sun 30°20'

Venus 60°15'

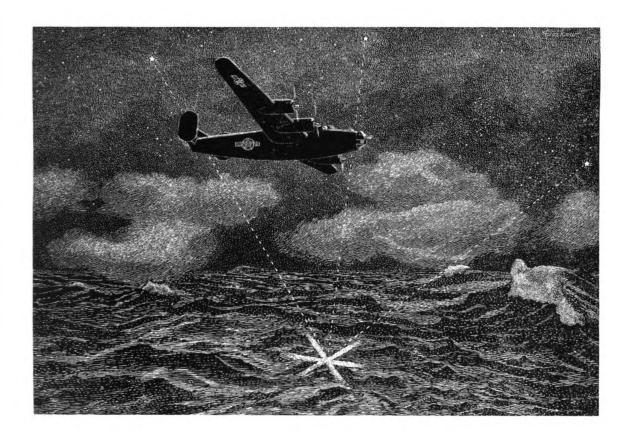
Altair 20°12'

Moon 28°35'

What are the true altitudes?

- 8. On May 20, 1943, GCT 11h20m20s in longitude 145°18' West, the altitude of Polaris (using a bubble sextant) was found to be 32°15'. If the height of the plane was 5000 ft. and the I.C. 0°, what was the latitude of the observer?
- 9. At DR latitude 30°15' North, longitude 70°25' West, on May 30, 1943, at a height of 7000 ft., I.C. 0°, and GCT 03h16m07s, the observed altitude of Antares was 30°07'. What are the altitude intercept and azimuth?
- 10. (a) Describe the process of forming the bubble in a Pioneer octant.
 - (b) In what relation are the bubble and the body for accurate sights? For inaccurate sights?





\$ 10 \$

STARS AND THE WEATHER

☆ 139 ☆

A WORKING knowledge of the stars is easy to acquire, yet few people make an effort to become familiar with them. The fact that the stars, to the average observer, appear so countless and complex in their arrangement probably accounts for the general ignorance about stars and constellations. As a result, most people view the night sky with the same awe and perplexity with which they might view some complicated maze.

It is true that the thousands of stars which may be seen at a single glance do appear to be a complicated maze. However, on examining the sky more closely, the observer will note that a few stars—and only a few—are relatively bright, and because of their unusual brilliance they appear to stand out prominently from all the other stars. Only these few bright stars are used in navigation. Therefore, it is very important that the aerial navigator be able to recognize them quickly, because they are literally the tools of his trade.

The astronomer, working in behalf of the navigator, has calculated and tabulated in the Air Almanac the positions in the celestial sphere of the 55 brightest stars and five planets most suitable for observation, so that the navigator may compute from these 60 known celestial positions the location of his aircraft. Of these 60 stars and

planets which are tabulated in the Air Almanac an infinitely small total compared to the innumerable stars seen at night—the author has used not more than 34 for navigation during his last 500,000 miles of travel.

IDENTIFICATION BY GROUPS

Knowing that only a few of the celestial bodies are needed for navigational purposes, the first step in learning these few is to obtain some good chart of the sky, such as that shown in Figure 136, taken from the Air Almanac. In gaining this knowledge, as in learning the parts of a complicated airplane structure, one may divide the stars into groups, or individual "sub-assemblies of the sky." For a start, Orion's Belt and Sword and the bright stars close by may be considered.

First Group—"Orion's Belt and Sword" (See Group Chart, Figure 137)—The constellation of Orion is easily recognized as a perfectly shaped little dipper. The three brightest stars, which usually are drawn as the belt in Orion, form the bottom of the dipper. This group, definitely recognized in the sky, may be used as a starting point for identifying other nearby stars.

Notice, for instance, that seven bright stars appear to form a circle around Orion; they are Rigel, Sirius, Procyon, Pollux, Castor, Capella, and Aldebaran. Try to learn these stars in this order, and then study each star to learn its individual characteristics.

- 1. RIGEL is just in front of the open end of the dipper.
- 2. SIRIUS is the brightest star in the sky and is located between Rigel and Procyon.
- 3. PROCYON is a very bright star. Nearby is a much dimmer, but easily seen sister star. Also, Procyon is located between Sirius and the sister stars, Pollux and Castor.
- 4. and 5. POLLUX (4) and CASTOR (5) are known as sister stars because they are of nearly equal brightness and very close together. Pollux, the brighter, is nearer Procyon.
- 6. CAPELLA is nearly as bright a star as Sirius. It has three little stars nearby in the shape of a triangle. Also, at a little greater distance are four other stars which, together with Capella, form a pentagon.
 - 7. ALDEBARAN is a bright, reddish-col-

ored star which forms, with four stars nearby, a perfect letter A.

Inside this group of stars, and near the bottom of the dipper, are two other very bright stars, Betelgeux and Bellatrix. Betelgeux is the brighter and has a reddish color.

After these stars have been learned and can be easily located in the sky, the observer will be able to find and name many other stars by their positions relative to this group.

For instance, assume that a very bright star is visible and its name is desired. With relation to known stars, it lies in a line with Procyon and Sirius. It appears to be a little farther away from Sirius than is Procyon, and not quite in a direct line but, rather, slightly offset in a direction away from Orion. Looking at the star chart (Figure 136) the name of this star is determined to be Canopus.

CANOPUS is the second brightest star in the sky.

This same procedure may be used to locate a star in the sky by use of the star chart (Figure 136). Suppose it is desired to find Regulus in the sky. Using the stars already known, the star chart indicates that Regulus is in direct line with Procyon and the three stars forming the belt of Orion.

REGULUS also is distinguished by the fact that it appears as the brightest star in the handle of a small sickle, formed by four dimmer stars nearby.

Note: In describing these stars, the author is endeavoring to record the exact line of reasoning followed when trying to identify the stars in flight. On the charts, and especially the group charts, they appear easy to find, but unless they are definitely located with relation to others known, they may prove difficult to identify.

Second Group—"Big Dipper and Associated Stars" (See group chart, Figure 138)—The Big Dipper is perhaps the easiest constellation to recognize. It is formed by seven stars: Alkaid, Mizar, Alioth, Megrez, Phecda, Merak, and Dubhe. Of these seven, Alkaid, Mizar, and Alioth in the handle, and Dubhe at the end of the cup are the best for navigation. The declination of the Big Dipper is above 50° North, therefore, if the navigator is above 40° North latitude the Big Dipper would never set below the horizon but would appear to revolve en-



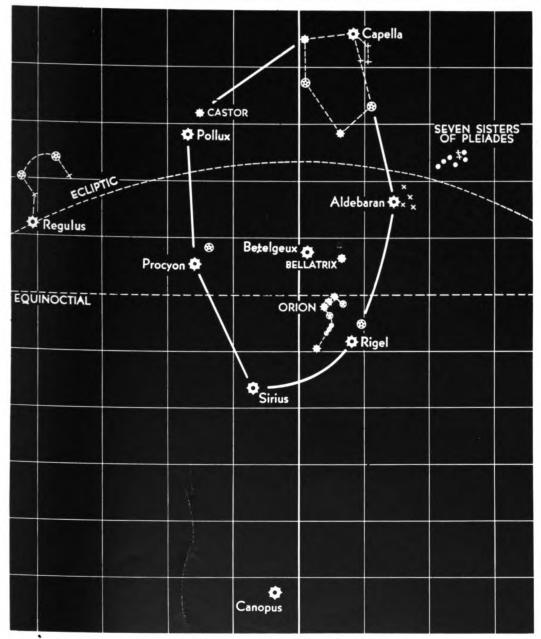


FIG. 137—"ORION'S BELT AND SWORD" GROUP

tirely around the North pole, due to the earth's daily rotation. At one time the Dipper might be seen right side up, as though filling, and then twelve hours later upside down, as though emptying.

To the astronomer, the Big Dipper is known as Ursa Major, but to mariners, for as

long as they have sailed in the Northern hemisphere, the Big Dipper is the North pole indicator. This is because the two stars in the cup, Merak and Dubhe, known as the pointers, point almost directly to Polaris.

POLARIS is the North pole star. Actually it is about 1° from the true North celestial pole.

☆ 141 ☆



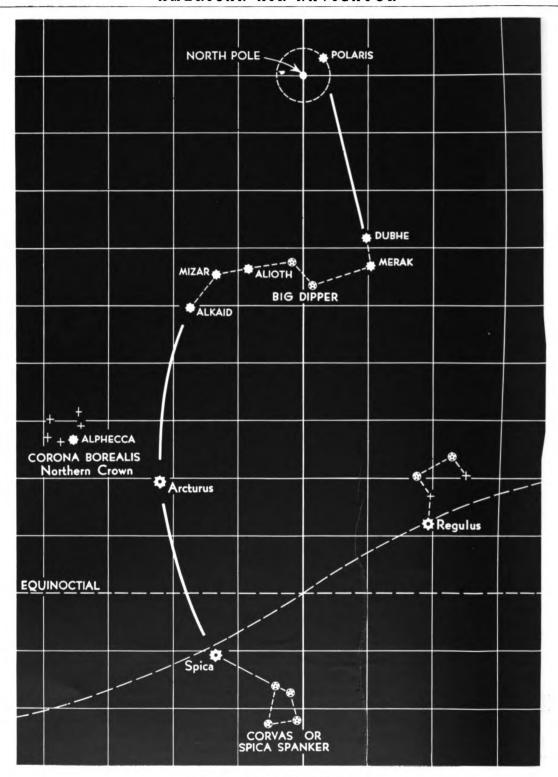


FIG. 138—"BIG DIPPER" GROUP

☆ 142 ☆



ARCTURUS and SPICA are two very bright stars which may be found by following the curve of the Big Dipper's handle on across the sky. First seen is Arcturus and then Spica. The distance of Spica from Arcturus appears to be very nearly equal to the distance of Arcturus from the end of the handle.

SPICA also may be identified by the constellation Corvus. Corvus is sometimes called Spica Spanker as it resembles a ship's spanker sail. The two stars at the top of the sail point to Spica.

ALPHECCA is the bright star in the constellation Corona Borealis, known as the Northern Crown. Corona Borealis is easily identified by its shape, which resembles a crown, and may be found by searching the skies northwest of Arcturus.

Third Group—"Great Right Triangle" (See group chart, Figure 139)—The Great Right Triangle is formed by the three very bright stars Altair, Vega, and Deneb.

ALTAIR is identified by two dimmer stars, which are located on either side of it in a straight line pointing directly toward Vega.

VEGA is the bright star at the right angle of the great triangle. It may be identified further by two dimmer stars close by, each of which points to an adjacent angle of the great triangle, and which with Vega form a tiny right triangle.

DENEB at the third angle of the great triangle appears slightly dimmer than either Altair or Vega. It also may be identified by two dimmer stars nearby. Each of these stars points to an adjacent angle of the great triangle and form with Deneb a medium-sized equilateral triangle.

Fourth Group—"Square of Pegasus" (See group chart, Figure 139)—All of the stars in this group are of medium brightness, but they are easily recognized in the sky and are useful in placing other stars. The four stars Alpheratz, Scheat, Markab, and Algenib, equally distant from one another, form a great square. Sometimes, however, this constellation is called "The Kite" as there are three other stars lined up with one corner of the square which makes the Square of Pegasus resemble a kite and tail.

ALPHERATZ, the star in the tail corner and MARKAB, in the opposite corner are tabulated in the Air Almanac, and are thus useful for navigation.

The Square of Pegasus identifies Fomalhaut and Deneb-Kaitos.

FOMALHAUT is in line with Scheat and Markab.

DENEB-KAITOS is in line with Alpheratz and Algenib.

ENIF affords another example of finding a star by lining it up with stars already known, as it is in line with, and halfway between, Altair and Markab.

These four star groups include most of the useful navigation stars. If the student learns them well, he should have little difficulty in identifying the other bright stars in the sky.

Constellation Groups — There are a few other stars often used in navigation which may be easily identified by their own constellation characteristics, as was Alphecca in Corona Borealis, without resort to grouping. These are, in part:

- 1. CAPH, SCHEDIR, and RUCHBAH in the constellation Cassiopeia. (See star chart, Figure 136). Cassiopeia is a northern constellation in the shape of a W, M, or a chair and is sometimes called the W, the M, or The Chair depending on its appearance to the observer as it changes position in the sky.
- 2. NUNKI and KAUS-AUSTRALIS in the constellation Sagittarius. Sagittarius is a Southern constellation near the ecliptic having the appearance of a little dipper.
- 3. RIGIL KENTAURUS and the SOUTH-ERN CROSS. In the Southern Cross (CRUX) the two stars tabulated in the Air Almanac are β and γ Crucis, identified on the chart by the Greek letters β (BETA) and γ (GAMMA). Rigil Kentaurus and β Kentaurus are called the Southern Cross pointers, as they point directly to the Southern Cross.

IDENTIFICATION BY H. O. 214

Sometimes flight conditions arise where it is necessary for the navigator to take a sight of a celestial body which he is unable to identify by the usual method of its relation to nearby stars. For example, after flying under an overcast sky for several hours the navigator sights a single celestial body through a break in the clouds. In such a case the body may be identified by reference to any altitude-azimuth table or star finder if the altitude and azimuth of the body and the Greenwich civil time are known.



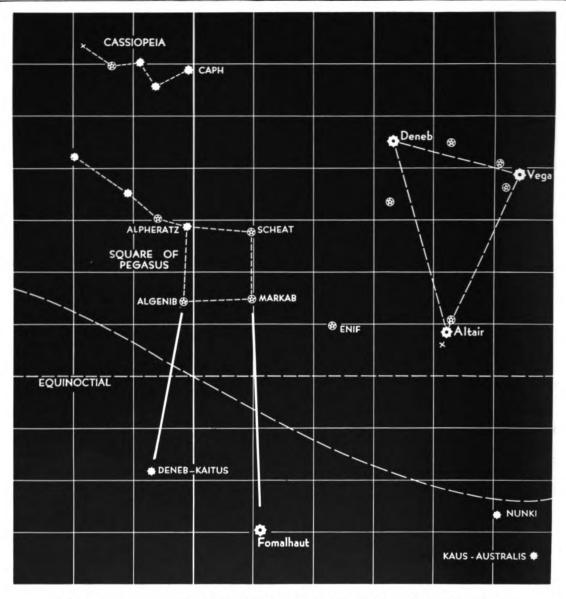


FIG. 139—"GREAT RIGHT TRIANGLE" AND "SQUARE OF PEGASUS" GROUPS

The Procedure using H. O. 214 is as follows:

- a. Observe altitude of the body.
- b. Note exact GCT.
- c. Estimate the body's true bearing and convert true bearing to azimuth (Figure 140).
- d. Enter Star Identification Table H. O. 214, which immediately follows the proper latitude (latitude of the observer), with the alti-

tude and azimuth of the body, and extract tabulated values of approximate LHA and declination. The LHA is tabulated from 0° to 180° East or West. The azimuth name determines the name of the tabulated LHA. If the azimuth is East, the LHA is East because the body is rising. If the azimuth is West, the LHA is West because the body is setting. Tables show declination North or South.

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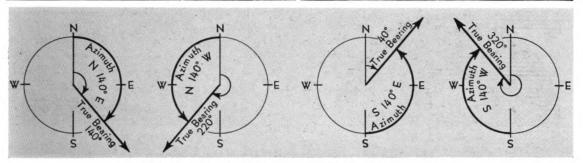


FIG. 140-AZIMUTH MEASURED FROM ELEVATED POLE

- e. Convert tabulated LHA if East to LHA West by subtracting LHA East from 360° (360° LHA East = LHA West).
- f. Apply DR longitude to LHA West to obtain GHA body.

$$\begin{array}{ccc} & + & \text{West longitude} \\ \text{GHA} = \text{LHA West} & - & \text{East longitude} \end{array}$$

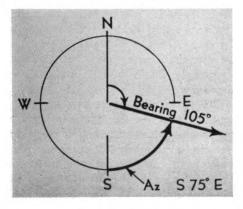


FIG. 141— Z_n 105° = A_z S 75° E

- g. Extract $GHA\gamma$ from Air Almanac for the exact GCT of observation.
- h. Find SHA body by subtracting GHA Υ from GHA body (add 360° to GHA body if necessary).
- i. Enter Air Almanac, inside back cover, with SHA body and declination. Extract name of star whose coordinates are nearest to calculated SHA and declination.

Example: (Solution of star identification problems is simplified by the use of some such form as that employed below).

May 30: A navigator obtains an altitude of an unknown celestial body of 67°26′ at 07^h52^m00^s GCT. With the aid of the pelorus (instrument for measuring a bearing) he estimates its true bearing to be 105°.

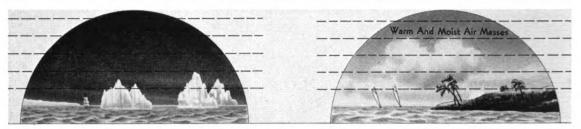
DR position = latitude $32^{\circ}16'$ S, longitude $117^{\circ}28'$ W.

$$Z_n = 105^\circ$$
; Az = S 75° E (Figure 141).

SHA* 86°31'
Dec. 35°S
Star is Kaus. Australis

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AMERICAN AIR NAVIGATOR



POLAR AIR MASS

TROPICAL AIR MASS

Dotted Lines Illustrate Different Levels Where Temperature, Pressure
and Moisture Content Are Relatively the Same Throughout the Air Mass.
FIG. 142—CHARACTERISTICS OF AIR MASSES DERIVED FROM SOURCE REGIONS

PRACTICAL WEATHER MAP FORECASTING

Weather map forecasting is the science of graphically recording possible weather and winds to be expected along a proposed route. This information is predetermined, primarily by reference to known observations of past weather. If the sky were continually clear, weather in itself would be relatively unimportant. But the fact that temperature and pressure changes cause rain, snow, fog, hail, or any number of various other weather phenomena makes a study of meteorology—or at least a general knowledge of its more important aspects—essential to successful flight.

This knowledge is of particular interest to the navigator, who is responsible for seeing that his aircraft reaches its destination safely. It is apparent that an aircraft, having no physical ties to the earth, is subject to every weather condition generated by the atmosphere.

A general knowledge of the fundamentals of meteorology and an understanding of the problems of the meteorologist in forecasting weather, together with the ability to converse with the meteorologist in his own terms, are important qualifications for the air navigator of today. The following is an attempt to familiarize the navigator with the more important aspects of weather analysis in general, and to acquaint him with the causes and effects of weather phenomena as they apply to him in particular.

Air Masses—An air mass is a large body of air approximating horizontal homogeneity. In other words, the physical characteristics are the same over a large area at different levels. These large bodies of air derive their characteristics from, and are named for, their source

regions. That is, air masses originating over polar regions are inherently cold and dry. Those originating in tropical regions tend to be warm and moist (Figure 142). Tropical and polar, therefore, are the names generally applied to warm and cold air masses respectively; however, the source region does not necessarily have to be the tropical or polar region. For instance, large air masses which become stagnant over the Gulf of Mexico take on the warm, moist characteristics of the Gulf water, and in the winter the large air mass between the Cascades and the Rocky Mountain range becomes cold and dry.

The air mass, though it is stagnant long enough to take on the characteristics of its source region, does not remain stagnant, because wind changes and air pressure phenomena cause it to move across the surface of the earth. As the air mass moves it begins to take on the properties of the surface over which it passes. For example, a cold, dry air mass which lingers over a warm body of water takes on moisture and heat. As it warms and expands it is able to hold more moisture. The air mass, however, does not simply mix, but instead the cold air being heavier underruns the lighter, warmer air causing a discontinuity known as a frontal surface, which chiefly causes storms.

Pressure Systems—A study of the movement of air masses must take into consideration the development of high and low pressure areas. Temperature is the chief cause of changing pressure. The atmosphere contracts at low temperatures and, concentrating over a smaller area, exerts higher pressure. Conversely, high temperatures cause air to expand and the resulting distribution of its weight results in lower pressure (Figure 143).

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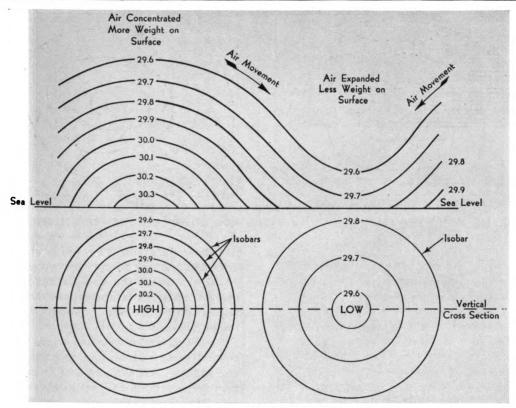


FIG. 143—PRESSURE SYSTEMS AND ISOBARS

Isobars—Isobars are lines connecting points of equal barometric pressure. By reference to these lines on a synoptic chart (a chart which condenses much data into one source), high and low pressure areas may be located in a manner similar to that used to show mountains and valleys on an aeronautical chart by means of contour lines (Figure 143).

Winds—Wind is merely the result of moving air. This movement takes place from an area of high pressure toward an area of low pressure in an attempt to equalize the total atmospheric pressure. Figure 143 shows how air moves in a manner similar to water flowing downhill. The steeper the gradient, the faster the flow. It is obvious, then, that the closer the isobars are together, the faster will be the flow of air indicated, hence the greater the wind velocity. Thus far it would seem, taking into consideration only the gradient force, that the wind would blow in a direction perpendicular to the isobars toward the low pressure area. However, a deflecting element known as

Coriolis force must be considered. This force is a result of the rotation of the earth upon its axis, and turns all winds to the right in the Northern hemisphere and to the left in the Southern hemisphere. It then becomes apparent that, in the Northern hemisphere, winds develop a counterclockwise movement toward the center of a low or cyclonic area, and a clockwise movement outward from a high or anticyclonic area. This is illustrated in Figure 144. The same force causes the reverse situation in the Southern hemisphere. Turning to the left instead of to the right, the movement becomes clockwise in a low and counterclockwise in a high. The direction of the wind is always given in degrees, measured clockwise from true North in the direction from which the wind is blowing.

Surface winds are affected by local high and low pressure areas, while upper air winds more or less conform to the prevailing highs and lows and change with frontal systems. That is, winds in mid-latitudes become prevailing westerlies in both hemispheres where they



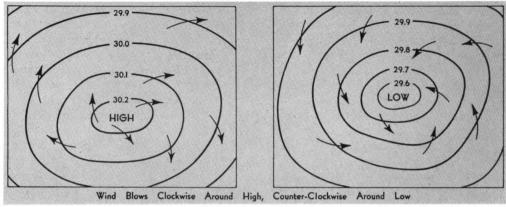


FIG. 144-WIND MOVEMENT AROUND HIGHS AND LOWS IN NORTHERN HEMISPHERE

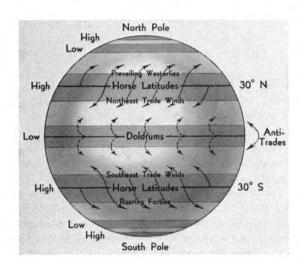


FIG. 145—EARTH'S BASIC WIND CIRCULATION

rise above the gradient force of local highs and lows and are less affected by surface friction. At higher levels, the Coriolis force predominates. Equatorial latitudes have their prevailing easterly trade winds for much the same reason (Figure 145).

Another factor affecting winds is the unequal cooling and heating properties of land and water. Land surfaces heat quickly during the daytime, resulting in sea breezes blowing in over the coast. Conversely, land areas cool faster at night, causing winds to shift and resulting in land breezes out to sea. This phenomenon becomes important when flying close to continental coastlines.

CLOUDS

Cloud Families—Clouds are a visible sign of atmospheric activity, appearing as visible

2. Ciri	rus (Ci) ro-cumulus (Cc) ro-stratus (Cs)	Thin and Featherlike Thin—Cotton or Flakelike Very Thin—High Sheet Cloud
MIDDLE CLOUDS	(CM) MEAN LEVELS	S 6500 TO 20,000 FEET
	o-cumulus (Ac) o-stratus (As)	Puffy—Sheep Back Medium High—Uniform Sheet Cloud
LOW CLOUDS (CL	.) MEAN LEVELS C	LOSE TO SURFACE TO 6500 FEET
7. Stra	ato-cumulus (Sc) atus (St) abo-stratus (Ns)	Globular Masses or Rolls Low Uniform Sheet Cloud Low Amorphous and Rainy Layer
VERTICAL CLOUI	OS (CL) MEAN LEV	ELS 1600 TO 20,000 FEET
	nulus (Cu) nulo-nimbus (Cb)	Dense—Dome-shaped and Puffy Towering Cauliflower—Anvil Top

FIG. 146—CLOUD FAMILIES

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moisture condensed from warm, moist air which is cooled by expansion upon rising to higher levels. The two basic cloud types are cumuliform and stratoform, the former being developed vertically in puffy shapes, and the latter appearing as more or less flat sheet clouds. These are further broken down into four family names according to the heights at which they are found. Symbols for these clouds are shown on all weather maps.

Figure 146 shows the cloud families.

Ceiling—The height of the clouds above the surface of the earth is defined as ceiling.

Sky Cover—The amount of clouds covering the dome of the sky is shown by four symbols (Figure 147):

Classification	Sky Cover
Clear	Total Sky Cover less than one-tenth.
Scattered	One-tenth to five-tenths covered.
Broken	More than five-tenths but less than nine-tenths.
Overcast	Over nine-tenths of sky covered.
	Clear Scattered Broken

FIG. 147—SKY COVER

Fogs—Practically the only difference between a fog and a cloud is the point of view of the observer; fog is nothing more than a stratus cloud on the surface of the earth. There are four principal types of fogs: advection, upslope, radiation, and frontal.

Advection fog is the result of warm moist air blowing over a cooler surface. Coastal sea fogs are an example of this type.

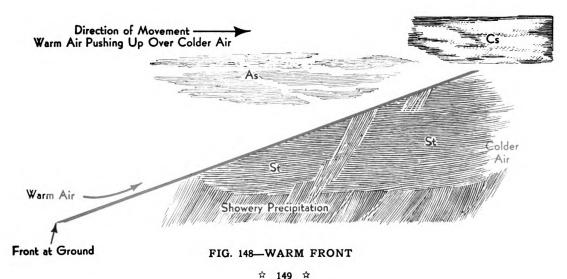
Up-slope fogs form when parcels of air are mechanically lifted over mountainous terrain and cooled to their dew point. These are obviously restricted to land areas.

Radiation fogs form mainly over land surfaces at night as a result of the earth's cooling. Prerequisites include a temperature inversion and winds of less than eight miles per hour. They are very low-hanging and disappear soon after the sun starts heating the earth once more in the morning.

Frontal fogs occur in frontal zones, principally warm fronts, where warm moist air contacts a body of colder air. They form similarly to the advection type, but are restricted to the smaller area at the front only.

FRONTS

General—A front is simply a line of discontinuity separating two air masses of dissimilar characteristics. Warm moist air pushing up over the surface of colder air is cooled, and precipitation takes place. Heavier cold air squeezing in under warm moist air lifts it to the condensation level and again precipitation occurs. Familiarization with fronts is essential because most of the hazards of flying take place where these air masses of unlike qualities meet. Of particular interest to the pilot is the fact that approximately 90% of all icing takes place in a frontal zone.



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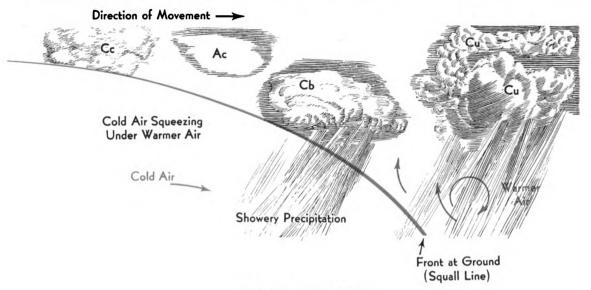


FIG. 149—COLD FRONT

The observer should remember that the fronts are shown on weather maps as a line of discontinuity at the ground. The air navigator must take into consideration the altitude of his aircraft when attempting to determine the point where he will encounter the front, in addition to the movement of the entire frontal system which occurs in an East-South-Easterly direction across the Pacific at a rate of approximately 500 miles per day. Passage of a front is recognized chiefly by a decided temperature change and wind shift; both are items of importance to be considered in air navigation.

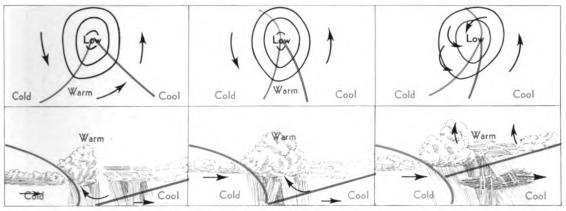
Fronts are divided into three main categories: warm, cold, and occluded.

Warm Fronts (Figure 148)—A warm front is indicated where warm air is replacing cold air at the ground. It has a very gentle slope upward over the colder air and is usually accompanied by stratoform clouds, lowering ceilings, and an area of steady precipitation preceding the front. The sequence of clouds observed is usually cirro-stratus, alto-stratus, and stratus. Passage of the front is indicated by an attempted clearing, a decided wind shift, humid air, and mild to moderate turbulence. The principal hazard to aircraft associated with a warm front is fog. Any icing encountered is usually of the rime variety, which is porous and can be taken care of by deicer or anti-icing equipment.

Cold Fronts (Figure 149)—Cold air is replacing warm air at the ground in the case of a cold front. A fast-moving cold front is accompanied by severe turbulence and line squalls which may include frontal thunder storms recognized by the familiar cumulo-nimbus clouds with their anvil tops. Precipitation is more intense but usually confined to the showery type in spotted areas under the cumulus clouds. Hail may be encountered if temperatures are low enough and high swelling cumulo-nimbus clouds are present. In many cases under these conditions, vertical currents beneath these clouds are in excess of 100 miles per hour. It is sufficient to say that they can be dangerous. Passage of the front is indicated by a decided wind shift and drop in temperature followed by clear, cold, good flying weather. Cumuliform clouds follow after the front. The slope is steeper than the warm front.

The principal hazard of the cold front is icing, but also may include severe vertical currents and probable hail showers. Icing is mostly of the clear type which spreads quickly and destroys the airfoil. Vertical currents support larger droplets of water which spread before freezing.

Occluded Fronts — In an occluded front warm air is squeezed off the ground entirely and replaced by colder air. By reference to



Occluded Front
Warm Front
Cold Front

FIG. 150—DEVELOPMENT OF OCCLUDED FRONT

Figure 150 it will be seen that an occluded front is actually the breaking up of a low pressure area, and passage directly through the occluded part will be accompanied by a drop in temperature and very changeable winds. Passage to the south will encounter successive warm and cold fronts according to the direction of flight. Figure 150 shows both top and side view drawings of an occlusion in process.

SUMMARY

Figure 151 represents a typical weather map. The summary below will follow through a flight, and indicate how you, as the navigator, would analyze this information for flight purposes.

First of all, notice the GCT for which the map was drawn, which is important in that the fronts to be crossed on your course are located for 18h00m GCT only and will move easterly at approximately 21 miles per hour as we progress. It is apparent that temperatures will gradually rise as we leave San Francisco, and that we will be aided by moderately increasing tail winds.

We may expect to encounter the warm front indicated by the heavy red line considerably sooner than indicated, due to the fact that, in addition to the front having moved toward us, its gentle forward slope will cause us to encounter it even sooner at our flight altitude. The definite wind shift from East to Southwest will be accompanied by a slow increase in temperature, weather clearing, and

smooth air after passage through the front. Low stratus clouds will probably be observed preceding the front with an area of continuous precipitation underneath.

A second wind shift may occur with probable head winds as the heavy blue line (cold front) approaches. It will be noted that at 18h00m GCT, this front is at Honolulu, but will have passed Honolulu before your arrival. Assuming we have a fast plane, we may still pass South of the approaching line squalls which would be visible ahead as a black wall of clouds in the daytime, or evident by the blotting out of low stars at night in the general direction. In any event, we should be prepared to alter course to the left to avoid considerable turbulence and rough weather. This is based on the assumption that the line of discontinuity in question separates air masses of decidedly opposite characteristics. We would be advised of this previous to take-off by the meteorologist in charge.

Assuming that we pass South of the approaching cold front, we may still expect head winds gradually increasing in velocity. This is made evident by the fact that the isobars are closer together, and by the presence of a low pressure area moving in from the Northwest.

The approaching cold front will definitely cross our path and will indicate its passage by a temperature drop, squally weather, and the presence of cumulus type clouds. The intensity of its vertical currents and turbulence may be

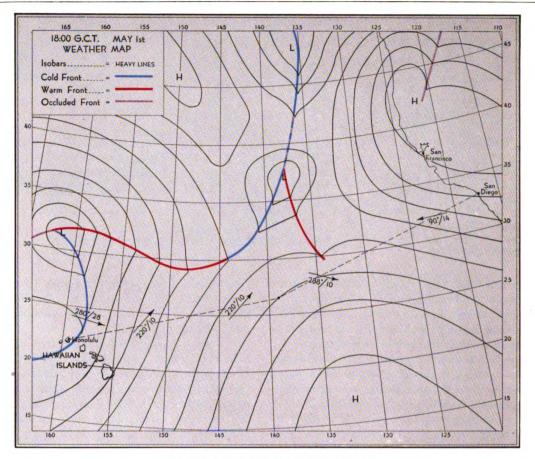


FIG. 151-TYPICAL WEATHER MAP

judged by the vertical swelling of its cloud systems.

The knowledge obtained from the meteorologist before the take-off may be augmented by a radio weather report from Honolulu as to the frontal conditions which we will encounter.

Another wind shift from Southwest to Northwest may be expected after passage of the front. Head winds are still prevailing but the shift may counteract the drift applied on our present heading. A celestial fix at this time should show us any drift tendency, and our destination should be in sight shortly thereafter. Note: No attempt is made in the foregoing to go deeply into meteorology as a science with its accompanying lapse rates, pressure tendencies, and various weather phenomena. The effort has been directed entirely toward acquainting the air navigator with the basic principles as they apply to the safe flight of his aircraft. Perhaps the air navigator of tomorrow will himself be a competent meteorologist. Until then, he can learn a great deal through intelligent conversation with the weather forecaster if he has been trained to know what the forecaster is talking about in addition to knowing what to look for and the probable results.



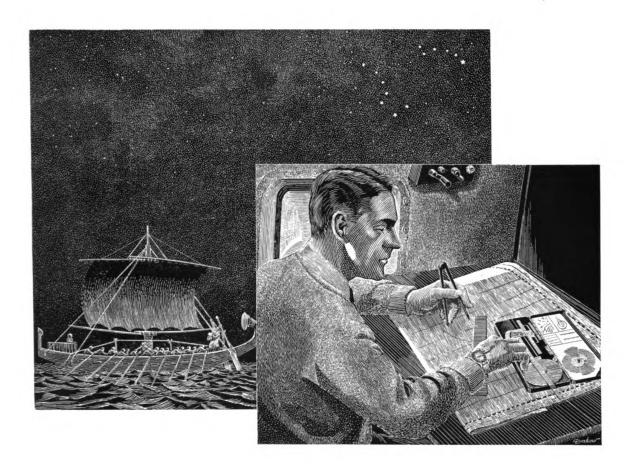
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PROBLEM WORK NO. 30 STAR IDENTIFICATION BY H. O. 214

(Identify stars by H. O. 214 method.)

			DR P	OSITION			
No.	DATE	GCT	Lat.	Long.	Ho	AZIMUTH	STAR
1	5- 5-43	13:27:00	37°50′N	121°01′E	19°58′	N 55°E	
2	5- 1-43	13:14:00	39°24′S	110°31′E	37°12′	S 80°W	
3	5-10-43	11:24:00	38°15′N	146°14′E	38°15′	N160°E	
4	5- 5-43	19:43:00	36°14′S	89°45′E	25°00′	S 120°E	
5	5-20-43	13:40:00	32°40′N	123°14′E	38°02′	N100°W	
6	5- 1-43	12:04:00	38°42′S	173°13′W	36°14′	S 25°W	
7	5-25-43	00:49:00	34°17′N	64°50′W	53°08′	N 90°E	
8	5-30-43	02:43:00	35°10′S	84°30′W	51°10′	S 90°E	
9	5-20-43	08:32:00	30°10′S	135°11′W	44°04′	S 80°E	
10	5-15-43	19:24:00	34°48′S	132°12′E	51°34′	S 110°W	
11	.5-25-43	20:48:00	33°21′S	56°46′E	44°38′	S 165°E	
12	5-30-43	07:52:00	32°16′S	117°28′W	67°26′	S 75°E	
13	5-25-43	11:36:00	30°03′S	137°17′E	18°08′	S 40°W	
14	5-10-43	10:30:00	33°45′N	179°46′W	59°32′	N120°W	
15	5- 1-43	02:44:00	38°30′N	43°28′W	66°40′	N 35°W	
16	5-15-43	19:33:00	31°38′N	32°32′E	24°26′	N140°E	
17	5-10-43	02:17:00	39°18′S	28°04′W	67°22′	S 85°E	
18	5-20-43	14:32:00	37°10′N	122°44′E	23°46′	N 50°E	
19	5- 5-43	18:42:00	31°26′N	170°23′W	60°04′	N 85°E	
20	5-15-43	18:22:00	36°20'N	146°12′W	34°52′	N170°E	





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SPECIAL PROCEDURES

THE navigator who understands and applies all available navigation procedures, keeps a constant check on his aircraft's track and carefully analyzes all position data for possible errors, will be able to report quickly, and within close limits, the position of his aircraft at any time. Furthermore, he seldom will feel in doubt as to his location.

However, certain factors over which he has no control—such as weather, or fatigue—may cause him temporary uncertainty. At such

times, position-finding data appears conflicting and unreliable, and it is then that the navigator must guard against the natural tendency to become excited and confused. Several rules apply under such circumstances:

- 1. Remain calm. A cool mind functions much better in an emergency than one which tries to make decisions under emotional tension.
 - 2. Act intelligently. Use common sense.
- 3. Continue searching for information. The best plan, of course, is to try to obtain a celes-

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tial fix. If this is not possible, perhaps there are gaps in the overcast which will at least permit securing of a single L.O.P., which can be used for a track or ground speed check. Also, it may be possible to climb above the overcast.

At the same time, the navigator should continue trying for radio bearings which, either alone or combined with celestial lines of position, will enable him to establish his location.

- 4. Recheck all work. Correction of a careless mistake may enable you to establish your position.
- 5. Most important of all—do not alter aircraft's heading unless the decision to do so is based upon definite information.

FIXED SQUARE SEARCH

In the event the E.T.A. has elapsed without the destination having been sighted, the best procedure is to continue on the same heading until certain the objective has been passed. The navigator should keep trying to get celestial lines of position or radio bearings which

will give him definite information as to the aircraft's position. If such information cannot be obtained and the navigator is entirely dependent upon DR, direction of flight should be continued for a period of from 20 to 30 minutes, depending upon the accuracy with which ground speed was known when computing the E.T.A., and also upon the amount of fuel remaining. If the destination has not been sighted by then, nor any new position data obtained, a fixed square search procedure may be instituted. This is a method by which an aircraft can systematically search a fairly large area to locate a small object, such as an island, a disabled ship or a life raft. It is called a "fixed" square search, because it presumes that the object being sought is stationary. Before beginning the search it is necessary to determine the visibility (or the distance, in nautical miles, the observer can see in any direction). This distance is the visibility factor (V), and is based on the size of the object being sought, altitude of the aircraft and, principally, the

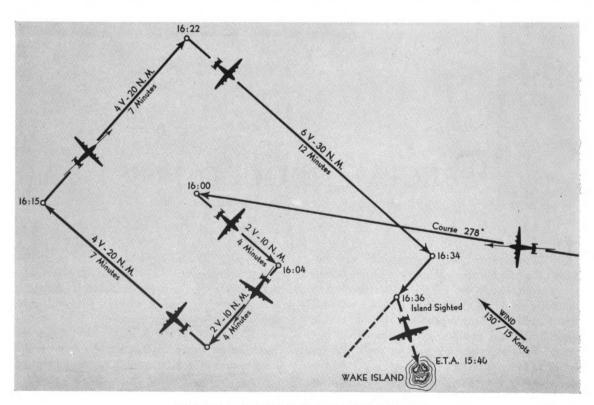


FIG. 152—SQUARE SEARCH PROCEDURE

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visibility of the atmosphere. As visibility often is difficult to estimate, it is wise to be conservative in choosing a visibility factor. The determination of this factor, and the application of the square search procedure is illustrated by the following example.

Example (Figure 152):

The navigator of an aircraft having exceeded his E.T.A. (15:40 GCT) by 20 minutes without sighting his objective (Wake Island), is authorized by the captain to institute a fixed square search procedure. Accordingly, at 16:00 GCT he advises the captain to assume a heading of 130° true in order to fly directly into the wind for the first leg. This upwind heading is flown first, both because it requires no drift calculation and because it reduces the ground speed to a minimum, thus affording more time in which to compute headings for the other legs. The T.A.S. is 165 knots; the wind-determined as carefully as possible by estimate, forecast, or double drift—is 130°/15 knots. The atmospheric visibility appears to be about eight miles, but to be safe the navigator decides to . use a visibility factor of five miles.

The upwind heading is held for a distance equal to 2V (10 miles). And since the aircraft is flying upwind, its ground speed is equal to T.A.S. less the velocity of the wind, or 150 knots. Therefore, it requires 4 minutes to complete the first leg. When the first leg has been completed (16:04), the pilot turns to the right, putting the aircraft on a true heading of 215°. This heading was worked out by the navigator during the first leg, and includes proper drift allowance. This second heading enables the aircraft to make good a track 90° from the first leg.

Note: Instead of turning *right*, as cited in this example, the pilot might have turned *left* to assume a course 90° to the *left* of the original track. Direction of turn is dictated by circumstances under which the search procedure is employed.

This second heading is, in turn, held until a distance equal to 2V (10 miles) has been covered, which requires 4 minutes. When the second leg has been completed (16:08 GCT) the pilot again turns to the right and flies directly downwind (true heading 310°) for the

third leg, a distance equal to 4V (20 miles). At 16:15 GCT, heading is again altered to 045° in order to make good a track 90° from that flown on the third leg, and a distance of 4V (20 miles) is flown on this heading.

Since Wake Island still is not in sight on completion of the fourth leg (16:22 GCT), the navigator prepares to repeat the entire procedure, again increasing the distance to be flown by 2V for each succeeding two legs. Accordingly, at 16:22 GCT a right turn is made to begin the fifth leg, which, like the first leg, is directly upwind. This upwind heading is held for a distance equal to 6V (30 miles). Wake Island is not sighted on the fifth leg, so at 16:34 GCT a right turn is made for the sixth leg. After flying on this leg for two minutes, the island is sighted, bearing 160° true and seven miles distant. On checking his search plan, the navigator finds that Wake Island actually was 26 miles distant, bearing 127° true from the aircraft when the search was started.

RUNNING DOWN A SUN LINE

Running down a sun line is a procedure used by the navigator to reach a difficult objective, such as a small island, when only the sun is available for observation.

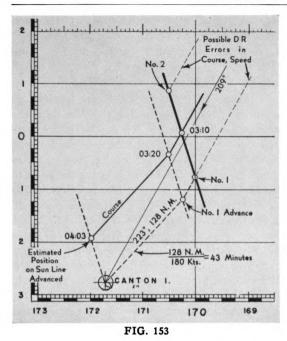
For instance, assume that an aircraft is making a daylight flight from Honolulu to Canton Island. During the day, the navigator has been estimating his position solely by sun position lines and drift meter readings. The sun lines have given him a fair estimate of the aircraft's position. However, several hours from Canton Island, he turns on the radio direction finder in order to make sure of his approach, and finds the radio isn't working.

Canton Island is a very small coral atoll, and the navigator knows that if he were only a few miles off course he could easily pass Canton by without seeing it. He therefore recommends to the captain that it would be advisable to run down a sun line.

The procedure is as follows (Figure 153): Given: course 209°—G.S. 180 knots.

a. About one hour from Canton Island the navigator observes the sun and obtains the 03:10 position line. From previous position lines and drift meter readings he indicates the





most probable position on the sun line with a circle.

- b. He then estimates possible errors in ground speed and course, and finds positions No. 1 and No. 2, which represent possible position limits on the sun line.
- c. 03.20—Since it took ten minutes to calculate and plot the sun line, he advances position No. 1 ten minutes of ground speed and measures the course to Canton as 223°, distance away 128 NM.
- d. Altering compass heading to fly 223° true, he then knows the aircraft will be definitely to one side of Canton, and should be somewhere on the position line advanced through Canton Island at 04:03.
- e. To check, he again observes the sun and plots another position line at 03:40. Advancing this line through Canton Island, he determines the aircraft will be somewhere on the advanced line at 04:00 (Figure 154).
- f. Therefore, at 04.00 he once more alters compass heading to fly 168° true which would run down the sun line, and thus fly over Canton Island.
- g. Until Canton Island is sighted, however, he continues to plot sun lines at ten-min-

ute intervals to make certain his course will pass over the island.

LATITUDE BY MERIDIAN ALTITUDE

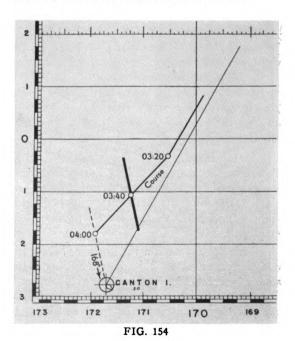
To take a meridian altitude sight means to measure the altitude of a celestial body when it is on the observer's meridian. This procedure is employed to determine the observer's latitude, and it is one of the simplest problems in celestial navigation. Its solution is derived from the fact that when a body is on the observer's meridian, its local hour angle is zero, hence the astronomical triangle is reduced to a straight line (Figure 155).

Procedure — The procedure necessary to determine latitude by meridian altitude is as follows:

- a. Observe altitude of celestial body.
- b. Find zenith distance (Zd) by subtracting true altitude (H₀) from 90°.

$$90^{\circ} - H_{\mathbf{0}} = Zd$$

c. Determine bearing of observer's zenith from the celestial body (North or South) and name zenith distance accordingly. Thus, in example No. 1 (Figure 155), the zenith is North of the celestial body. Zenith distance, therefore, takes the name *North*. In example No. 2 (Figure 155), the zenith is South of the celestial body. Zenith distance, therefore, takes the name *South*.



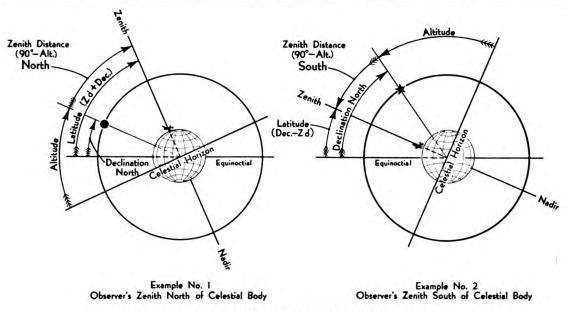


FIG. 155-LATITUDE BY MERIDIAN ALTITUDE

d. Combine zenith distance and declination to obtain observer's latitude. If values have same name, add them together and give the resulting latitude their common name. If values have contrary names, subtract smaller from larger to obtain their difference which will take the name of the *larger* value and will, again, represent the observer's latitude.

again, represent the observer's latitude.

$$Zd \sim dec. = Latitude$$

Example No. 1

Observer's Zenith North of celestial body

 H_{S} Sun $= 55^{\circ}$ 00'

 $Refraction = 0'$
 $H_{O} = 55^{\circ}$ 00'

 $from 90^{\circ}$ 00'

 $ZD = 35^{\circ}$ 00' N

 $Declination = 12^{\circ}$ 00' N

 $Latitude = 47^{\circ}$ 00' N

Example No. 2

Observer's Zenith South of celestial body

 H_{S} Star $= 60^{\circ}$ 00'

 $Refraction = 0'$

 $=60^{\circ} 00'$

 $=30^{\circ} 00' \text{ S}$

 $= 13^{\circ} 00' \text{ N}$

from 90° 00'

Declination =43° 00′ N

FINDING TIME OF MERIDIAN TRANSIT

When the GHA of a celestial body is the same as the observer's longitude, the LHA is zero. This instant is called the *time of meridian transit*.

As has been previously stated, longitude may be defined as the angle, measured at the terrestrial poles, between the Greenwich meridian and the meridian of an observer. Similarly, GHA may be defined as the angle, measured at the celestial poles, between the Greenwich (celestial) meridian and the celestial meridian (hour circle) of a celestial body. It is apparent, therefore, that longitude and GHA correspond exactly, the only difference being that GHA is measured to the West through 360°, whereas longitude is measured East or West through 180°.

Graphic Method — The time of meridian transit may be found graphically by advancing the DR position of the observer along the course until his DR longitude is equal to the GHA of the body (found in the Air Almanac) for the same instant of time. This procedure is illustrated in the following example:

Example (Figure 156):

On January 1, at 17h00m GCT in longitude 100° 10′ West, the navigator desires to precompute the time of meridian transit of the sun.



 $H_{\mathbf{0}}$

ZD

Latitude

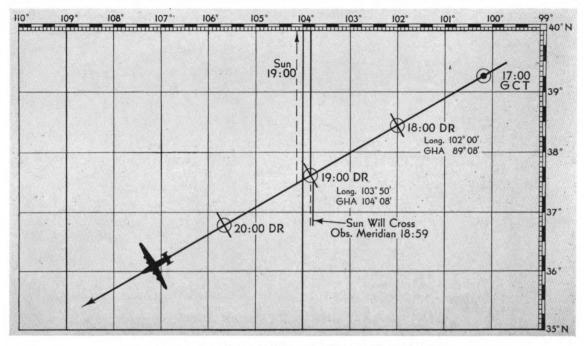


FIG. 156—FINDING TIME OF MERIDIAN TRANSIT

His course is 240° true and ground speed 102 knots.

Referring to the Air Almanac, he finds the GHA to be 89°08′ for 18h00m GCT. His DR longitude, however, he computes 102°00′, hence the sun will still not have overtaken him by this time. Accordingly, the navigator again computes his DR longitude, this time for 19h00m GCT, and finds it to be 103°50′. He then notes the tabulated GHA as 104°08′, hence the sun will by this time (19h00m GCT) be 18′ past his meridian, or approximately one minute of time.

Note: A celestial body advances in longitude to the West

15° in one hour 1° in four minutes ½°, or 15' in one minute

Therefore, he concludes that the time of meridian transit will be very close to 18h59m GCT.

Rate of Closure Method—The time of meridian transit also may be worked as a rate of closure problem (rate at which celestial body is overtaking the aircraft). The procedure is as follows:

- a. On an even hour before meridian transit, step off one hour of ground speed along the course.
- b. Next, measure the aircraft's rate of departure, that is, the number of degrees and minutes of longitude which the aircraft crosses in one hour.
- c. Since a celestial body travels westward, traversing longitude at the rate of 15° per hour, find the rate of closure (R of C), or rate at which the sun is overtaking the aircraft, by subtracting the aircraft's rate of departure from 15°.
- d. The LHA of the celestial body at the time of departure is the distance in degrees and minutes of arc which the body must close in order to overtake the aircraft. Therefore,

$$\frac{LHA}{R \text{ of } C} + GCT \text{ departure} = time \text{ of }$$
meridian transit.

Example:

Using the same data as in the previous example (Figure 156), the navigator determines the aircraft's rate of departure to be 1°53′ of longitude per hour. Therefore, 15° less 1°53′ = 13°07′ R of C. (Plane flying away from sun causes sun to close at a rate less than 15° per hour).



The navigator then finds the interval of closure (LHA at 17h00m GCT) as follows:

GCT
$$17^{\text{h}}00^{\text{m}}$$
 GHA = $74^{\circ}09'\text{W}$
Longitude = $100^{\circ}10'\text{W}$
LHA = $25^{\circ}01'$

Hence,

$$\frac{25^{\circ}01'}{13^{\circ}07'} = \frac{25.01^{\circ}}{13.11^{\circ}} = 1.91^{h} = 1^{h}56^{m}$$
or, $17^{h}00^{m} + 1^{h}56^{m} = 18^{h}56^{m}$ time of meridian transit.



PROBLEM WORK NO. 31 LATITUDE BY MERIDIAN ALTITUDE

(Find latitude by meridian altitude method.)

No.	CELESTIAL BODY	DATE	MTr (GCT)	Ho	BEARING	LATITUDE
1	SUN	5- 1-43	01:50	78°48′	S	
2	SUN	5-15-43	04:32	74°31′	N	
3	SUN	5-10-43	19:45	61° 3 6′	S	
4	SUN	5-20-43	14:21	56°47′	N	
5	SUN	5- 5-43	22:00	49°48′	N	
6	JUPITER	5- 5-43	02:40	68°31′	S	
7	VEGA	5-10-43	11:00	81°09′	N	
8	MOON	5-20-43	08:14	41°01′	S	
9	ARCTURUS	5- 5-43	07:11	65°29′	N	
10	ANTARES	5-15-43	08:50	28°17′	S .	
11	MOON	5-15-43	04:15	62°07′	S	
12	SPICA	5- 5-43	05:45	55°29′	S	
13	REGULUS	5- 1-43	03:45	79°26′	S	
14	ALTAIR	5-20-43	10:31	66°00′	S	
15	ALKAID	5-15-43	07:24	69°43′	N	
16	NUNKI	5- 1-43	15:14	76°13′	S	
17	MIZAR	5-20-43	07:58	76°38′	N	
18	DENEBOLA	5-10-43	05:00	48°47′	N	
19	RASALAGUE	5-15-43	12:13	71°11′	N	
20	ALPHECCA	5- 5-43	09:30	62°47′	N	

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YOU NAVIGATE TO HONOLULU

THE following notes, experiences and flight data are based upon several actual trips made by the writer. Engine-performance curves, graphs and other factors have been altered, and essential data has been recomputed and brought up to date.

Regardless of these changes, the conditions of flight, information cited and general procedure followed are essentially the same as will apply to any long-range ocean flight and may, therefore, be considered accurate examples.

It is hoped the following description of an actual flight will furnish a more workable con-

cept of the practical application of aerial navigation principles and methods described in earlier chapters.

THE FLIGHT

A phone call from the dispatch office on a May afternoon advises that you will be the navigator on a PBY scheduled for delivery to Honolulu the next day.

Next morning you are up early gathering your gear. By nine o'clock you are busy in the Airway's Navigation Office, checking over all equipment needed for the flight. You have, of course, kept it constantly ready, stowed in a

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sturdy briefcase for compact handling, but you know it always pays to make a final check. You remember well the navigator who failed to take along a current Air Almanac. Two hundred miles at sea he discovered, much to his discomfort, that the date of his Almanac had expired. Fortunately, another aircraft was nearby, on the same flight, and so by means of inter-plane radio communication, the navigator of the other aircraft dictated enough data from a current Almanac to enable him to compute celestial fixes and so continue enroute.

Equipment Check—You check your equipment to make certain the following items are included:

- 2 Air chronometers (very accurate watches).
- 1 Aircraft octant (including spare batteries and bulbs).
 - 1 Air Almanac (correct date).
- 1 Set H.O. 214 tables (one volume for each 10° of latitude to be flown).
- 1 Weems plotter (for drawing courses and lines of position).
 - 1 Pair 6" dividers.
 - 6 Pencils (sharpened).
 - 1 Scratch pad.
- 1 *Notebook* (for recording celestial sights and observations).
 - 1 Flashlight.
 - 1 Roll of masking tape (to hold charts down).
- 1 Operations Manual (containing the graphs and engineering data concerning engine performance and fuel consumption, and navigation aids such as sunrise and sunset tables, courses and distances*, radio aids*, radio station frequencies and identification signals*, schedule of time ticks, radio weather codes* and other essential information).
- 1 Flight Manual* (containing all detailed information needed regarding check points such as islands and reefs, landing areas, air bases and other facilities along the intended or alternate routes).
- 1 Set of charts (including plotting and detail charts of all islands and landfalls along the proposed route, including possible alternates).

Note: A plotting chart is most practical when its scale is small (¾ inch to 1 inch equal to 1° of longitude at the equator), because this small scale permits plotting the course for an average point-to-point flight (usually not more than 2000 miles), whereas a larger scale would necessitate changing charts. Furthermore, a small scale chart provides a clearer picture of the aircraft's track, ground speed and drift, and fixes plotted are accurate within a few miles—a negligible error in long-range flying.

Chronometer Check—Before placing the equipment aboard your aircraft, you first wind your chronometers and set them to correct Greenwich civil time (GCT). They are set to coincide with the master watch, kept in the navigation office, and as an additional check, as soon as possible after take-off, the radio operator will pick up a time tick so you may make absolutely certain your watches are set correctly. This is very important, as four seconds of chronometer error will result in an error of one minute of longitude (one mile at the equator).

Later in the morning you board the PBY and arrange your equipment for the flight. With masking tape, you fasten the chart you are going to use to the navigator's table. The rest of the charts you stow in a drawer, and the navigation books are put in handy places for use when needed. You then set the aircraft's watches to GCT and altimeters to zero.

Pre-forecast Check—The aircraft being delivered is a Consolidated Vultee Catalina type flying boat. Take-off has been scheduled for late in the afternoon in order to arrive in Honolulu sometime after sunrise tomorrow. You are not yet certain that the flight will be made today because if the weather forecast is not favorable, the flight will have to be cancelled out. Therefore, you obtain a preliminary forecast which gives you the weather and anticipated flying time, both of which look promising. So you prepare for pre-flight check.

The forecast, to be described in more detail later on, is the weather report obtained from the meteorologist (Weather Bureau in peacetime and the Army or Navy department during war). The forecast includes predicted



^{*}These items are restricted during war, and can be obtained by the captain from Army or Navy officials only, immediately prior to departure.

weather, winds, clouds and fronts along the proposed route. Applying the force and direction of the wind to the true air speed of the aircraft, an estimate is then made of the average ground speed, and total number of flying hours. If head winds were predicted of such force as to result in the estimated total flying time being very nearly equal to the aircraft's total available fuel hours, the flight would be cancelled out, pending more favorable winds. For a Catalina, 18 to 20 hours is considered a good forecast; over 20 hours, a long forecast.

Pre-flight Check — By 11:00 A. M. the crew is ready to take your Catalina for its final check flight. You still won't leave if it isn't in perfect flying condition. It has had 12 hours of shakedown (flight test) and should be in good shape. However, this is your last opportunity to uncover faults, and if any remain, to have them corrected before departure.

With the crew on board, the captain takes the ship off the water and climbs to 5,000 feet where he levels off. Captain and co-pilot then conduct a series of tests to see if any faults can be shaken out-checking flying performance on first one engine and then the other, with both engines set at various manifold pressures (M.P.) and revolutions per minute (r.p.m.). Magnetos, de-icers, propeller-feathering mechanism and other devices are tested. It looks as though you have a "good airplane," as everything is running smoothly. These final shakedowns are important, as minor flaws revealed in these flights might develop into major failures in long-range flying, resulting in possible disaster for ship and crew.

Radio Compass Check in Flight — When the captain is satisfied that the aircraft is in good operating condition, you then check the radio direction finder loop for calibration error. This is not difficult when relative bearings (R.B.) are computed as outlined in the following procedure.

Fulfilling one of your duties as a navigator you select a small landmark—the South tip of South Coronado Island—and measure the correct magnetic heading between it and radio station KFSD, San Diego. Next, the magnetic headings to fly are computed, as well as the correct relative bearings for each 30° interval

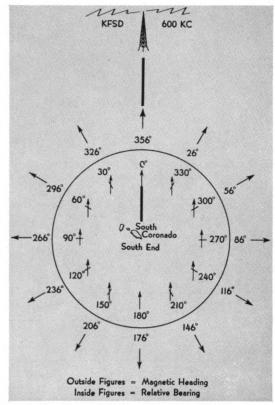


FIG. 157—RADIO COMPASS CHECK

from the first magnetic heading to the radio station, as shown in Figure 157.

To assist you in checking the radio direction finder, your captain steadies the PBY on each of the headings indicated on the diagram. At the instant the ship passes over the selected landmark, on each of the headings, he signals to the radio operator who then takes a relative bearing on KFSD while you double check the compass heading. Knowing the relative bearing, you then quickly determine the amount of calibration error, which equals the difference between the radio bearing taken and the correct relative bearing indicated on the diagram (Figure 157).

With the plane heading 266°, the radio operator took a relative bearing of 96°. By reference to the actual pre-computed bearing, this indicated at once that the direction finder was reading too large a value by 6°. Therefore, the calibration correction on this heading is minus 6°.



WEATHER FORECAST

Date 5-4-43

From San Diego To Honolulu Course 252° Plane Catalina GCT 2250

		ZONE 1	ZONE 2	ZONE 3	ZONE 4	ZONE 5
WE	ATHER	Clear	Clear	Ptly Cldy	Cldy	Ptly Shrs
	Туре	Sctd	Sctd	.4 Sc	.7 Sc Cu	.6 Sc Cu
DS	Ceil.	1000	1500	1500	2000′	2000*
сгоџрѕ	Tops	2000′	3500′	6500°	7500°	7000
0	Upper	х	х	Sctd 30,000'	Sctd 14,000	Sctd 14,000
	1000	310/12	320/12	X.	х	x
ND	5000	330/14	360/14	40/10	170/10	40/12
WIND	7000	320/12	360/14	120/10	310/14	10/7
	10,000	х	x	х	х	х

No pronounced Fronts along course.

San Diego—2230 to 0230 GCT, no lower clouds, no upper clouds, surface winds 290°/8 kts., visibility 5/10 smoky, sea smooth.

Terminal: Pearl Harbor—1700 to 1900 GCT May 5th, partly showers, .6 Sc Cu at 2000', tops at 7500', high clouds sctd at 14,000', surface winds 40°/12, visibility unlimited.

Alternate: Hilo—1600 to 1800 GCT May 5th, party showers, 6 Sc Cu at 1500', tops at 8500', high clouds sctd at 14,000', surface winds 40°/14, visibility unlimited.

Remarks-Flight Time Analysis at 7000, 19.8 hours to Pearl Harbor, 18.7 hours to Hilo.

Recommend a drift southward in early portion of flight since winds are more favorable to south of course.

Signed: Weather Officer

FIG. 158

Calibrating the radio direction finder is an important procedure, for if you can take radio bearings that are reasonably accurate, you will be able to use them to check celestial fixes, or, under proper conditions, to employ such bearings alone to fix the ship's position. You should be able, if necessary, to direct your aircraft to its destination without radio. However, pilots who are accustomed to radio and contact flying over land begin to feel a little worried after flying for ten or fifteen hours without seeing anything but water. At such times, a radio bearing which checks your celestial fix is an added comfort to the crew-and even to yourself. Such bearings are a comfort to the navigator because occasionally a wind will blow your aircraft into an unbelievable position, and though you take celestial sights as often as possible in order to catch these sudden shifts of wind, it is not unusual to be blown 50 miles off course between fixes. You know that your celestial fixes are usually accurate. Nevertheless, when both a celestial fix and a radio bearing check, even if the check establishes your position as off course, everyone on board feels more confidence in your ability.

By 12:00 noon, your check flight is over. Engines, aircraft and radio are in perfect condition; the crew is satisfied they have a "good airplane."

The engineer has elected himself food supply officer and is off to town to obtain a supply of provisions. Since there is nothing left to check on the aircraft, the crew is temporarily at liberty.

Final Forecast—By 2:00 P. M. you would usually be back at the Airway's office, but due to the war you check in at the Naval Briefing Office for final briefing and weather forecast. Briefing means you'll be given the latest confidential data bearing on the proposed route. This includes instructions for receiving and sending messages and weather reports via radio, information on air base facilities, let-down and approach procedures and other restricted information. You are shown the latest weather map, and given a copy of the forecast (Figure 158) which estimates your flight time as 19.8 hours. However, you will recalculate it yourself and then plot a flight graph of time and fuel consumption. Use of this graph in flight will enable you to determine very quickly if the aircraft is flying according to the estimated forecast. It will indicate whether engines are using too much fuel and, if so, whether you can make your destination, or whether you will have to turn back. The graph also indicates the point of no return (PN), or "splash point," the times of sunrise and sunset, and location of weather fronts. Sometimes, for multi-engine aircraft, when engine data is available, you plot a second curve on the graph to show the PN in the event one of the engines fails.

Note: This weather forecast was based upon the latest weather maps, which, in turn,

70115	DOUNDABLES	DISTANCE	cou	RSES
ZONE	BOUNDARIES	(Nautical Miles)	MAGNETIC	TRUE
1	San Diego to 120°W	153	237°	252°
2	120°W to 130°W	540	237°	252°
3	130°W to 140°W	555	237°	252°
4	140°W to 150°W	577	240°	252°
5	150°W to PCY (Pearl Harbor, Honolulu)	494	240°	252°
	Total Distance	2319		

FIG. 159—COURSE ZONES



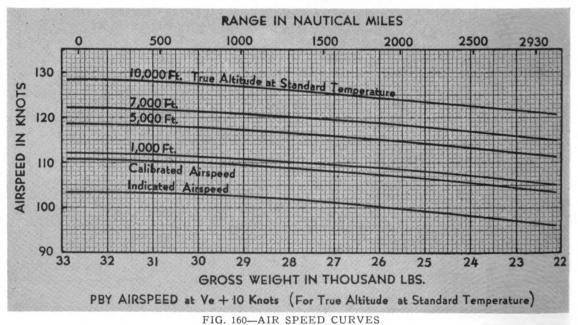
were based upon all available weather reports received from ships, aircraft and weather stations along the proposed route. Therefore, in order that following flights also may have the benefit of a good forecast, the navigator should carefully and conscientiously observe weather encountered in flight, and report correct weather information by radio.

Course Zones - Looking at the forecast again, note that it is divided into five zones. The report found below each zone provides weather and wind predictions for that particular zone. Weather forecasting, at best, is only an estimate, and since weather reports over vast water areas are few and far between, definite wind predictions cannot be given for every mile of the course. As a result, the weather forecaster has divided the various air routes into several basic segments called zones (see Figure 159). Various zone boundaries are employed. Sometimes the zones are an even 5° of longitude in width; on the other hand they may cover 10° of longitude, depending upon the purposes and procedures of those originating the forecast. However, the general practice is to allow the amount and accuracy of available weather information in each area to determine the width of the zone. Where available weather reports are numerous and accurate, the area covered by each zone is relatively small. If only a few reports are available, the area included is greater. Usually the weather forecast states the boundaries and areas of each zone. However, zones are practically of standard dimensions, and the Operations Manual which is part of your equipment furnishes this information for your proposed route.

Flight Time Analysis—Your next job as navigator is to analyze the forecast. Analyzing the forecast involves applying the wind predicted for each forecast altitude to pre-determined true air speeds and course, thus gaining an estimate of expected ground speeds and flying time in each zone. When the information is arranged in some such form as illustrated in Figure 161, it is called the Flight Time Analysis.

The predetermined true air speeds, which are computed for standard temperature, can be had by inspection of air speed curves, (Figure 160) contained in your Operations Manual.*

^{*}The Operations Manual contains a number of longrange cruising curves which have been computed by the aircraft manufacturer after years of research. These curves indicate engineering and flight data on long-range performance, fuel consumption, engine power settings (M.P. and r.p.m.), etc., for the aircraft under various conditions of gross weight, load and altitude. Of particular interest to the navigator are the air speed curves (Figure 160), and the fuel consumption curves (Figure



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YOU NAVIGATE TO HONOLULU

					FLIG	НТ	TIME	ANA	LYS	IS						
		2	ZONI	E 1	2	ZON	E 2	2	ZONI	E · 3	2	CON	E 4	7	ZONI	E 5
col	URSE		252			252			252			25	-2	252		
ZON	RE DISTANCE	153				540			555			5	77	494		
TOTAL DISTANCE		153		693		1248			1825			2319		19		
		TAS	G.S.	TIME	TAS	G.S.	TIME	TAS	G.S.	TIME	TAS	G.S.	TIME	TAS	G.S.	TIMI
ы	1000′	112	105	1:28	112	107	5:03	///								
5000		//8	115	1:20	118	122	4:26	117	126	4:25	116	114	5:04	115	125	3:57
ALTITUDE	7000′	122	117	1:19	122	126	4:17	121	128	4:20	119	111	5:12	118	121	4:00
4	10,000′												11			

FLIGHT PLAN

ALTITUDE	1000'	1000'	1000'	1000'	7000'
ZONE TIME	1:19	4:17	4:20	5:12	4:05
TOTAL TIME	1:19	5:36	9:56	15:08	19:13
GAS USED	175	500	805	1160	1425
GAS REMAIN					325

RETURN 2 ENGINES COURSE 72°

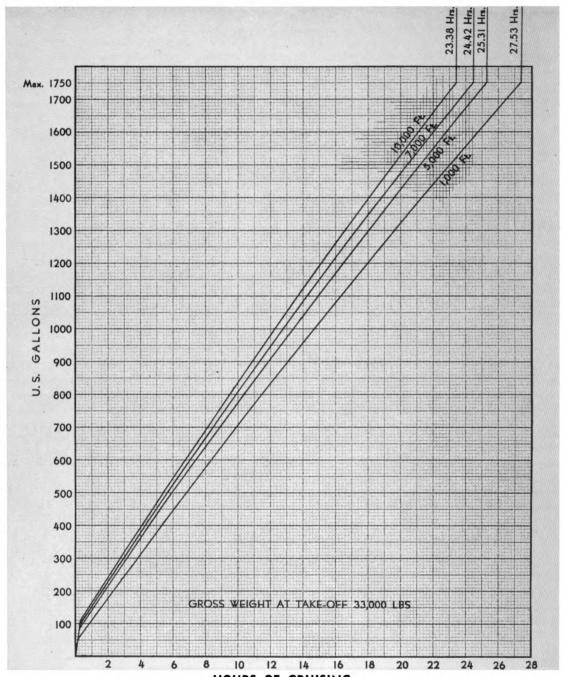
ALTITUDE: 7000' TOTAL AVAILABLE FUEL HOURS: 24.42 hrs. or 24 h. 25 m.

ZONE	T.A.S.	G.S.	ZONE TIME	TOTAL ZONE TIME	TOTAL FUEL HRS. MINUS TOTAL ZONE TIME	FUEL USED
1	115	119	1:17	1:17	23:08	1670
2	116	111	4:52	6:09	18:16	1365
3	117	110	5:03	11:12	13:13	10 30

FIG. 161

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HOURS OF CRUISING
PBY Fuel Consumption For Long Range Cruising Ve + 10 Knots
FIG. 162—FUEL CONSUMPTION CURVES

162), as these are necessary for long-range forecasting. Notice in Figures 160 and 162 that these curves are for Ve + 10 knots performance. Ve indicates the effective velocity (indicated air speed) at which the aircraft would have to be flown in order to make good maximum flying hours. Ve curves are used only for endurance flights be-

cause it has been proven that when there is a wind blowing, which is usually the case, greater range can be attained by increasing the power on the engines slightly in order to indicate an air speed 10 knots faster than V_e , hence $V_e + 10$ knots. For this reason $V_e + 10$ knots curves are generally used for all long-range flights.

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Flight Plan-You then carefully analyze the Flight Time Analysis to ascertain the most desirable cruising altitude, and begin to make out the Flight Plan (Figure 161). Normally, it is desirable to select that cruising altitude which will make possible the shortest flying time; however clouds, fronts, temperature and icing level may make it advisable to select a "slower" altitude, where safer, better flying conditions prevail. For today's Flight Plan you use 7000', because at this altitude you should be able to keep above the clouds and stay in clear weather all the way. Totalling the zone times gives you 19h13m, indicating that you actually have a 19.2 hour forecast and not 19.8 as stated by the meteorologist.

In order to complete the Flight Plan you refer to the $V_{\rm e}+10$ knots fuel consumption curves (Figure 162), also contained in the Operations Manual, and find, using the 7000' curve, the amount of fuel which would be consumed by the end of each zone. The flight plan now indicates that if the flight forecast is accurate, your PBY will use a total of 1425 gallons of fuel and have in reserve 325 gallons on arrival at Honolulu.

Return Flight Plan—A plan for the return flight also is prepared because this information is to be plotted on a flight graph (Figure 163) which provides an ideal method of establishing the amount of reserve fuel needed for safe operation, as well as the radius of action and point of no return.

Several steps are necessary in preparing the Return Flight Plan (Figure 161).

First, you re-compute the Flight Analysis for the first half of the flight, using:

- 1. Reciprocal course.
- 2. The forecast winds (Figure 158) at the altitude most favorable for the return course.
- Pre-determined true air speeds (Figure 160).*

Second, you total the zone times and find the length of time required to return to base from the end of zone one, zone two, and zone three.

Third, obtain the maximum flying time from the fuel consumption curve (Figure 162). In this case, your aircraft can fly 24.42 hours or 24h25m, as this is the time indicated at the end of the 7000' curve on which your forecast is based.

Fourth, subtracting the total zone time (time required to return to base from each zone) from maximum fuel hours, you find the total possible hours you could fly in order to reach the end of each zone, and still be able to reach your base.

Finally, using total flying hours, obtain from the fuel consumption curve (Figure 162) the total fuel that could be used to reach the end of each zone.

Flight Graph—With the flight plans completed, the final step is to plot the computed data in the form of a flight graph (called by many air navigators the "Howgozit"), which will permit a constant, clear check during the flight. The procedure for making the Flight Graph (Figure 163) is as follows:

- a. On a sheet of graph paper of convenient scale, establish a *course distance scale* along the lower edge.
 - b. Mark off the forecast zones as shown.
- c. Establish a fuel consumption scale along the left edge.
- d. On the zone lines, mark the total fuel used at the end of each zone (as computed in the Flight Plan) and draw in the fuel vs. miles curve. This curve provides the most important information found on the graph, as it indicates the distance flown by the aircraft with relation to fuel consumed.
- e. Establish a *time scale* along right edge. The scale, on this preliminary layout, should indicate only hourly intervals as the GCT take-off time will have to be known before the actual time scale can be established.

Note that in this instance the time scale is started above the fuel scale, to keep the fuel



^{*}Notice in Figure 160 that the air speed decreases as the range increases. This increase occurs because the aircraft is continuously losing weight as fuel is consumed, and as the weight decreases, flight efficiency increases. That is, the air speed and engine power can be reduced, resulting in less fuel consumption, while the aircraft will

continue to maintain the same cruising performance (Ve + 10 knots). Therefore, in order to obtain correct information from the air speed curves (Figure 160), and from the fuel consumption curves (Figure 162), you assume that the aircraft already has flown the first half of its maximum range prior to preparation of the Return Flight Plan.

AMERICAN AIR NAVIGATOR

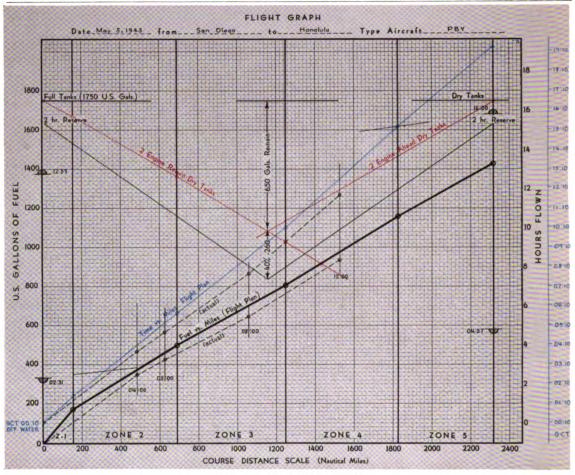


FIG. 163-FLIGHT GRAPH

curve and time curve (to be drawn) separated, thus permitting easier reading.

- f. On the zone lines mark the total forecast time to the end of each zone (Flight Plan) and draw in the *time vs. miles* curve.
- g. On the zone lines mark the total return fuel used to the end of each return zone (Return Flight Plan), and commencing at point of full tanks, draw in the *two-engine return dry tanks* curve. The intersection of this curve, extended, with the fuel vs. miles curve locates the PN.
- h. From the point of dry tanks (at destination), draw a line parallel to the fuel vs. miles curve. This line is the *two engine ahead dry tanks* curve. The point at which the two dry tanks curves intersect represents the absolute maximum amount of fuel the aircraft can consume and still return or go ahead to destination.

- i. Determine amount of fuel remaining at point where dry tanks curves intersect, and from this point, at a distance equal to 40% of the remaining fuel, locate a second point vertically beneath the point of intersection.
- j. Obtain from fuel consumption curve (Figure 162) amount of fuel required for final two hours cruising. Mark this amount on Flight Graph below full tanks and empty tanks points and draw in 40% to 2 hours reserve ahead and return curves. These curves represent safe flying curves, and any position below these curves would be considered safe.
- k. In airline operations it is especially important also to plot on the Flight Graph the maximum amount of reserve fuel required on arrival at destination. As an example, four hours reserve fuel is ample safe allowance for

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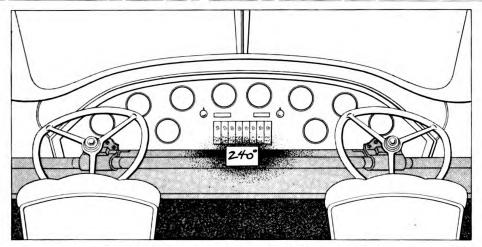


FIG. 164—HEADING MEMORANDUM FOR PILOT

your PBY. Plotting this amount on the Flight Graph you see from the relationship of this amount to the fuel vs. miles curve that you are carrying 75 gallons of fuel over and above the required reserve. Converted into cargo weight, 75 gallons of fuel is equivalent to approximately 450 pounds. In other words, the Flight Graph proves it would be safe to carry 75 gallons less fuel, thus allowing the aircraft to carry two or three extra passengers. It is easy to see that similar additional payloads on all flights would, in the course of a year, amount to many thousands of dollars additional income for the airline.

Note: The average time required to make up one of these flight forecasts and flight graphs is thirty to forty minutes, and its value is inestimable. An airline could not afford to neglect it, and its correct use in flight makes it practically impossible for an aircraft to run out of fuel except through mechanical failure.

Departure Clearance—3:30 P. M.—The copilot, radio operator and engineer are at the aircraft waiting for take-off. You and the captain are at the Airway's office receiving last minute instructions, customs papers, bill of health, clearance papers, cargo and mail manifests.

The flight clearance approved, you are on your way. With wide-open throttles your plane roars down the bay, rapidly picking up speed—70...80...90 knots. Gradually the spray stops flying past the windshield. The next

moment the ship is clear of the water, and the earth appears to drop away.

Off the Water—May 5, 1943—00:10 GCT. In the excitement of take-off you almost forgot to read the time!

The captain's first question will be, "What is our heading?" You have the answer ready for him, having worked it out in advance. (This and other vector problems will be solved on the computer to save time).

252° True Course —15° E Variation

237° Magnetic Course

+5° L Drift (from forecast wind—320°/12 knots)

242° Magnetic Heading

—2° E Deviation

240° Compass Heading to fly

You have found from experience that it is a good rule to write the heading on a slip of paper and stick it on the controls where the captain and co-pilot can see it easily (Figure 164).

By now San Diego is far behind. The plane is climbing steadily, higher and higher into the sky. Everyone is in excellent spirits.

00:29 GCT—Nineteen minutes from take-off—your aircraft is now leveling off at 7000' as per forecast. The captain is pulling back on the throttles, adjusting them and the propeller pitch so that the manifold pressure and revolutions per minute are for $V_e + 10$ cruising range, as per engine performance graph.



The reduced power now makes the engines relatively quiet. The engineer has changed the fuel mixture from full rich to automatic lean. The radio operator is sending in the departure time to the shore watch station.

Flight routine has begun.

Navigator's Flight Report—Your first job is to start filling out the Navigator's Flight Report (see example, Figure 166) to which you will refer each hour, filling in the hourly record. From this report you will check courses, positions, and make up the radio reports. After the flight is over it will be given to the Airway's office so they can keep a record of the flight.

In order to save time, the type of position is given a numerical designation as follows:

- 1. Dead Reckoning Position.
- 2. Approximate Fix (Single position line and DR, or radio bearings).
 - 3. Fix (Celestial or Visual)

Chart Preparation—Before starting to navigate it is advisable, in order to save time, to draw in the course line marked off in units of 100 nautical miles, and indicate the zone boundaries and forecast winds (Figure 165).

First Position Report-You are now ready to find the 01:00 GCT position. It is a common belief that an aerial navigator has to be extremely fast in his work. While it is true that the ability to calculate rapidly is certainly an asset to the navigator, accuracy and common reasoning are far more important. Navigation is not an exact science, particularly aerial navigation, but it does give an approximate position which is sufficiently accurate with relation to the aircraft's speed for all practical purposes. Bearing in mind the limitations of aerial navigation, it is the navigator's job to know which of the various navigational methods, or combination of methods, will enable him to most accurately determine the aircraft's position with the least effort.

The sun is setting in the West, and if an observation of the sun were taken, it would give you a single line of position which would serve as a fair speed check. However, during the climb you kept track of the indicated air speed, which averaged 98 knots. The indicated air speed now is 103 knots. Since the forecast wind force and direction usually is quite accurate for the first zone, and since you are less

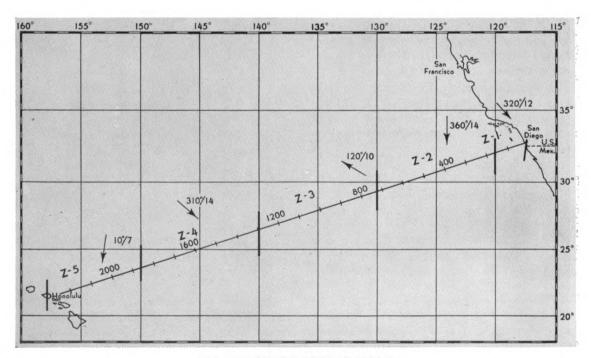


FIG. 165—CHART PREPARATION

		-			R.P.M.		1980	28.0 1980	0861	0861	1950	1950	1950	1930	1930	1930	1930	1930	1930	1930	1880	0881	26.0 1880	1880			
					M.P.		28.0	28.0	28.0	28.0	270	270	270	26.5	26.5	26.5	26.5	26.5	26.5	26.5	26.0	26.0	26.0	26.0			
				TH	MEIC	33,000					30,912			29,574 26.5							26,556 26.0						
	T	AN	3R	TE .	Remain	1750 33,000		1630	1553	1477		1327	1253	6411	1105	1032	959	188	918	246	676	809	540	473	370		
	CO-PILOT	RADIOMAN	ENGINEER	GASOLINE	Used			120 1630	197 1553	273	348 1402	423 1327	164	571	645	218	166	863	466	1001	1074	1142	1210	1277	1380		
	00	RAI	ENG	6.4	Rate Cons.				17	94	75	75	44	74	44	23	23	77	11	2	20/	89	89	67	103	T	
				NCE	To Go F	23/9	2286	2225	2099	6961	_	-	1544	4041			6101	899	789	699	249	414	284	159			
				DISTANCE	Flown 7	3	33 2	942	2202	350 /	485 1834	630 1689	775	9151	1090	1951	/300/								2319		
				ED	ELAPS		61:0	0:00	1.50	2.50	3.50 4	4:50	5:50	6:50 9	7:50/060/259	8.50 1195 1124	9:50	10:50 1420	11:50 15:30	12:50 1650	13:50 1770	128 14:50 1905	128 15:50 2035	16:50 2160	60.81		
H		~	J	- a	SPEE	401		117	127	127	128	139	139	139	140	140	126	120 1	113/	11611	122 /	28/	28/	128/	'	1	-
POR	Z	ATOI	CALL	-	e GROUI	12/		12/	181	181	23 /	20 /	/ 9/	191	/8/	17/	1 10	05/	12/	14/	15/	191	/9/	191		+	-
FLIGHT REPORT	CAPTAIN	NAVIGATOR	RADIO	WIND	Dir.	310			09		09		20	04	100	20	30					0/	0/	0/			-
IGH	CA	NA	RA	Comp		2403		240 320	240 360	240360	240360	240		237		236	236	236 300	2E 236 280	245 310	245 340	245	249	249			
					DEVIAT	2E :		2E ;	2E 2	2E 2	-			2E ;	2E 3	2E 2	W	2 E	ZE .	2E	ZE	2E	2 E :	ZE ;			
OR				NOI	TAIAAV	15.6		13E	15E	15E	15E	15E		34/	146	14E		13E	13E	12E	12E	12E	12E	118			
NAVIGATOR'S				Trie	Head	257		257	257	257	257 15E 2E	257 ISE	253		253 14E	252	252 IHE	251 13E	251	259	259	259	263	_			
NAV		7		Т	DKIE	5.4		5.4	78	78	101	54		0	38	0	3 R	11	34	5.4	76	76	7.4	79			
_		DESTINATION		Course	or Track	252		252	249	249	247	252	253	253	236	252	255	250	248	254	252	252	256	256			
	<u>н</u>	LIN	H H	Temp	°C.		75	75	75	46	16	*+		0/+		0/+	0/+		110	01+	110		0/+	0/+			
	DATE	DES	TYPE		JTITJA		2000	2000	2000	2000	2000		2000			7000		9000 +10	7000 110	7000	7000 +10	7000 +10	2000 +10	7000 +10			
				ED	TAS			57	123	123	123	123		-		133	-		123	122	122	122		122			Ī
				AIR SPEE		00:		011	011	011	011	0//	011	601	601	601		601	109	801	108	801	301	108			
				AIR	IAS CAS	SAN DIEGO		103	103	103 110	103		183	102	102	102	102	102	102	101	101	101 108	101				
					TYPE	-	CLIMB	-	N	_	m	3	-	-	10	_		-	₁	1	5			7	NON		-
			0.	POSITION	Long.	WATER		32-15/18-55	03:00 31-25 121-10	03:00 30-40 /23-30 /	0029-35 125-55 3	05:00 28-55/28-40	06:00 28-15 131-10	07:00 27-35 /33-40	136-20 3	138-50	10:00 26-15 140-45 3	11:00 25.35 /42-50 1	12:00 24-45 144.35	04-941	14:00 23-35 148-45 3	15:00 22-55 151-00 3	16:0022-20 153-15	17:00 21-50 155-25	ON WATER HONOLULU		
	TRIP NO.	NI	PLANE NO.	POS	Lat.	11	END OF	12-15/	1-25	04-0	9-35	8-53	8-15	7-35	7-15	6-35	6-15	15.35	4-45	4-15	3-35	12-55	2.20	11-50	ON WA		1
	TRIP	ORIGIN	PLA	2774	G.C.T.	00:10 OFF	00.29		2:00 3	3.00	04:003	00.50	00.90	7.00 2	08:00 27-15	08:00 26-35	00:0	00: /	2.00.2	13:00 24-15	4.00 K	5:00	6:00	7:00	18:29		1

FIG. 166

than an hour out, a DR position will be just as accurate 'as a celestial line of position, and easier to determine.

Referring to the Performance Manual (Figure 160), the air speed calibration correction is found to be +7 knots. Therefore, the calibrated air speed during the climb was 105 knots, and now is 110 knots. The temperature, read off the instrument panel, is +5°C. Using these calibrated air speeds, and with the computer set at +5°C and at about 3000′ for the climb and 7000′ for your present altitude, you find the true air speeds flown to be 109 knots on the climb and 123 knots at 7000′.

Applying the forecast wind (Figure 158) to the true air speeds (using the computer) gives the following ground speeds:

104 knots—Ground speed during climb 118 knots—Ground speed at 7000'

Using this information you compute the distance flown as follows:

- a. 00:10 Off water 00:29 End of climb
 - 19 minutes elapsed during climb
- b. 19 minutes @ G.S. 104 knots = 33 NM
- c. 00:29 End of climb
 - 01:00 Time of position desired

31 minutes elapsed since climb

- d. 31 minutes @ G.S. 118 knots = 61 NM
- e. 33 NM
 - +61 NM

94 NM = Distance flown along course from point of departure to DR position at 01:00 GCT.

Measuring along the course a distance of 94 miles from point of departure, you find that the 01:00 GCT DR position is latitude 32°15′ North, longitude 118°55′ West (Figure 168).

Fill in the Navigator's Flight Report (Figure 166).

DR Ahead—As it is good practice always to know the airplane's estimated position at least one or two hours in advance, you step off the DR positions for 02:00 and 03:00 o'clock GCT. Both of these positions will be in Zone 2. Until you have a fix to definitely determine the wind, refer back to the forecast wind which is 360°/14 knots. Since the true air speed is



FIG. 167-LEVELED OFF AT 7000'

still 123 knots, and course 252°, you obtain a ground speed of 127 knots and drift of 6° left.

Next, using the mid-latitude scale (Figure 168) opposite the distance to be measured, set the dividers to 127 knots ground speed and step off two points from the 01:00 position. Mark these two points 02:00 DR and 03:00 DR respectively. The actual position of the plane at these two times will probably be south of the course since you are only allowing 5° left drift. However, these are only estimated positions to be revised later when more exact information is found.

01:48 GCT—The radio operator is listening to KFSD, San Diego, so you decide to take a radio bearing which will give you a good check on the drift, as the station lies directly on the course.

A radio bearing taken at the aircraft is the relative bearing of the radio station measured clockwise from the nose of the aircraft. Therefore, at the instant the radio operator takes the bearing of the radio station, he signals and you read the compass heading.

He finds the bearing to be 163°, and the compass heading which you simultaneously noted was 241°. Checking the radio calibration graph you find a correction of +7° for a relative bearing of 163°, making the correct relative bearing 170°.

The next step is to find the true bearing (Figure 169) to which the Mercator correction is then applied in order to obtain the Mercator bearing. This procedure is as follows:

YOU NAVIGATE TO HONOLULU

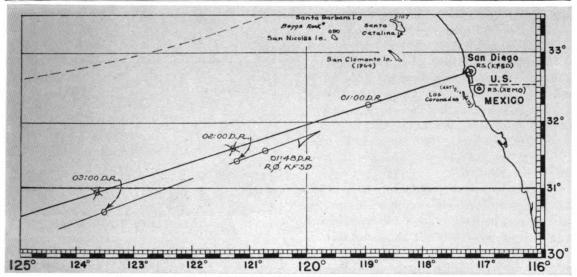


FIG. 168-01:00, 02:00, AND 03.00 GCT POSITIONS

241°	Compass heading
+ 15° E	Variation (found on chart)
256°	Magnetic heading
+ 2° E	Deviation (from deviation card)
258°	True heading
$+170^{\circ}$	Correct relative bearing
428°	
-360°	
68°	True (great circle) bearing of KFSD
+ 1°	Mercator correction
69°	Mercator bearing of KFSD
	from aircraft

The reciprocal of 69° then is plotted on the chart from KFSD, and a DR position established on the bearing line for 01:48, the time the bearing was taken (Figure 168).

You notice that the position thus obtained is about 12 miles south of the course. Assuming that the radio bearing is correct, you conclude that the wind has changed. On measuring the track made good from departure, you find it to be 249°, or 3° less than the track you intended to fly. Therefore, the drift has been 8° left instead of the 5° left you allowed.

To be 12 miles off course is not considered serious in aerial navigation, and since

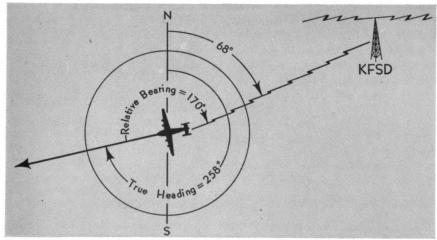


FIG. 169—COMPUTING RADIO BEARING FROM KFSD

the forecast recommended drifting south of the course for more favorable winds, you decide to hold the same heading (240°) until a more definite fix is established. Also to be considered is the forecast wind shift in the next zone which will tend to blow the aircraft back on course.

Advancing the 01:48 position to 02:00 GCT (Figure 168), you fill in the Navigator's Flight Report (Figure 166), entering the forecast wind, track made good and temperature, which now is $+6^{\circ}$ C.

You now re-establish the 03:00 position and fill in the Navigator's Flight Report for that time. The data (except for latitude and longitude of position) will be identical with that found for the 02:00 report, as there will be no more fixes until the stars are visible.

(Erase the previously estimated 02:00 and 03:00 DR positions).

Using the information on the Navigator's Flight Report sheet, you now prepare the Radio Weather Report using the information obtained at briefing, carefully noting the prevailing weather conditions, especially cloud formations and temperature.

Next, you refer to the Flight Graph (Figure 163) and fill in the GCT scale for the time vs. miles curve, with the GCT time of take-off as starting point. Then you find in the Air Almanac the times of sunrise and sunset for both San Diego and Honolulu, and mark them on the graph as illustrated, using the time and distance scales. Connecting the two sunset and sunrise points with a ruler, you draw short lines where the ruler crosses the time vs. miles curve. These lines indicate the approximate time and position along course at which you may expect sunset and sunrise to occur. They also indicate the duration of night flying. Your curve shows that sunset will occur at about 02:50 GCT.

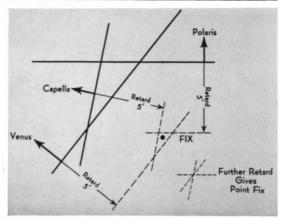


FIG 170-ANALYZING YOUR FIRST FIX

03:00 GCT-The sun has set and the stars are beginning to be plainly visible. You study the sky to determine which of the celestial bodies will afford the best fix. Venus is the first body selected because it is nearly ahead and very bright, thus serving as an excellent speed line sight. (Speed is most important to establish at this time, as it will help check the fuel consumption). Because it is also desirable to know the aircraft's definite position, Polaris, which is easiest to compute, is selected for a latitude and course check. Then a third celestial body, Capella, whose position line will cross the other two at a good angle, is selected to check the other two position lines and make a good three-line fix.

Next, you select a comfortable spot in the aircraft, usually the pilot's or co-pilot's seat, where you can easily observe all three bodies.

Adjusting the octant to the body's approximate altitude, you observe Polaris first, since it is the least brilliant of the three bodies and most difficult to sight in the octant. Then, Capella is shot and, last, the speed sight, Venus.

Their altitudes measured, you proceed to find the resultant lines of position (by H.O. 214 in this case).

POLARIS GCT 03h12m15s		
		269°37′
		0°35′
GHAT	=	270°12′W
DR Long.	=	124°12′W
ILIAM		146° W

$$H_{S}$$
 = 29°51′
Ref. = -1′
 H_{O} = 29°50′
Corr. LHA Υ = +30′
Latitude = 30°20′N

CAPELLA				$H_{\mathbf{S}}$	=	35°39′
GCT 03h15m07s				Ref.	=	-1'
301 00 10 01		269°37′		H_{0}	=	35°38′
		1°17′		$H_{\mathbf{c}}$	=	35°47.7′
		281°53′		a	=	9.7' away
GHA		552°47′ —360°			-	
GHA	_	192°47′		$\triangle \mathbf{d}$	=	.14' (x 4' = .6')
Assumed Long.		27 T. 17 J. 18 1		H	=	35°48.3′
	-			$\triangle d$ corr.		—.6 ′
LHA Assumed Lat.			Lat. 30° N Dec. 46° N	$H_{\mathbf{c}}$	=	35°47.7′
Dec.		45°56′N	Same name	Az	=	N 52.5°W

VENUS

$$^{\circ}$$
 Hs
 $= 32^{\circ}47'$

 GCT $03^{h}18^{m}07^{s}$
 Ref.
 $= -1'$
 $187^{\circ}44'$
 $^{\circ}$ Ho
 $= 32^{\circ}46'$
 $^{\circ}$ GHA
 $= 189^{\circ}46'$
 $^{\circ}$ Hc
 $= 32^{\circ}58.6'$

 Assumed Long.
 $= 124^{\circ}46'$ W
 $^{\circ}$ Δd
 $= .35 (x 15' = 5.2')$

 LHA
 $= 65^{\circ}$ W
 H
 $= 32^{\circ}53.4'$

 Assumed Lat.
 $= 30^{\circ}$ N
 $= 32^{\circ}53.4'$

 Dec.
 $= 25^{\circ}15'$ N
 Dec. $= 25^{\circ}$ N

 Same name
 Hc
 $= 32^{\circ}58.6'$

 Az
 $= N 78^{\circ}$ W

You then plot these three lines of position on the chart (Figure 171), Venus first, then Capella and finally Polaris, advanced to give a fix at 03:18 GCT, the time at which Venus was observed.

Analyzing Fix—You notice that the three position lines form a small triangle, establishing, for all practical purposes, the aircraft's position for the time of the fix as being in the center of the triangle. However, the careful navigator analyzes each of his fixes to determine the reasons, if any, why he did not get a point fix. Rechecking your work carefully you find no mathematical errors. It occurs to you, therefore, that the octant may have some instrument error not accounted for.

Checking the position lines (Figure 170), you quickly see that if each was retarded along its azimuth line, the triangle would be reduced

in size, eventually becoming a point fix. But if these lines were so retarded, you would be presuming that the error was entirely due to unknown instrument error, and that all of your sights were accurate. You feel, however, that, actually, the Polaris sight was somewhat inaccurate since it was dim and consequently difficult to observe. Therefore, you estimate the amount of instrument error as 5' and retard each of the lines by this amount. The resulting triangle is quite small, although lying outside the original triangle, but should much more accurately represent your true position.

This fix shows you to be 30 miles south of the course, making good a track of 247° with a ground speed of 128 knots and drift 10° left. Setting this up on the computer against true air speed you determine the wind to be 360°/23 knots.



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Since the speed has increased, you are getting the more favorable wind forecast by keeping south of the course, so you decide to hold the same heading. Advancing this fix to 04:00 GCT on the new course of 247°, at a ground speed of 128 knots, you fill in the Navigator's Flight Report (Figure 166) and make up the Radio Weather Report so it may be sent in on the hour.

Referring to the Flight Graph (Figure 163), you then plot in the actual data in dotted lines alongside the pre-computed curves. This information for 04:00 GCT is as follows:

Time vs. Miles Curve
Time 3h50m
Distance 485 NM
Fuel vs. Miles Curve
Fuel 348 gals.
Distance 485 NM

Since both of these actual curves fall below the estimated curves, the ship is making better time and using less fuel than was forecast. 04:30 GCT—Having just eaten a tasty steak sandwich which the engineer cooked up in fine style on the electric grill, you are feeling 100% better. By now members of the crew have settled down to the definite routine of a long-range flight. The motors drone monotonously as you fly on and on, steadily and surely eating up the miles between San Diego and Pearl Harbor. There is little feeling of forward movement when flying, especially at high altitudes or at night. In a train you can note your movement by watching telephone poles whiz by—but there are no phone poles up here!

Anxious now to check up on the 10° left drift you still are allowing for, you scan the sky to see what stars are available for a sight. Though it is beginning to cloud up, there are still plenty of stars out so you decide to shoot Polaris once more for a drift check. Since it is always good policy to select three bodies and plot a definite fix while you are at it, you also shoot Regulus for a speed check and Capella to complete the fix.

POLARIS

GCT
$$04^{h}36^{m}07^{s}$$

$$\begin{array}{rcl}
& & 289^{\circ}41' \\
& & & 1^{\circ}32'
\end{array}$$
GHA Υ = $291^{\circ}13'W$
DR Long. = $127^{\circ}30'W$

$$LHA \Upsilon$$
 = $163^{\circ}43'W$

$$H_{S}$$
 = 28°2 $^{\prime}$ I. C. = -5 $^{\prime}$ Ref. = -1 $^{\prime}$ Ho = 28°23 $^{\prime}$ Corr. LHA γ = +45 $^{\prime}$ Latitude = 29°08 $^{\prime}$ N

Hs

Az

CAPELLA

GCT 04h39m07s

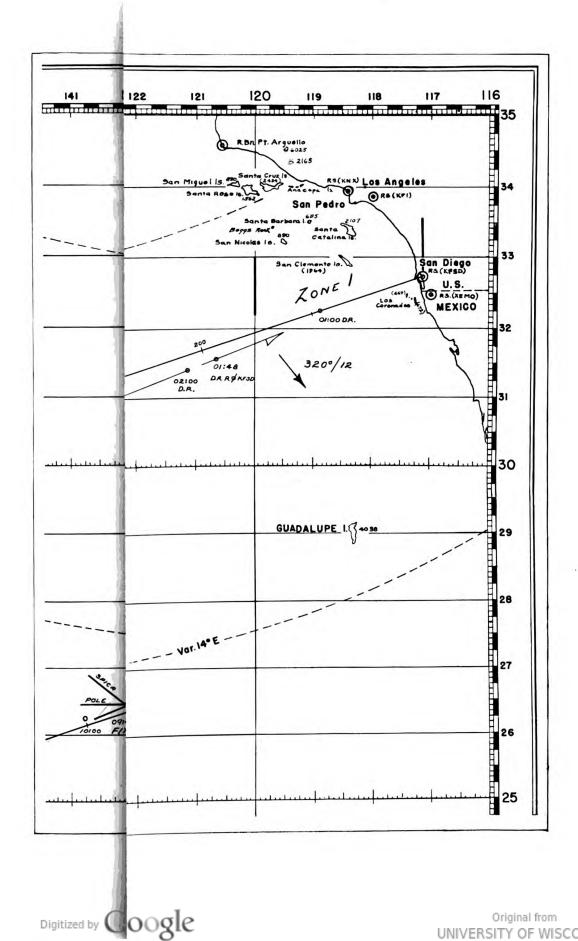
$$\begin{array}{c} 289^{\circ}41' \\ 2^{\circ}17' \\ 281^{\circ}53' \\ \end{array}$$

$$\begin{array}{c} \text{GHA} = 573^{\circ}51' \\ -360^{\circ} \\ \end{array}$$

$$\begin{array}{c} \text{GHA} = 213^{\circ}51' \\ \text{Assumed Long.} = 127^{\circ}51' \\ \text{W} \\ \text{Assumed Lat.} = 29^{\circ} \\ \text{N} \\ \text{Dec.} = 45^{\circ}56' \\ \end{array}$$

I. C.	=	—5'
Ref.	==	—2'
H_{0}	=	23°05.0′
Hc	=	23°00.2′
a	=	4.8' toward
$\triangle \mathbf{d}$	_	.32 (x 4' = 1.3')
H	=	23°01.5′
$\triangle d$ corr.		—1.3 ′
Нc	=	23°00.2′

N 48.8°W



REGULUS			$H_{\mathbf{S}}$	-	69°00′
GCT 04h42m07s			I. C.	=	—5'
GC1 04"42"07°	292°11′		Ref.	=	0'
	0°32′		H_{0}	=	68°55′
	208°40′		Hc	=	68°46.8′
GHA =			<u>a</u>	=	8.2' toward
GHA =	-360°		$\triangle \mathbf{d}$	=	.82 (x $15' = 12.3'$)
			H	=	68°34.5′
Assumed Long.			$\triangle d$ corr.		+12.3'
LHA = Assumed Lat. =	14° W 29° N	Lat. 29° N Dec. 12° N	IIc	=	68°46.8′
Dec. =	. 12°15′N	Same name	Az	=	N 139.6°W

These three lines of position crossing in a point fix prove that you correctly analyzed the last fix, and that your octant actually has an instrument error of about 5'.

Measuring the track and ground speed from the last fix indicates that the wind is shifting around, as forecast.

Advancing the fix to 05:00 GCT you fill in the Navigator's Flight Report, using the track and wind found. Then, after compiling the Radio Weather Report, you plot in the actual data on the Flight Graph.

The temperature has dropped to $+4^{\circ}$ C. and the sky now is overcast, making it impossible to take any more sights, so you estimate the 06:00 and 07:00 positions (Figure 171).

Since the temperature has lowered, you are probably passing through a mild front which is the reason for the wind shift. Knowing the wind is shifting, you estimate it as 70°/16 knots. Laying out a new course to your destination (253°) you fill in the 06:00 GCT Navigator's Flight Report. Calculating a no-drift heading, you advise the captain to alter compass heading to 237°, which takes into account the change in variation.

06:45 GCT—The temperature has risen to +7°C. The sky is still overcast so you use the 07:00 DR position to fill in the Navigator's Flight Report and Radio Weather Report, using estimated wind.

07:10 GCT — The temperature is now +10°C, and the stars are starting to break

through the clouds. It is possible to take a quick sight between cloud breaks. However, the horizon is rapidly clearing so you decide to wait a few minutes and take a good fix when the sky clears.

07:20 GCT—It is nearly clear, so you start shooting, as you are anxious to obtain a speed line in order to check fuel consumption. You are nearing the PN and a good fuel vs. distance check is necessary in order to determine definitely if you have sufficient fuel to continue to your destination.

This decision as to whether to continue to destination or to turn back is a very important one, and it should be based upon the most reliable information obtainable. Actually, the decision itself will be up to the captain, but he will have to rely largely upon the data with which you supply him. It behooves you, therefore, to keep a very accurate check on ground speed, winds encountered and fuel consumed, so that when it becomes time to decide there will be no cause for hesitation. The more complete and accurate your information, the easier will be the captain's decision, and the faster he can act. The more closely you approach the PN, the more critical becomes the time element. A delay of even a few minutes in acting can sometimes mean the difference between a safe arrival and a forced landing at sea.

So far your fuel consumption has not been excessive, but your proximity to the PN makes it important to have a final check. Accordingly, you work out the following sights:



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SPICA			$H_{\mathbf{S}}$	=	51°24′
GCT 07h20m07s			I. C.	=	—5'
GC1 0/"20"0/"	332°18′		Ref.	=	0'
	02'		H_{0}	=	51°19′
	159°27′		Нc	=	52°01.3′
GHA	= 491°47′		a	=	42.3' away
CHA	$=\frac{-360^{\circ}}{131^{\circ}47'}$		$\triangle \mathbf{d}$	=	1.0 (x 8' = 8.0')
Assumed Long.			H ^ 1	=	51°53.3′
LHA	= 3° E	Lat. 27°N	∆d corr. H c		$\frac{+8.0'}{52^{\circ}01.3'}$
Assumed Lat.		Dec. 11°S	116		32 01.3
Dec.	$= 10^{\circ}52'S$	Opp. names	Az	=	N 175.2°E

ARCTURUS		$H_{\mathbf{S}}$	=	74°10′
GCT 07h23m07s		I. C.	=	—5'
der 0/ 25 0/	332°18′	Ref.	=	0'
	0°47′	H_{0}	=	74°05′
	146°44′	$H_{\mathbf{c}}$		74°19.2′
GHA	= 479°49′	a	=	14.2' away
GHA	$=\frac{-360^{\circ}}{119^{\circ}49'}$	$\Delta \mathbf{d}$	=	.52 (x $1' = .5'$)
Assumed Long.	= 134°49′W	H		74°19.7′
LHA	= 15° E	Lat. 27°N △d co	rr.	
Assumed Lat.	$=$ 27 $^{\circ}$ N	Dec. 19°30′N Hc	=	74°19.2′
Dec.	= 19°29′N	Same name Az	=	N 115.4°E

REGULUS				$H_{\mathbf{S}}$	=	43°09′
GCT 07h26m07s				I. C.	=	—5'
GC1 0/*20*0/*		332°18′		Ref.	=	—1 ′
		1°32′		H_{0}	=	43°03.0′
		208°40′		Hc	=	42°45.8′
GHA		542°30′ -360°		a	=	17.2' toward
GHA	_			$\triangle \mathbf{d}$	=	.44 (x 15' $=$ 6.6')
Assumed Long.				H	=	42°39.2′
LHA	=	48° W	Lat. 27°N	$\triangle d$ corr.		+6.6′
Assumed Lat.	=	27° N	Dec. 12°N	$H_{\mathbf{c}}$	=	42°45.8′
Dec.	=	12°15′N	Same name	Az	_	N 98.8°W

Once again analyzing the fix (Figure 171), it becomes apparent that moving each of the lines slightly away from the body along the azimuth line will result in a point fix at the center of the triangle. The small triangle probably is due to a slight personal error in observation, as most of your sights are fairly close.

07:50 GCT—You find you are making good a track of 256° true from the last fix with wind 100°/18 knots, resulting in 3° right drift. Since the forecast has proved nearly accurate, you assume the wind will continue shifting around to the north. You decide, therefore, to fly a no-drift heading, parallel to the original course of 252°, estimating the same ground speed. You then advise the captain to alter compass heading to 236° which should keep the aircraft south of the course.

Advancing the fix to 08:00 GCT, you fill in the Navigator's Flight Report, Radio Weather Report and plot the actual position and fuel consumed on the Flight Graph. The graph indicates that you are using less gasoline than was estimated, and that it will be safe to continue to Honolulu.

09:00 GCT—You feel quite sure of your position, and since you have been busy the last hour catching up on all radio and weather reports, you take time out to cook up a can of soup and some coffee. You then fill in the 09:00 DR position on the Navigator's Flight Report.

09:30 GCT—It is time now to obtain another fix. Your previous fix included a good speed line, which afforded an accurate check on the distance flown—hence average ground speed—and the fuel-distance relationship. For the present, therefore, you are satisfied with the information you have regarding speed and distance. It now seems advisable to check the aircraft's position with reference to the course line, so you take another series of sights as follows:

POLARIS

GCT
$$09^{h}34^{m}07^{s}$$

$$\begin{array}{rcl}
& 4^{\circ}53' \\
& 1^{\circ}02' \\
& \text{GHA } \Upsilon &= 5^{\circ}55' \\
& +360^{\circ}00' \\
& \text{GHA } \Upsilon &= 365^{\circ}55'W \\
& \text{DR Long.} &= 139^{\circ}55'W \\
& \text{LHA } \Upsilon &= 226^{\circ} & W
\end{array}$$

$$H_{S}$$
 = 25°41′
I. C. = -5′
Ref. = -1′
 H_{O} = 25°35′
Corr. LHA Υ = +57′
Latitude = 26°32′N

ANTARES

$$\begin{array}{lll} \text{Hs} & = & 34^{\circ}02' \\ \text{I. C.} & = & -5' \\ \text{Ref.} & = & -1' \\ \text{Ho} & = & 33^{\circ}56' \\ \text{Hc} & = & 34^{\circ}15.5' \\ \text{a} & = & 19.5' \text{ away} \\ \hline \triangle \text{d} & = & .93 \text{ (x 18'} = 16.7') \\ \text{H} & = & 34^{\circ}32.2' \\ \triangle \text{d corr.} & & -16.7' \\ \text{Hc} & = & 34^{\circ}15.5' \\ \text{Az} & = & \text{N 158.1}^{\circ}\text{E} \end{array}$$

SPICA	$H_{\mathbf{S}}$	$= 44^{\circ}36'$	
GCT 09 ^h 40 ^m 07 ^s 7°23' 02' 159°27'	I. C. Ref. Ho Hc	= -5' = -1' = 44°30.0' = 44°44.1'	
$GHA = 166^{\circ}52'$	а	= 13.9' awa	y
Assumed Long. = 139°52′W LHA = 27° W Assumed Lat. = 26° N Dec. = 10°52′S	Lat. 26°N Dec. 11°S Opp. names △d H △d corr Hc Az	= .82 (x 8' = 6.6) $= 44°37.5'$ $+6.6'$ $= 44°44.1'$ $= N 141.2°W$	

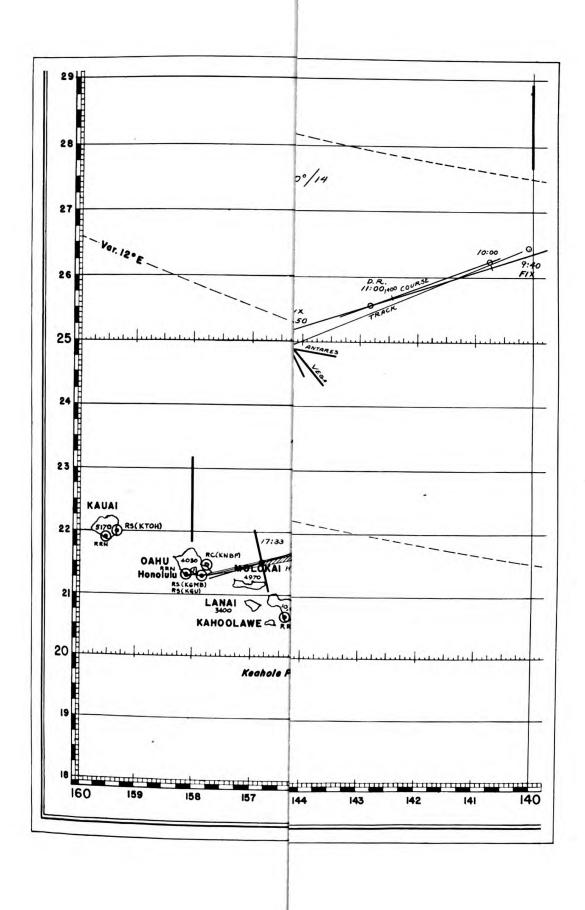
Checking the track made good (Figure 171), you find the aircraft is still drifting 3° to the right; however, the ground speed has decreased to 126 knots and the wind has shifted around to 130°/07 knots. You then advance the fix to 10:00 GCT and fill out the Navigator's Flight Report, using wind found and track made good.

Since the aircraft is a little North of the track, you continue to hold the same heading

but estimate the wind will continue shifting around gradually to the Northwest as forecast. Therefore, you establish a DR position for 11:00 GCT (Figure 172) using estimated wind of 300°/05 knots and course of 250°.

11:40 GCT — It is time to compute the ETA (Estimated Time of Arrival) and also to check your course for the estimated wind shift; accordingly, you proceed to take another series of sights.

ANTARES			H_{S}	=	38°18′
GCT 11h44m07s			I. C.	=	—5'
GCI II ++ O/	37°28′		Ref.	=	-1'
	1°02′		H_{0}	=	38°12′
	113°31′		$H_{\mathbf{c}}$	=	38°07.3′
GHA	$= 152^{\circ}01'$		a	=	4.7' toward
Assumed Long.	$= 144^{\circ}01'W$		Δd		00 (19/ 17.9/
LHA	= 8° W		H	=	.99 (x 18' = 17.8') $38^{\circ}25.1'$
Assumed Lat.	= 25° N	Lat. 25°N	∆d corr.		—17.8′
Dec.		Dec. 26°S			
		Opp. names	H _C Az	=	38°07.3′
			AZ		N 170.8°W
VEGA			$H_{\mathbf{S}}$	=	65°51′
GCT 11h47m07s			I. C.	=	—5'
der ir ii oi	37°28′		Ref.	=	0′
	1°47′		H_{0}		(504601
			1.0	_	65°46.0′
	81°14′		Hc		65°32.7′
GHA	4.75				
GHA Assumed Long.	$= \frac{81^{\circ}14'}{120^{\circ}29'}$		H _C	=	65°32.7′ 13.3′ toward
	$= \frac{81^{\circ}14'}{120^{\circ}29'}$	2501	H _c a △d	=	$\frac{65^{\circ}32.7'}{13.3' \text{ toward}}$ $45 \text{ (x } 14' = 6.3')$
Assumed Long.	81°14′ = 120°29′ = 144°29′W	Lat. 25°N	H c a △d H	=	$\frac{65^{\circ}32.7'}{13.3' \text{ toward}}$ $\frac{.45 \text{ (x } 14' = 6.3')}{65^{\circ}39.0'}$
$ \begin{array}{c} \textbf{Assumed Long.} \\ \text{LHA} \end{array} $	81°14′ = 120°29′ = 144°29′W = 24° E = 25° N	Lat. 25°N Dec. 38°30′N Same name	H _c a △d	= = = =	$\frac{65^{\circ}32.7'}{13.3' \text{ toward}}$ $45 \text{ (x } 14' = 6.3')$



SPICA	H_{S}	=	25°27′
GCT 11h50m07s	I. C.	=	—5'
39°59′	Ref.	=	-2'
02'	H_{0}	-	25°20.0′
159°27′	$H_{\mathbf{c}}$	_	25°31.2′
GHA = $199^{\circ}28'$	a	=	11.2' away
Assumed Long. $= 144^{\circ}28'W$	$\triangle \mathbf{d}$.57 (x 8' = 4.5')
$LHA = 55^{\circ} W$	Н		25°26.7′
Assumed Lat. $= 25^{\circ}$ N	Lat. 25°N △d co	rr.	+4.5'
Dec. = $10^{\circ}52'S$	Dec. 11°S H _c	=	25°31.2′
	Opp. names Az	=	N 117°W

This fix (Figure 172) indicates that you have correctly estimated the wind shift; however, since you now wish to remain on course, you advance the fix to 12:00 GCT and lay out a new course to destination (254°). Estimating 5° left drift for additional wind shift, you then advise the captain to alter compass heading to 245°.

The Navigator's Flight Report and Radio Weather Report then are made out for 12:00 GCT, using wind and track made good.

To determine your ETA, you estimate that

the ground speed probably will average about 125 knots, as the wind is expected to shift to $10^{\circ}/07$ knots. This means you have $6^{h}18^{m}$ more flying time ahead of you. Allowing 10 minutes for let-down procedure, you estimate the ETA to be 18:28 GCT.

Plotting your present actual position on the time vs. miles curve (Flight Graph) provides a good check on the ETA.

The 13:00 GCT report then is made out, using course to destination and estimated wind of 310°/14 knots as forecast.

POLARIS						
GCT 13h24m07s	7.1			$H_{\mathbf{S}}$		= 23°44′
7-7 7 7 7 7 7 7		62°32′		I. C.	3	= $-5'$
		1°02′		Ref.	2	= $-2'$
. GHA T	=	63°34′		H_{0}		= 23°37′
	-	+360°		Corr. LH	AΥ	= $+21'$
GHAΥ	=	423°34′W		Latitude		= 23°58′N
DR Long.	=	147°34′W				
LHAΥ	=	276°00′W				
ANTARES				$H_{\mathbf{S}}$	=	32°02′
GCT 13h27m07s				I. C.		—5 ′
		62°32′		Ref.	=	-1'
		1°47′		H_{0}	=	31°56′
		113°31′		$H_{\mathbf{c}}$	=	31°56.5′
GHA	=	177°50′		a	=	0.5' away
Assumed Long.	=	147°50′W	(X)	$\triangle \mathbf{d}$.84 (x 18' = 15.1')
LHA	=	30° W		Н		32°11.6′
Assumed Lat.	=	24° N	Lat. 24°N	∆d corr.		—15.1′
Dec.	=	26°18′S	Dec. 26°S	Нc	=	31°56.5′
			Opp. names	Az		N 148°W

ARCTURUS		$H_{\mathbf{S}}$	=	30°52′
GCT 13h30m07s 65°03′ 02′ 146°44′		I. C. Ref. Ho Hc		-5' -1' 30°46' 30°53.2'
$GHA = 211^{\circ}49'$		a	=	7.2' away
Assumed Long. = 147°49′W		$\triangle \mathbf{d}$.29 (x 1' = .3') $30^{\circ}52.9'$
$\begin{array}{ccc} \text{LHA} &=& 64^{\circ} & \text{W} \\ \text{Assumed Lat.} &=& 24^{\circ} & \text{N} \end{array}$	Lat. 24°N	H ∆d corr.		+.3'
Dec. = $19^{\circ}29'N$	Dec. 19°30'N	$H_{\mathbf{c}}$	=	30°53.2′
	Same name	Az	=	N 81.0°W

13:20 GCT—To check the ETA and track, you take another series of sights as follows:

The 13:30 fix (Figure 172) proves that the wind is shifting to the North as forecast. Your ground speed has increased to 122 knots and your ETA is still 18:28 GCT.

Advancing this latest fix to 14:00 GCT, you again fill in the Navigator's Flight Report and Radio Weather Report.

14:50 GCT—Since the sky is starting to get lighter you decide to check the course and speed once more before daybreak, and so obtain the following sights:

Checking the track made good, you find the wind has increased so that you are now making a ground speed of 128 knots with 7° left drift.

Advancing the fix to 15:00, and before filling in Navigator's Flight Report, you first fix your present position as of 15:20 GCT and establish a new course to Honolulu. You then advise the captain to alter compass heading to 249° in order to make 256° true.

15:30 GCT — The sun is starting to rise, and although you have felt you could hardly hold your eyes open for the last couple of hours, you now feel exhilarated, your energy renewed. You anxiously anticipate seeing the peaks of the Islands break through the clouds.

Until the sun is higher, it will not be practical to take sights, so you establish a DR position for 16:00 and fill in the Navigator's Flight Report, using present course and last known wind.

16:20 GCT—You turn on the radio compass and listen to the Honolulu radio range. Hearing a steady dash, with an occasional weak dot-dash (A), proves you are right on course. You relax, feeling satisfied that you have done a nice job of navigation.

17:00 GCT—The sun is high enough now for a sight, so you take a shot to check the speed (see below).

The sun line (Figure 172) indicates that you still are making 128 knots.

17:20 GCT—There are clouds obscuring Maui, but you are sure of your position now and the radio range proves you are well clear of the mountain peaks on Maui and Molokai. You tell the captain that if he will start letting down through the clouds, he will see the east end of Molokai abeam at 17:35.

The captain follows your suggestion and sure enough you see the shore line. However, the increased speed of letting down puts Molokai abeam at 17:33, and the crew razz you for being two minutes off. Nonetheless, you know from their smiles that they would trust your navigation anywhere.

For you the flight is as good as over. You start packing your equipment and sit back and relax while the captain brings in the PBY contact and lands on the bay at Honolulu.

The navigator shouldn't always relax, however, upon sighting land. Quite often he can be of immense assistance to the captain by keeping a close check on the landmarks passed and by computing the best headings to the air base. This is especially true in bad weather when the captain must give all of his attention to flying.

18:29 GCT—On water. Finish filling out the Navigator's Flight Report.

Your trip to Honolulu is over.

SUN

GCT
$$17^{h}00^{m}07^{s}$$
 $75^{\circ}50'$

O2'

Assumed Long. = $154^{\circ}52'$ W

LHA = 79° E

Assumed Lat. = 22° N

Dec. = $16^{\circ}08'$ N

Lat. 22° N

Dec. $15^{\circ}54.3'$

Az = $15^{\circ}28'$

I. C. = $-5'$

Ref. = $-3'$

Ho = $15^{\circ}20'$

Hc = $15^{\circ}54.3'$

a = $34.3'$ away

$$\Delta d = .32 (x 8' = 2.6')$$

H = $15^{\circ}51.7'$

$$\Delta d \text{ corr.} \qquad +2.6'$$

Hc = $15^{\circ}54.3'$

Az = $15^{\circ}28'$

I. C. = $-5'$

Ref. = $-3'$

Ho = $15^{\circ}54.3'$

Ad corr. +2.6'

Hc = $15^{\circ}54.3'$

PROBLEM WORK NO. 32

PBY FLIGHT FROM SAN DIEGO TO HONOLULU MAY 5, 1943

True Course = 253° Total Distance = 2,290 Nautical Miles

I.A.S. = 92 knots, calibration correction +5 knots.

Fuel aboard at start = 1875 U. S. gallons. Average fuel consumption = 75 g.p.h., during climb = 100 g.p.h. Flight altitude = 8000'. Temperature +10°C for total trip.

(Follow all procedures in order, thus simulating actual flight. Plot fixes on a small scale chart. Keep running account of flight by filling in flight plan for each hour before proceeding with next fix. Using forecast wind, establish first heading. Do not alter course unless indicated. Deviation is 0°.)

FORECAST WIND FOR 8000' ZONE 1 SAN DIEGO to 120° W Long. 315° / 20 knots ZONE 2 315° / 20 knots 120° W to 130° W ZONE 3 130° W to 140° W 135° / 20 knots ZONE 4 140° W to 150° W 20° / 20 knots ZONE 5 150° W to HONOLULU 45° / 15 knots

00:31 GCT off water, compass heading = 246°. (Climb 29 min. at an I.A.S. of 100 knots.)

00:37 Relative radio bearing taken of KFSD, San Diego = 171°. Magnetic heading = 247° (at the instant bearing was taken). Mercator correction = -1°.

No.		STAR SIGHTS	TAKEN EN RO	OUTE-INDEX C	ORRECTION	= 0°
1	DUBHE	GCT = 03:27:00 H _S = 57° 06′	BETELGEUX	GCT = 03:32:00 H ₅ = 26° 32'	SIRIUS	GCT=03:37:00 H _s =21° 18'
2	PROCYON	GCT = 05:00:00 H _S = 31° 44′	DUBHE	GCT=04:56:00 H _s =57° 16'	POLLUX	GCT=05:05:00 H _S =41° 15'
3	DUBHE	GCT = 07:14:00 H _s =49° 12'	POLLUX	GCT = 07:00:00 H _s = 20° 06′	SPICA	GCT = 07:05:00 H _S = 50° 49′
4	REGULUS	GCT = 09:00:00 H _S =22° 21'	SPICA	GCT = 09:04:00 H _s = 46° 30'	DUBHE	GCT=09:09:00 H _S =37° 42'
0	9:50 GCT Alt	er course to interce	ept destination.			
5	ANTARES	GCT = 11:55:00 H _S = 37° 35'	ARCTURUS	GCT = $12:00:00$ H ₈ = 46° 42'		
6	ALKAID	GCT = 13:04:00 H _S = 32° 48′	ARCTURUS	GCT = 13:07:30 H ₅ = 33° 38'	ANTARES	GCT = 13:12:00 H _S = 32° 04'
7	ANTARES	GCT = 14:04:00 H _s = 26° 46′	ARCTURUS	GCT = 14:00:00 H _S = 23° 32'	1	

16:34 GCT Radio bearing KMZA = 296°, magnetic heading = 263°.

16:36 GCT Radio bearing KNBF = 333°, magnetic heading = 263°.

16:45 GCT ALTER COURSE TO INTERCEPT DESTINATION.



YOU NAVIGATE TO HONOLULU

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Appreciation is herewith expressed to the U. S. Naval Observatory, and to its superintendent, Capt. J. F. Hellweg, U.S.N., Retired, for permission to reprint the following pages from the Air Almanac.

APPENDIX



GREENWICH A. M. 1943 JANUARY 1 (FRIDAY)

10 20 30 40 50 10 20 30 40 50 20 30 40 50 20 30 40 50 50 10 20 30 40 50 40 50 50 40 50 50 50 50 50 50 50 50 50 50 50 50 50	181 184 186 189 191 194 196 201 204 206 209 211 214 216 219 221	44 43 13 43 13 43 13 43 13 43 13 43 13	S23 S23	05 05	102 104 107 109 112 114 117 119 122 124 127 129 132 134	47 18 48 18 49 19 50 20 50 21 51 22	212 214 217 219 222 224 227 229 232 234 237 239	21 51 21 51 21 51 21 51 21 52	S22 S22		348 351 353 356 358 1 3	56 26 57 27 57 28 58	N21		37 39 42 44	01	N 19		257 260 262	25 5 50 15 40 -		25 27 29 30 32 34	+ Corr.	į.	Ecent	
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AMERICAN AIR NAVIGATOR

GREENWICH P. M. 1943 JANUARY 1 (FRIDAY)

GCT	O SUN GHA Dec.	TP GHA	MARS 1.7 GHA Dec.	JUPITER - 2.2 GHA Dec.	SATURN 0.0 GHA Dec.	MOON GHA Dec.	
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APPENDIX

GREENWICH A. M. 1943 MAY 1 (SATURDAY)

GCT	O SUN GHA Dec.	φ GHA	VENUS - 3.5 GHA Dec.	MARS 1.1 GHA Dec.	JUPITER - 1.6 GHA Dec	MOON GHA Dec.	C. Par.	
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AMERICAN AIR NAVIGATOR

GREENWICH P. M. 1943 MAY 1 (SATURDAY)

GCT		O SUN	φ		VENUS + 3.5			MARS		2.5			JUPITER - 1.6			@ MOON				15	Sun-	Twit.	Moon-	Diff.			
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GREENWICH A. M. 1943 MAY 5 (WEDNESDAY)

GCT	O SUN GHA Dec.	Ψ VENUS - 3.5 GHA GHA Dec.	MARS 1.1 GHA Dec.	JUPITER - 1.6 GHA Dec. GH	MOON (11.
h m 0 00 10 20 30 40 50 1 00 20 30 40 50 2 00 10 20 30 40 50 50 50 50 40 50 50 40 50 50 40 50 50 40 50 50 40 50 50 50 50 50 50 50 50 50 50 50 50 50	198 19 200 49 203 19 · · · 205 49 208 19	224 30 142 46 227 00 145 16 229 31 147 46 232 01 150 16 234 32 152 46 237 02 155 16 N25 15 239 32 157 46 242 03 160 16	239 19 241 50 244 20 · · · 246 50 249 20 251 50 S 8 02 254 20 256 50 259 20 · · 261 50 264 21 266 51 S 8 01 269 21 271 51	118 25 · · · 175 120 56 181 123 26 182 125 56 N22 27 186 130 57 191 133 27 · · 194 135 58 196 138 28 196 140 58 N22 27 143 29 200 145 59 200 151 00 216	2 17 N13 07 4 42 08 7 07 10 9 33 · 11 1 58 13 4 23 14 23 14 23 14 25 14 36 48 N13 15 9 13 17 0 13 18 ° 4 03 · 19 0 5 28 21 7 3 5 53 22 13	Ecast 180 + ' 566 555 54 53 53 53 53 53 54 9
3 00 10 20 30 40 50 4 00 10 20 30 40 50 5 0 10 20 30 40 50 40 50 40 50 40 50 40 50 40 50 40 50 40 50 40 40 50 40 40 50 40 40 50 50 40 40 50 50 50 50 50 50 50 50 50 50 50 50 50	228 19 230 49 233 19 235 49 238 19 240 49 N15 59 243 19 245 49 250 49 253 19 255 49 N16 00 258 19 260 49	267 07 185 14 N25 15 269 37 187 44 272 08 190 14 274 38 192 44 277 09 195 14 279 39 197 44 282 09 200 14 N25 16 284 40 202 43 287 10 205 13 289 41 207 43 292 11 210 13 294 41 212 43 297 12 215 13 N25 16 299 42 217 43 302 13 220 13 304 43 222 43 307 14 225 12 309 44 227 42	284 22 286 52 289 22 · · · 291 52 294 22 296 52 S 8 00 299 22 301 52 304 22 · · 306 53 309 23 311 53 S 7 59 314 23 316 53	156 01 N22 27 215 158 31 226 163 32 · · 225 166 02 225 171 03 N22 27 23 173 33 176 03 23 176 03 22 177 03 N22 27 23 178 34 · · 23 181 04 24 183 34 24 183 34 24 183 35 N22 27 24 188 35 24 191 05 24 193 66 · · 25 196 06 25	31 32 33 33 34 32 35 34 37 36 39 37 40 40 47 47 47 47 47 48 49 47 49 49 49 49 49 49 49 49 49 49 49 49 49	48 47 46 45 44 43 42 41 40 39 38 37 36 33 33 33 34 33 32 32 32 32 32 32 32 32 32 32 32 32
6 00 10 20 30 40 50 7 00 10 20 30 40 50 8 00 10 20 30 40 50 50	273 19 275 49 278 19 280 49 283 19 285 49 N16 01 288 19 290 49 293 19 295 49 295 49 298 19	312 14 230 12 N25 16 314 45 232 42 317 15 235 12 319 46 237 42 322 16 240 12 324 46 242 42 327 17 245 11 N25 16 329 47 247 41 332 18 250 11 334 48 252 41 337 18 255 11 339 49 257 41 342 19 260 11 N25 17 344 50 262 41 347 20 265 10 349 50 267 40 352 21 270 10 354 51 272 40	329 24 331 54 334 24 · · · 336 54 339 24 341 54 S 7 57 344 24 346 54 349 25 · · 351 55 354 25 356 55 S 7 57 359 25 1 55	203 37 264 206 07 264 208 38 · · · 266 211 08 265 213 38 27 218 39 22 26 27 218 39 27 223 40 · · · 281 226 10 283 228 41 226 233 41 22 26 238 42 · · 293 241 12 295	1 46 57 61 4 11 58 62 5 36 13 59 64 9 01 14 01 65 1 26 02 66 3 51 N14 03 67 5 16 05 68 3 41 06 69 1 06 07 70 3 31 09 71 5 56 10 72 3 32 N14 11 73 0 47 12 74 3 12 14 76 5 37 15 77 8 02 16 78	29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 15 15 18 17 16 15 15 17
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GREENWICH P. M. 1943 MAY 5 (WEDNESDAY)

GC	т	O SUN GHA Dec.	φ GHA	VENUS - 3.5 GHA Dec		MARS GHA	1.1 Dec.	JUPITE GHA	R - 1.6 Dec.	MOON GHA Dec.	3	Sun- rise	Ž	Moon- rise	Diff
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GREENWICH A. M. 1943 MAY 10 (MONDAY)

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GREENWICH P. M. 1943 MAY 10 (MONDAY)

GC1	GHA Dec.	φ GHA	VENUS - 3.6 GHA Dec.	MARS 0.9 GHA Dec.	JUPITER - 1.5 GHA Dec.	MOON GHA Dec.	2	Sun- rise	7	Moon- rise
3 0 1 1 2 3 3 4 4 5 5 5 4 4 6 5 5 5 5 6 6 6 6 6 6 6 6	0 0 55 N17 28 0 3 25 0 5 55 0 10 55 0 13 25 0 13 25 0 15 55 N17 28 0 18 25 0 20 55 0 20 25 55 0 25 55 0 30 55 N17 29 0 33 25 0 33 25 0 33 25 0 33 25 0 34 55	49 55 52 26 54 56 57 26 59 57 62 27 64 58 67 28 69 59 72 29 74 59 77 30 80 00 82 31 85 01	318 41 N25 38 321 11 323 41 323 40 331 10 338 40 331 10 338 40 341 10 348 40 346 10 348 40 N25 38 351 09 353 39 356 09 1 09	\$8 23 S 6 29 60 53 63 23 65 53 68 23 70 54 73 24 S 6 28 75 54 78 24 80 54 83 24 85 54 88 24 S 6 28 90 55 93 25 93 25 93 25 93 25 93 25	295 26 N22 20 297 57 300 27 302 57 305 28 307 58 310 28 N22 20 315 29 315 29 317 59 320 323 00 323 00 325 30 N22 20 328 01 330 31 333 01 333 335 32 338 02	289 56 39 292 21 38 294 46 37 297 11 37 299 37 36 302 02 N18 36 304 27 35 306 52 34 309 18 34 311 43 33 314 08 33	68 66 64 62 60 58 56 54 52 50 45 40 35 30 20	h m 1 38 2 18 2 46 3 06 23 37 3 59 4 08 16 23 38 4 51 5 01 11 26	24	h m 5 57 6 49 7 21 7 45 8 03 19 32 43 8 53 9 02 10 26 40 9 51 10 01
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5 0 1 2 3 4	0 60 55 N17 30 0 63 25 0 65 55 0 68 25 · ·	105 04 107 35 110 05 112 35 115 06 117 36	18 38 N25 38 21 08 23 38 26 08 · ·	115 56 118 26 S 6 26 120 56 123 26 125 56 · · · 128 26	353 04 355 35 N22 19 358 05 0 35 3 06 · · · 5 36	343 11 25 345 36 N18 25 348 02 24 350 27 23 352 52 23 355 17 22	35 40 45 50	34 43 6 52 7 04 18 25		35 45 11 56 12 10 26 34
7 0	73 25 75 55 N17 31 0 78 25 0 80 55 0 83 25 · · 0 85 55	120 07	31 07 33 37 N25 38 36 07 38 37 41 07 · · · · 43 37	130 56 133 27 S 6 25 135 57 138 27 140 57 • • • • • • • • • • • • • • • • • •	8 06 10 37 N22 19 13 07 15 37 18 08 · · · 20 38	357 43 21 0 08 N18 21 2 33 20 4 58 19 7 24 19 9 49 18	54 56 58 60 S	32 40 7 49 8 00	38 40 43	42 12 52 13 03 13 16
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5 0 1	0 115 55 0 118 25 0 120 55 N17 33	162 44 135 14	73 35 76 05 78 35 N25 39	173 28 175 59	50 42 53 12 55 43 N22 19 58 13	38 52 10 41 17 09 43 43 N18 09 46 08 08	62 60 58	32 17 20 05 19 55	68 60 52 47	1 12 0 56 43 32
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2 3 4 5 0 1 2	0 150 55 N17 34 0 153 25 0 155 55	202 50	116 03		20 10		35	17 09	27	16
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GREENWICH A. M. 1943 MAY 15 (SATURDAY)

GREENWICH P. M. 1943 MAY 15 (SATURDAY)

GC	т	O SUN GHA Dec.	Υ GHA	VENUS GHA	- 3.6 Dec.	MARS GHA	0.9 Doc.	JUPITER -	- 1.5 Dec.	O MOON GHA Dec.	Ig.	Sun- rise	Twlt.	Moon- rise
113	10 20 30 40 50	0 57 Ni8 43 3 27 5 57 8 27	54 51 57 21 59 52 62 22 64 53 67 23 69 53 72 24 74 54 77 25 79 55	334 46 337 16 339 45 342 15 344 45 347 15 N 349 45	. 125 41	62 20 64 50 67 20 69 50 72 20 74 50 S 77 21 79 51 82 21 84 51 87 21	5 02	99 31 N22 302 01 304 31 307 02 - 309 32 312 02 314 33 N22 317 03 319 33 322 04 - 324 34 327 04 329 35 N22 334 35 337 06 339 36 342 06	2 13	s ' s 27 232 26 N 3 27 234 51 25 237 16 23 239 42 21 242 07 20 244 33 18 246 58 N 3 16 249 24 14 251 49 12 254 14 11 254 14 11 255 40 09 259 05 07 261 31 N 3 05 263 56 04 266 21 02 268 47 3 00 271 12 2 58 273 38 56	N 0 70 68 66 64 62 600 58 56 45 40 35 30 20 10	h m 53 352 26 50 99 25 3 8 49 3 59 4 08 16 4 57 7 24 39	77 154 154 154 154 154 154 154 154 154 154	h m 14 02 05 08 10 12 14 16 17 18 20 21 23 25 27 28 31 33
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16	00 10 20 30 40	60 57 N18 46 63 27 65 57 68 27 · · 70 57	112 30 115 01 117 31 120 02 122 32	19 44 22 14 24 43 • 27 13		119 53 S 122 23 124 53 127 23 • 129 53	5 00	357 09 359 39 N22 2 09 4 40 7 10 • 9 40		288 10 46 290 35 N 2 44 293 01 42 295 26 40 297 52 39 300 17 37	52	37 46 6 57 7 10 25 33	25 27 29 31 36 37	42 44 46 48 50 51
7	50 00 10 20 30 40 50	73 27 75 57 N18 46 78 27 80 57 83 27 • 85 57 88 27	125 02 127 33 130 03 132 34 135 04 137 34 140 05	29 43 32 13 N 34 43 37 13 39 43 • 42 13 44 43	:25 41	132 23 134 53 S 137 24 139 54 142 24 • 144 54 147 24		12 11 14 41 N22 17 11 19 42 22 12 • 24 42 27 13	2 12	302 42 35 305 08 N 2 33 307 33 31 309 59 30 312 24 - 28 314 49 26 317 15 24	54 56 58 60 S	40 49 7 59 8 11	39 42 44 48	52 54 55 14 57
	00 10 20	90 57 N18 47 93 27 95 57	142 35 145 06 147 36	47 12 N 49 42 52 12	25 41	149 54 S 152 24 154 54	4 59	29 43 N22 32 13 34 44		319 40 N 2 23 322 05 21 324 31 19	Lat.	Sun- set	Twit.	Moon-
9	30 40 50 00 10 20	98 27 · · · · 100 57 103 27 105 57 N18 48 108 27 110 57 113 27 · · ·	150 07 152 37 155 07	54 42 · 57 12 59 42	125 41	157 25 · 159 55 162 25 164 55 S 167 25 169 55 172 25 ·	. 4 58	37 14 · 39 44 42 15 44 45 N22 47 15 49 46 52 16 ·	2 12	326 56 · 17 329 22 15 331 47 14 334 12 N 2 12 336 38 10 339 03 08 341 29 · 06	68 66	h m 23 13 22 05 21 30 21 05	m HH HH 98	h m 3 09 3 03 2 58 54
	40 50	115 57 118 27 120 57 N18 48	167 39 170 10 172 40	72 11 74 41 77 11 N	25 41	174 55 177 26 179 56 S		54 46 57 17		343 54 05 346 19 03	62	20 46 29	74 64	51 48 45
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20	00 10 20 30 40 50 00 10 20 30	125 57 128 27 · · · 130 57 133 27 135 57 N18 49 138 27 140 57 143 27 · ·	175 11 177 41 180 11 182 42 185 12 187 43 190 13 192 44 195 14	79 41 82 11 84 41 • 87 11 89 40 92 10 N 94 40 97 10 99 40 •		182 26 184 56 187 26 189 56 192 26 194 56 S 197 26 199 57 202 27 204 57		59 47 N22 62 17 64 48 67 18 * 69 48 72 19 74 49 N22 77 19 79 50 82 20 *		348 45 N 2 01 351 10 1 59 353 35 57 356 01 56 358 26 54 0 52 52 3 17 N 1 50 5 42 48 8 08 46 10 33 45	58 56 54 52 50 45 40 35 30	20 04 19 54 46 38	50 46 42 39	43 40 39 37
2 (1)	00 110 220 330 440 550 00 110 220 330 440 550 00 110 220 330	125 57 128 27 · · · · 130 57 130 57 133 27 135 57 N18 49 138 27 140 57 143 27 · · · 145 57 148 27 153 27 155 57 158 27 · · ·	175 11 177 41 180 11 182 42 185 12 187 43 190 13 192 44 197 44 200 15 202 45 205 16 207 46 210 16	79 41 82 11 84 41 • 87 11 89 40 92 10 N 94 40 97 10 99 40 • 102 10 104 40 107 10 N 109 40 112 09 114 39 • 1	. 25 41	182 26 184 56 187 26 189 56 192 26 194 56 197 26 199 57 202 27 204 57 207 27 209 57 8 212 27 212 27 217 27 -	3 4 57	59 47 N22 62 17 64 48 67 18 - 69 48 72 19 74 49 N22 77 19 79 50 82 20 - 84 50 87 21 89 51 N22 92 21 94 52 97 22 -	2 12	348 45 N 2 01 351 10 1 59 353 35 57 356 01 56 358 26 54 0 52 52 3 17 N 1 50 5 42 42 44 10 33 45 12 58 43 15 24 41 17 49 N 1 39 20 15 37 22 40 22 55 34	58 56 54 52 50 45 40 35 30 20 10 0	20 04 19 54 46 38 21 19 07 18 56 46 28 14 18 00 17 46 31 15	50 46 42 39 34 31 28 26 24 22 22 23 24 25	43 40 39 37 33 30 27 24 20 16 12 08 04 2 00
2 (1)	00 110 220 330 440 550 00 00 00 00 00 00 00 00 00 00 00 0	125 57 128 27 · · · · · · · · · · · · · · · · · ·	175 11 177 41 180 11 182 42 185 12 187 43 190 13 192 44 195 14 197 44 200 15 202 45 205 16 210 16 212 47 215 17 217 48 220 18 222 48 222 48 222 19 222 48	79 41 82 11 84 41 87 11 89 40 92 10 N 94 40 97 10 99 40 102 10 104 40 107 10 N 112 09 114 39 117 09 119 39	. 25 41	182 26 184 56 187 26 189 56 192 26 194 56 197 26 199 57 202 27 202 27 204 57 207 27 209 57 S 212 27 212 27 212 27	. 4 57	59 47 N22 62 17 64 48 67 18 - 69 48 72 19 74 49 N22 77 19 79 50 82 20 - 84 50 87 21 89 51 N22 92 21 94 52	· 2 12 ·	348 45 N 2 01 351 10 1 55 353 35 356 01 56 0 52 56 3 17 N 1 50 5 42 48 8 08 46 10 33 46 15 24 41 17 49 N 1 36 22 40 36 22 40 36 22 40 36 32 21 N 1 28 39 38 23 39 38 23 40 30 32 21	58 56 54 52 50 45 40 35 30 20 10 0 10 20 30 35 52 54 55 50 45 50 45 50 45 50 50 50 50 50 50 50 50 50 50 50 50 50	20 04 19 54 46 38 21 19 07 18 56 46 28 14 18 00 17 46 31	50 46 42 39 34 31 28 26 24 22 22 22 23 24	43 40 39 37 33 30 27 24 20 16 12

GREENWICH A. M. 1943 MAY 20 (THURSDAY)

GCT	O SUN GHA Dec.	T VEN	IUS - 3.6 Dec.	MARS 0.9 GHA Dec.	JUPITER - 1.6 GHA Dec.	O MOON GHA Dec.	Cs Par.	
10 20 30 40 50 1 00	0 / 0 / 180 55 N19 45 183 25 185 55 188 25 190 55 193 25 185 55 N19 45	239 17 138 3 241 47 141 0 244 18 143 3 246 48 146 0 249 19 148 3	4 4 4 · · · 4	241 09 S 3 45 243 39 246 09 248 40 · · · · 251 10 253 40 256 10 S 3 44	125 39 128 10 130 40 · · · · · · · · · · · · · · · · · ·	0 37 17 3 01 18 5 26 19 7 50 21	0 60 2	East
10 20 30 40 50 2 00 10 20 30 40 50	198 25 200 55 203 25 · · · 205 55 208 25 210 55 N19 46 213 25 215 55 218 25 · · · 220 55 223 25	254 19 153 3 256 50 156 0 259 20 158 3 261 51 161 0 264 21 163 3	3 3 3 3 3 3 3 N25 29 3 3 3	258 40 261 10 263 40 · · · 266 10 268 40 271 11 S 3 44 273 41 276 11	140 41 143 12 145 42 · · · 148 12 150 43	15 03 25 17 27 26 19 52 27 22 16 29 24 40 30	11 59 15 58 18 57 18 57 24 55 24 55 26 54 28 53 30 52 32 57 33 50 35 49	• 44
3 00 10 20 30 40 50	228 25 230 55 233 25 · · · 235 55 238 25	284 24 183 3 286 55 186 0 289 25 188 3 291 56 191 0 294 26 193 3	2 2 2 · · · 2	288 41 291 12 293 42 · · · 296 12 298 42	170 45 173 16 175 46 · · 178 16	41 31 S15 39 43 55 40 46 20 42 48 44 43 51 08 44 53 33 45	38 47 40 46 41 45 43 44 44 43 45 42	* Page
4 00 10 20 30 40 50 5 00	240 55 N19 47 243 25 245 55 248 25 · · 250 55 253 25 255 55 N19 47	299 27 198 3 301 57 201 0 304 28 203 3 306 58 206 0 309 29 208 3	1	301 12 S 3 42 303 42 306 12 308 42 · · 311 13 313 43 316 13 S 3 41	185 47 188 18 190 48 · · · 193 18 195 49	58 21 48 60 46 49 63 10 50 65 34 52 67 58 53	48 40 49 39 51 38 52 37 53 36 54 35 4	• 10. • 10.
10 20 30 40 50	258 25 260 55 263 25 · · · 265 55 268 25	314 29 213 3 317 00 216 0 319 30 218 3 322 01 221 0 324 31 223 3	1	318 43 321 13 323 43 · · · 326 13 328 43	200 49 203 20 205 50 · · · 208 20 210 51	72 47 55 75 11 57 77 36 58 80 00 15 59 82 24 16 00	55 34 57 33 58 32 59 37 60 30 61 29	
6 00 10 20 30 40 50 7 00 10 20 30 40 50 8 00 10 20 30 40 50	273 25 275 55 278 25 · · · 280 55 283 25 283 25 285 55 N19 48 288 25 290 55 293 25 · · · 295 55 298 25 305 55 N19 49 303 25 305 55 310 55 311 25	329 32 228 3 332 02 231 0 334 33 233 3 337 03 236 0 339 33 238 3 342 04 241 3 344 34 243 3 347 05 248 2 352 06 250 5 354 36 253 2 357 06 255 3 357 06 255 3 2 07 260 5 2 07 260 5 9 38 268 2	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 9 9 9 9	3 45 6 15 8 45 · · 11 16 13 46	215 51 218 22 220 52 · · · 223 22 225 53 228 23 N22 05 230 53 233 24 235 54 · · · 238 24 240 55 241 25 N22 05 245 55 248 26 250 56 · · 253 26 255 57	87 13 03 89 37 04 92 02 05 94 26 07 96 50 08 99 15 S16 09 101 39 10 104 03 10 108 52 14 111 16 04 18 118 29 120 53 20 123 17 21 125 42 22	62 28 63 27 64 26 65 25 66 24 67 23 68 22 69 21 70 20 71 19 72 18 73 17 74 16 75 15 76 14 77 13 78 12 79 11 80 10	· ***
10 20 30 40 50		12 09 270 5 14 39 273 2 17 10 275 5 19 40 278 2 22 10 280 5 24 41 283 2 27 11 285 5 29 42 288 2 32 12 290 5 34 42 293 5 37 13 295 2 39 43 298 2 42 14 300 5 44 44 303 2 47 15 305 5 49 45 308 5 52 15 310 5	8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 7 7 7 7	18 46 21 16 23 46 · · · 26 16 28 46	260 57 263 28 265 58 · · · 268 28 270 59 273 29 N22 05 275 59 278 30 281 00 · · · 283 30 286 01	128 06 S16 24 130 30 25 132 54 26 135 19 27 137 43 28 140 07 30 144 56 32 147 20 33 149 44 34 152 09 35 154 33 36 156 57 S16 38 159 21 39 161 45 40 164 10 41	SD, ⊙ 16 SD, ℂ 16 TE HA ℂ TE M	V _{rle} West

GREENWICH P. M. 1943 MAY 20 (THURSDAY)

7 00 10 20 30 40 20 30 40 50 10 20 30 40 30 30 30 30 30 30 30 30 30 30 30 30 30	0 55 N19 5 3 25 5 55 8 25 10 55 13 25 15 55 N19 5 18 25 20 55 23 25 25 55 28 25	59 47 62 17 64 47 67 18 69 48 72 19 74 49 77 19	318 26 320 56 323 26 325 56 328 26 330 56	N25 27	63 66 68	18	3	36	303 306		N22	05	171		S16	45	N				
40 50	30 55 N19 5 33 25 35 55 38 25 • 6 40 55 43 25	79 50 82 20 84 51 52 87 21 89 52 92 22 94 52 97 23 99 53	340 55 343 25 345 55 348 25 350 55 353 25 355 55	N25 27 N25 27	73 76 78 81 83 86 88 91 93 96 98	49 19 49 • 19 49	3 3	36 35	308 311 313 316 318 321 323 326 328 331 333 336 338 341	34 04 34 05 35 05 36 06 36 07 37 07 38 08 38	N22		176 178 180 183 185 188 190 193 195 197	12 36 00 25 49 13 37 02 26 50	S16 S16 16 17	46 47 48 49 50 51 52 54 55 56 57 58 59 00 01 02 03	70 68 66 64 62 60 58 56 54 52 50 45 40 35 30 20	1 22 2 06 34 40 3 51 4 000 99 27 41 4 54 5 04 223	125 82 69 60 54 45 42 36 29 27 24	20 49 40 32 24 20 08 19 56 45 35	
5 00 10 20 30 40 50 6 00 10 20 30 40 50 7 00 10 20 30 40 50	45 55 N19 5 48 25 50 55 53 25 - 55 55 60 55 N19 5 63 25 65 55 68 25 - 70 55 73 25 73 25 78 25 80 55 80 55 83 25 - 85 54	104 54 107 24 107 25 112 25 114 56 117 26 117 26 112 27 124 57 127 28 132 29 134 59 137 29 137 29 142 30	3 24 5 54 8 24 10 54 13 24 15 54 18 24 20 54 23 24 25 53 30 53 33 23 35 53 38 23 40 53		1 08 111 113 116 118 121 123 126 128 131 133 136 138 141 143	52 22 52 •	S 3	34	3 6 8 11 13 16 18 21 23 26 28	09 40 10 40 11 41 11 42 12 42 13 43 13 44 14 44	N22	. 05	226 229 231 233 236 238 241 243 245 248 250 253	03 27 51 15 39 04 28 52 16 40 05 29 53 17 41 05	S17 S17	06 07 08 09 10 11 12 13 14 15 16 17 18 19 20 21	10 20 30 35 40 45 50 52 54 56 58 60 8	38 5 53 6 08 23 40 6 50 7 02 15 32 39 48 7 57 8 08 8 21	23 22 24 25 27 29 32 36 38 40 43 46 50	18 51 38 24 18 08 17 59 48 36 21 14 17 06	
30 40 10 20 30 40 50 40 10 20 30 40 10 20 30 40 40 40 40 40 40 40 40 40 40 40 40 40	88 24 90 54 N19 93 24 95 54 98 24 100 54 103 24 105 54 N19 91 108 24 110 54 113 24 115 54 118 24 120 54 N19 91 123 24 125 54 128 24 125 54	150 01 152 32 155 02 157 33 160 03 162 33 162 33 167 34 170 05 172 35	48 23 50 52 53 22 55 52 58 22 60 52 63 22 65 52 68 22 73 21 75 51 78 21 80 51 83 21	N25 26 N25 26 N25 26	153 156 158 161 163 166 168 171 173 176 178 181 183 186 188	23 5	5 3	31	33 36 38 41 43 46 48 51 53 56 61 63 66 68 71	15 46 16 46 17 47 17 48 18 48 19 49 19 50 20	N22 N22	. 04	257 260 262 265 267 269 272 274 277 279 281 284 286 289 291 293	18 42 06 30 55 19 43 07 31 55 20 44 08 32 56	S17 S17	22 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39	70 68 66 64 62 60 58 56 54 52 50	Sun- set 22 36 21 50 21 21 20 59 40 26 14 20 03 19 53 44	m 日 元 元 元 元 元 元 元 元 元 元 元 元 元 元 元 元 元 元	Moon-set 2 49 3 16 36 3 53 4 06 18 28 37 45 52	
50 1 00 20 30 40 50 10 20 30 40 50 10 20 30 40 50 10 20 30 40 20 30 40 10 20 30 40 10 20 30 40 40 40 40 40 40 40 40 40 40 40 40 40	133 24 135 54 N19 5 138 24 140 54 143 24	190 08 192 38 195 09 197 39 200 10 202 40 202 40 202 10 210 11 212 42 217 42 220 13 57 222 43 227 44 230 15 232 45	88 21 90 51 93 21 95 50 98 20 100 50 103 20 105 50 113 20 110 50 113 20 115 50 118 20 120 49 123 19	N25 25	193	55 S S S S S S S S S S S S S S S S S S	3	29	76 78 81 83 86 88 91	21 52 52 52 53 53 53 54 54 54 55 56 56 56		. 04	298 301 303 305 308 310 313 317 320 322 325 327 329	33 57 21 45 09 34 58 22 46 10 34 58 22 46 11 35	S17	42 43 44 45 46 47 48 49 50 51 52	45 40 35 30 20 10 0 10 20 30 35 40 45 50 52 54	26 12 19 00 18 49 30 15 18 00 17 46 31 17 03 16 51 38 21 13	28 26 24 23 22 23 24 26 28 30 32 36 38 41 44 46	10 19 31	

GREENWICH A. M. 1943 MAY 25 (TUESDAY)

GCT	O SUN GHA Dec.	T VE	NUS - 3.6 Dec.	MARS 0.9 GHA Dec.	JUPITER - 1.5 GHA Dec.	MOON GHA Dec.	Cs Par.	
10 20 30 40 50 1 00	0 / 0 180 50 N20 45 183 20 185 50 188 20 190 50 193 20 195 50 N20 45	244 13 137 246 43 139 249 14 142 251 44 144 254 14 147	50 20 · · 50 20	0	0 / 0 / 127 09 N21 57 129 39 132 09 134 40 · · · 137 10 139 40 142 11 N21 57	289 29 31 291 53 30 294 17 28 296 42 27 299 06 26		East
10 20 30 40 50 2 00 10 20 30 40 50	198 20 200 50 203 20 · · · 205 50 208 20 210 50 N20 46 213 20 215 50 2218 20 · · · 220 50 223 20	259 15 152 261 46 154 264 16 157 266 46 159 269 17 162	20 50 19 · · · 49 19 49 N25 00 19 49 19 · ·	260 10 262 40 265 10 · · · · · · · · · · · · · · · · · ·	144 41 147 11 149 42 · · 152 12 154 42	303 55 24 306 19 23 308 43 21 311 07 20 313 32 19	9 59 14 58 17 56 20 55 23 55 25 54 27 53 29 52 31 50 33 50 35 49	* **
3 00 10 20 30 40 50	225 50 N20 46 228 20 230 50 233 20 235 50 238 20	289 20 182 291 51 184 294 21 187 296 51 189 299 22 192	18 48 18 · · · 48 18	290 11 292 41 295 11 · · · 297 42 300 12	174 45 177 15 179 46 · · 182 16 184 46	330 22 S16 11 332 46 09 335 11 08 337 35 07 339 59 06 342 24 04	38 47 39 46 41 45 42 44 44 43 45 42	* 700
10 20 30 40 50	240 50 N20 47 243 20 245 50 248 20 · · · 250 50 253 20 255 50 N20 47	304 23 197 306 53 199 309 23 202 311 54 204 314 24 207 316 55 209	18 48 18 · · 48 18 47 N24 59	305 12 307 42 310 12 · · · 312 42 315 12 317 43 S 2 15		347 12 02 349 37 01 352 01 ·16 00 354 25 15 58 356 50 57 7 359 14 S15 56	48 40 49 39 50 38 52 37 53 36 54 35	* 157
10 20 30 40 50	258 20 260 50 263 20 · · · 265 50 268 20	319 25 212 321 55 214 324 26 217 326 56 219 329 27 222	47 17 · ·	320 13 322 43 325 13 · · · 327 43 330 13	204 49 207 19 209 50 · · 212 20 214 50	1 38 55 4 03 53 6 27 52 8 52 51 11 16 50	56 33 57 32 59 31 60 30 61 29	· · ·
5 00 10 20 30 40 50 7 00 10 20 30 40 50 8 00 10 20 30 40 50 50 50 40 50 50 40 50 50 40 50 50 50 50 50 50 60 60 60 60 60 60 60 60 60 60 60 60 60	288 20 290 50 293 20 · · · 295 50 298 20 300 50 N20 48 303 20 305 50 308 20 · · · 310 50 313 20	334 28 227 336 58 229 339 28 232 341 59 234 347 00 239 349 30 242 352 00 244 354 31 247 357 01 249 359 32 255 2 02 254 4 32 257 7 03 259 9 33 262 12 04 264 14 34 267	47 17 · · · · · · · · · · · · · · · · · · ·	335 13 337 44 337 44 340 14 · · · 342 44 345 14 350 14 352 44 355 14 · · · 357 45 0 15 2 45 S 2 12 5 15 7 45 10 15 · · · 12 45 15 15	219 51 222 21 224 52 · · 227 22 229 52 3 232 23 N21 57 234 53 237 23 237 23 239 54 · · 242 24 24 25 N21 57 249 55 252 25 56 · · 257 26 259 56	16 05 47 18 29 46 20 53 · 45 23 18 43 228 07 S15 41 30 31 39 32 55 38 35 20 · 37 37 44 36 40 33 S15 33 44 57 32 47 22 30 49 46 · 29 52 10 28 54 35 27	62 28 63 27 64 26 65 25 66 24 67 23 68 22 69 21 70 20 71 19 72 18 73 17 74 16	4. A.
9 00 10 20 30 40 50 0 00 10 20 30 40 50 10 20 30 40 40 40 40 50 40 40 40 40 40 40 40 40 40 40 40 40 40	315 50 N20 49 318 20 320 50 323 20 325 50 328 20 330 50 N20 49 333 20 335 49 338 19 340 49 343 19 345 49 N20 50 345 49 N20 50 348 19 350 49 348 19 350 49 353 19	19 35 272 22 05 274 24 36 277 27 06 279 29 37 282 32 07 284 34 37 287 37 08 289 39 38 292 42 09 294 44 39 297	15 · · · 45 · · · 45 · · · · 45 · · · · 45 · · · ·	17 46 S 2 12 20 16 22 46 25 16 · · · 27 46 30 16 32 46 S 2 11 35 16 37 47 40 17 · · · 42 47 45 17 47 47 S 2 10 50 17 55 17 · · · 57 48 60 18	264 57. 267 27 269 58 272 28 274 58 277 29 N21 57 279 59 282 29 285 00 287 30 280 00	59 24 24 61 48 23 64 12 21 66 37 20 69 01 19 71 26 S15 17 73 50 16 76 14 15 78 39 13 81 03 12 83 28 11	Corr. HA	* West





GREENWICH P. M. 1943 MAY 25 (TUESDAY)

GCT	O SUN GHA Dec.	φ GHA	VENUS - 3.6 GHA Dec.	MARS 0.9 GHA Dec.	JUPITER - 1.5 GHA Dec.	MOON GHA Dec.	Sun-	Moon- rise	Diff.
12 00 10 20 30 40 10 20 30 40 10 20 30 40 50 14 00 10 20 30 40 50 50	0 49 N20 50 3 19 5 49 8 19 · · · 10 49 13 19 15 49 N20 51 18 19 20 49 23 19 · · · 25 49 28 19 30 49 N20 51 33 19 35 49 38 19 · · 40 49 43 19	82 15 84 46 87 16 89 46 92 17 94 47 97 18	314 43 N24 57 317 13 319 43 322 13 324 43 327 13 329 43 N24 57 332 13 334 13 337 13 337 13 339 42 342 12 344 42 N24 56 347 12 349 42 352 12 355 12	62 48 S 2 10 65 18 67 48 70 18 · · · · · · · · · · · · · · · · · ·	310 03 312 33 315 04 · · · 317 34 320 04	102 43 15 00 105 08 14 59 107 32 57 109 56 56 112 21 114 45 S14 53 117 10 52 119 34 50 121 59 49 124 23 48 126 48 46 129 12 S14 45 131 36 44 134 01 42 136 25 41 138 50 39 141 14 38	N	#	*** 0 1 1 2 2 2 2 3 3 3 3 4 4 4 4 4 4 4
15 00 10 20 30 40 16 00 10 20 30 40 50 17 00 10 20 30 40 50 50	45 49 N20 52 48 19 50 49 53 19 · · · 55 49 58 19 60 49 N20 52 63 19 65 49 68 19 · · · 70 49 73 19 75 49 N20 53 78 19 80 49 80 49 83 19 · · 85 49 88 19	109 50 112 20 114 51 117 21 119 51 122 22 124 52 127 23 129 53 132 23 134 54	359 42 N24 56 2 12 4 41 7 11 · · · 9 41 12 11 14 41 N24 56 17 11 19 41 22 11 · · · 24 41 27 11 29 41 N24 56 32 10 34 40 37 10 · · 39 40 42 10	110 20 112 50 115 20 · · 117 51 120 21	352 39 N21 56 355 09 357 39 0 10 · · · 2 40 5 10 7 41 N21 56 10 11 12 41 15 12 · · · · 17 42 20 12 22 43 N21 56 25 13 27 43 30 14 · · 3 32 44 35 14	143 39 S14 37 146 03 35 148 28 34 150 52 32 153 17 31 155 41 30 158 06 S14 28 160 30 27 162 55 25 165 19 24 167 44 22 170 08 21 172 33 S14 20 174 57 188	10 38 0 5 53 10 6 09 20 25 30 44 35 6 54 40 7 06 45 21 55 38 56 8 06 56 8 8 32 8	23 23 55 22 45 23 35 24 24 25 23 05 27 23 05 30 22 57 32 48 36 37 38 31 40 26 43 19 46 43 22 03	5 5 6 6 6 6 7 7 7 7 7 8 8 8
18 00 10 20 30 40 19 00 10 20 30 40 50 20 20 30 40 50	90 49 N20 53 93 19 95 49 98 19 100 49 103 19 105 49 N20 54 108 19 110 49 113 19 115 49 118 19 120 49 N20 54 123 19 125 49 128 19 130 49 130 49 131 19	152 27 154 57 157 28 169 58 162 28 164 59 167 29 170 00 175 00 177 31 180 01 182 32 185 02 187 32 190 03 192 33 195 04	44 40 N24 55 47 10 49 40 52 10 - 54 54 40 57 09 59 39 N24 55 62 09 64 39 67 09 - 69 69 39 72 09 74 39 N24 55 77 09 79 39 82 08 - 84 87 08	170 23 172 53 175 23 · · · 177 54 180 24	37 45 N21 56 40 15 42 45 45 16 47 46 50 16 52 47 N21 56 55 17 57 47 60 18 62 48 65 18 67 48 N21 56 70 19 72 49 75 19 77 50 80 20	189 24 10 191 49 08 194 13 - 07 196 38 05 199 02 04 201 27 S14 02 203 51 14 01 206 16 13 59 208 40 58 211 05 57 213 29 55 215 54 S13 54 228 18 18 220 43 51 223 07 49 5 225 32 48 227 56 46	Sun- set N	m h m 7 46 hkl 8 14 hkl 8 35 hkl 8 52 28 55 36 44 45 9 518 36 10 11	m 111 100 98 88 88 77 77
21 00 10 20 30 40 22 00 10 20 30 40 50 23 00 10 20 30 40 50 20 40 50 40 40 50 40 40 40 40 40 40 40 40 40 40 40 40 40	135 49 N20 54 138 19 140 49 143 19 · · · 145 49 148 19 150 49 N20 55 153 19 155 49 168 19 · · 168 19 170 49 173 19 · · 175 49 175 49 175 49 175 49 177 49 178 19	200 04 202 35 205 05 207 36 210 06 212 37 215 07 217 37 220 08 220 08 222 38 225 09 227 39 230 09 230 09 232 40 233 40	92 08 94 38 97 08 · · 99 38 102 08 104 38 N24 54 107 08 109 37 112 07 · · 114 37 117 07	197 54 S 2 03 200 25 202 255 205 25	85 21 87 51 90 21 · · · 92 52 95 22 97 52 N21 56 100 23 102 53 105 23 · · · 107 54	230 21 S13 45	30 11 35 17 00 40 16 48 45 33 50 16 52 16 07 54 15 58	322 21 29 31 27 39 24 10 53 23 11 05 22 17 23 28 24 40 26 11 54 28 12 01 30 10 32 21 33 39 41 12 53 44 12 53 46 13 00	6 6 6 6 6 5 5 5 4 4 4 4 3 3 3 3 3 2 2 2

GREENWICH A. M. 1943 MAY 30 (SUNDAY)

GCT	O SUN GHA Dec.	T VENUS -	Dec. GHA Dec	JUPITER - 1.5 GHA Dec.	MOON GHA Dec.	Ci Par.	
0 00 10 20 30 40 50 1 00	0 / 0 / 0 / 0 / 0 / 0 / 0 / 0 / 0 / 0 /	246 38 133 45 N2 249 08 136 15 251 39 138 45 254 09 141 15 - 256 40 143 44 259 10 146 14 261 40 148 44 N2	24 17 244 09 S 0 S 246 39 249 10 251 40 254 40 254 10 256 40 24 16 259 10 S 0 S	133 37 136 07 138 38 · · ·	227 58 06 230 23 07 232 48 09 235 13 11 237 39 13	Alt. Corr.	East
10 20 30 40 50 2 00 10 20 30 40 50	198 12 200 42 203 12 205 42 208 12 210 42 N21 37 213 12 215 42 218 12 - 220 42 223 12	264 11 151 14 266 41 153 44 269 12 156 14 - 271 42 158 44 274 13 161 14	261 40 264 10 266 40 - 269 11 271 41 274 11 S 0 9 276 41 279 11 281 41 - 281 41 284 41	148 39 151 09 153 39 · · 156 10	242 29 17 244 54 18 247 20 · 20 249 45 22 252 10 24	0 57 12 55 16 55 19 54 19 53 25 52 27 50 31 48	* %
3 00 10 20 30 40 50 4 00	225 42 N21 37 228 12 230 42 233 12	294 16 181 13 296 46 183 43 299 17 186 13 - 301 47 188 43 304 17 191 13	24 15 289 12 S 0 4 291 42 294 12 - 296 42 - 299 12 301 42 24 15 304 12 S 0 4	178 43 181 13 183 43 · · · 186 14	271 32 39 273 57 40 276 22 - 42 278 47 44 281 13 46	35 47 36 46	* 400
20 30 40 50 5 00 10 20 30 40	245 42 248 12 · · · 250 42 253 12 255 42 N21 38 258 12 260 42 263 12 · · · 265 42	311 49 198 43 314 19 201 12 · 316 50 203 42 319 20 206 12 321 50 208 42 N 324 21 211 12 326 51 213 42 329 22 216 12 · 331 52 218 42	309 13 311 43 314 13 316 43 24 14 319 13 S 0 4 321 43 324 13 326 43 329 14	196 15 198 45 · · · 201 16 203 46 8 206 16 N21 48 208 47 211 17 213 47 · · · 216 18	288 28 51 290 54 53 293 19 55 295 44 57 298 09 N 4 58 300 34 5 00 303 00 02 305 25 06 307 50 06	47 39 48 38 50 37 51 36 52 35 53 34 55 32 56 32 57 31	• • •
50 6 00 10 20 30 40 50 7 00 10 20 30 40 50 8 00 10 20 30 40 50 50 8 00 10 20 30 40 50 50 60 60 60 60 60 60 60 60 60 60 60 60 60	268 12 270 41 N21 38 273 11 275 41 278 11 · . 280 41 283 11 283 11 283 11 290 41 290 41 293 11 · . 295 41 298 11 300 41 N21 39 303 11 305 41 308 11 · . 310 41 313 11	339 23 226 12 341 54 228 42 344 24 231 11 - 346 54 233 41 349 25 236 11	351 45 354 15 356 45 359 15 1 45	223 49 226 19 228 49 · · · 231 20 233 50 6 236 20 N21 48 238 51 241 21 243 51 · · · 246 22 248 52	329 37 22 332 02 24 334 28 - 25 336 53 27 339 18 29	59 29 59 28 61 28 62 27 63 25 64 25 65 24 66 22 68 21 68 20 71 19 72 18 73 17 74 16	
9 00 10 20 30 40 50 0 10 20 30 40 50 1 00 20 30 40 50 40 50 40 50 40 40 50 40 40 40 40 40 40 40 40 40 40 40 40 40	315 41 N21 40 318 11 320 41 323 11 · · · 325 41 328 11 330 41 N21 40 333 11 335 41 338 11 · · 340 41 343 11 345 41 N21 40 348 11 350 41 353 11 · · 353 41 353 11 · ·	22 00 268 40 N2 24 31 271 10 27 01 273 40 29 31 276 10 32 02 278 40 34 32 281 10 37 03 283 40 N2 39 33 286 10 42 03 288 40 44 34 291 09 47 04 293 39 49 35 296 09 52 05 298 39 N2 54 36 301 09 57 06 303 39 59 36 306 09 64 37 311 09	21 46 24 16 26 47 29 17 31 47 31 47 30 4 36 47 39 17 41 47 44 17 46 48	283 56 286 27 288 57 · · · 291 27 293 58	358 40 43 1 05 45 3 30 47 5 56 49 8 21 51 10 46 N 5 52 13 11 54 15 37 56 18 02 58 20 27 5 59 22 52 6 01	SD, ⊙ 16 SD, ℂ	- West

GREENWICH P. M. 1943 MAY 30 (SUNDAY)

GCT	O SUN GHA Dec.	Υ GHA	VENUS - 3.6 GHA Dec.	MARS O	.9 Dec.	JUPITER - 1.5 GHA Dec.	MOON GHA Dec.	1	Sun-	Twit.	Moon- rise	Diff.
h m 10 00 20 30 40 50 13 00 10 20 30 40 50 14 00 10 20 30 40 50 50	0 41 N21 41 3 11 5 41 8 11 10 41 13 11 15 41 N21 41 18 11 20 41 23 11 25 41 28 11 30 41 N21 41 31 11 35 41 36 11 40 41 43 11	67 08 69 38 72 08 74 39 77 09 82 10 82 10 84 40 87 11 89 41 92 12 94 42 97 13 99 43 102 13 104 44 107 14	316 09 318 39 321 09 · · · 323 38 326 08 328 38 N24 11 331 08 333 38 336 08 · · 338 38 341 08 343 38 N24 10 344 38 345 38 351 08 · · 353 37	64 18 S 0 66 49 69 19 71 49 · 74 19 76 49 79 19 S 0 81 49 86 50 · 89 20 91 50 94 20 S 0 99 20 101 50 · 104 21 106 51	. 42	311 30 N21 47 314 00 316 31 319 01 321 31 324 02 326 32 N21 47 329 02 331 33 334 03 336 33 339 04 341 34 N21 47 344 04 346 35 349 05 351 35 354 06	42 14 15 44 39 17 47 05 19 49 30 21 51 55 22 54 20 N 6 26 59 11 28 61 36 26 64 01 31 66 26 33	7 0 68 664 62 60 58 54 52 50 45 35 30	1 25 2 05 33 2 54 3 11 25 38 49 3 58 4 18 35 4 48 5 00 20	# □□≥≥15 115 80 65 56 42 37 32 22 27 24 23	2 144 19 23 26 30 32 355 37 39 40 42 46 48 51 53 2 57	1 1 1 2 2 2 2 2 2
15 00 10 20 30 40 50 16 00 10 20 30 40 50	45 41 N21 42 48 11 50 41 53 11 · · · 55 41 58 11 60 41 N21 42 63 11 65 41 68 11 · · 70 41 73 11 73 11 75 41 X21 43	114 45 117 16 119 46 122 17 124 47 127 17 129 48 132 18 134 49 137 19 139 49	1 07	111 51 114 21 116 51 · 119 21 121 51 124 22 S 0 126 52 129 22 131 52 · 134 22 136 52	. 40	356 36 N21 47 359 06 1 37 4 07 · · · 6 37 9 08 11 38 N21 47 14 08 16 39 19 09 · · 21 39 24 10 26 40 N21 47	85 48 47 88 13 49 90 30 51 93 04 52 95 29 54 97 54 N 6 56 100 20 57 102 45 6 59 105 10 7 01 107 35 00 04	10 20 30 35 40 45 50 52 54	38 5 54 6 09 26 46 6 57 7 10 25 43 7 52 8 02 13	23 24 26 28 30 33 37 38 41 44	3 01 04 08 11 15 18 21 24 28 29 31 34	4 5 5 5 6 6 6 7 7
10 20 30 40 50 18 00 10 20	78 11 80 40 83 10 · · · 85 40 88 10 90 40 N21 43 93 10 95 40	144 50 147 21 149 51 152 22 154 52 157 22 159 53 162 23	31 06 33 36 36 06 38 36 41 06 43 36 N24 09 46 06 48 36	141 52 144 23 146 53 • 149 23 151 53 154 23 S 0 156 53 159 23		29 10 31 41 34 11 · · · 36 41 39 12 41 42 N21 47 44 12 46 43	114 51 08 117 16 10 119 41 11 122 07 13 124 32 15 126 57 N 7 17 129 22 18 131 47 20	58 60 S	26 8 41 Sun- set	48 53	36 3 38 Moon-	7 8
30 40 50 19 00 10 20 30 40 50 20 00 10 20 30 40	98 10 · · · · · · · · · · · · · · · · · ·	174 55 177 26 179 56 182 26 184 57 187 27 189 58 192 28 194 59 197 29	51 06 53 35 56 05 58 35 N24 08 61 05 63 35 66 05 68 35 71 05 73 35 N24 08 76 05 78 35 81 05	171 54 174 24 176 54 • 179 24 181 54 184 25 S 0 186 55 189 25 191 55 • 194 25		49 13 · 51 43 · 54 14 N21 47 59 14 61 44 64 15 · 66 45 69 15 71 46 N21 47 74 16 76 46 79 17 · 81 47	143 54 29 146 19 30 148 44 32 151 09 34 153 34 35 7 156 00 N 7 37 158 25 39 160 50 41 163 15 42 165 41 44	66 64 62 60 58 56 54 52	21 52 24 21 02 20 44 30 17 20 06 19 57	m 日 記 120 80 65 57 51 45 42	h m 16 48 40 33 26 22 17 13 10 06 04	8 7 7 7 7 7 7
21 00 10 20 30 40 50 22 00 10 20 30 40 50 20 30 40 50 23 00 10 20 30 30	133 10 135 40 N21 44 138 10 140 40 143 10 · · 145 40 148 10 150 40 N21 45 153 10 155 40 158 10 · · 160 40 163 10 170 40 170 40 173 10 · ·	205 00 207 31 210 01 212 31 215 02 217 32 220 03 222 33 225 03 227 34 230 04 232 35	93 34 96 04 · · · 98 34 101 04 103 34 N24 07 103 04 110 04 · · · · · · · · · · · · · · · · · ·	196 55 199 25 S 0 201 55 204 26 206 56 • 2 209 26 211 56 214 26 S 0 216 56 219 26 221 57 • 224 27 224 27	. 35	89 18 91 48 94 19 96 49 99 19 101 50 N21 47 104 20 106 50 109 21 111 51 114 21	168 06 46 170 31 N 7 48 172 56 49 175 22 51 177 47 53 180 12 54 182 37 56	40 35 30 20 10 0 10 20 30 35 40 45 50 52	18 55 34 17 18 01 17 44 27 17 08 16 57 44 28 10 16 01 15 51	23 22 23 24 26 28 30	15 55 50 47 43 37 32 27 22 16 10 0 14 59 53 51 4 45	4 4 3 3 3 3 3 2 2 2 2 2

CONVERSION OF ARC TO TIME

•	h	m	•	h	m		h	m	۰	h	m	•	h	m	•	h	m	,	m	8	"	
0 1 2 3 4		4	60 61 62 63 64	4 4 4		120 121 122 123 124		4	180 181 182 183 184	12 12 12 12 12	8 12	240 241 242 243 244	16 16 16	0 4 8 12 16	300 301 302 303 304	20 20 20	0 4 8 12 16	0 1 2 3 4	0		0 1 2 3 4	0.0 0.0 0.1 0.2 0.2
5 6 7 8 9	0	20 24 28 32 36	65 66 67 68 69	4 4	20 24 28 32 36	125 126 127 128 129	8 8	20 24 28 32 36	185 186 187 188 189	12 12 12 12 12	24 28 32	245 246 247 248 249	16 16 16	20 24 28 32 36	305 306 307 308 309	20 20 20	20 24 28 32 36	5 6 7 8 9	0 2 0 2 0 3 0 3	8 2	5 6 7 8 9	0.3 0.4 0.4 0.6
10 11 12 13 14	0	40 44 48 52 56	70 71 72 73 74	4 4	40 44 48 52 56	130 131 132 133 134	8 8	40 44 48 52 56	190 191 192 193 194	12 12 12	44 48 52	250 251 252 253 254	16 16 16	40 44 48 52 56	310 311 312 313 314	20 20 20	40 44 48 52 56	10 11 12 13 14	0 4 0 4 0 5 0 5	8 2	10 11 12 13 14	0.0 0.1 0.1 0.1
15 16 17 18 19		4	75 76 77 78 79	5 5 5		135 136 137 138 139	9 9	4	195 196 197 198 199	13 13 13		255 256 257 258 259			315 316 317 318 319	21 21 21	0 4 8 12 16	15 16 17 18 19	1		15 16 17 18 19	1.0 1.1 1.1 1.1
20 21 22 23 24	1 1	20 24 28 32 36	80 81 82 83 84	5 5 5	20 24 28 32 36	140 141 142 143 144	9 9	20 24 28 32 36	200 201 202 203 204	13 13 13	20 24 28 32 36	260 261 262 263 264	17 17 17	20 24 28 32 36	320 321 322 323 324	21 21 21	20 24 28 32 36	20 21 22 23 24	1 2 1 2 1 3 1 3 1 3	24 28 32	20 21 22 23 24	1. 1. 1. 1.
25 26 27 28 29	1 1 1	40 44 48 52 56	85 86 87 88 89	5 5 5	40 44 48 52 56	145 146 147 148 149	9 9	40 44 48 52 56	205 206 207 208 209	13 13 13	40 44 48 52 56	265 266 267 268 269	17 17 17	40 44 48 52 56	325 326 327 328 329	21 21 21	40 44 48 52 56	25 26 27 28 29	1414	18	25 26 27 28 29	1. 1. 1. 1.
30 31 32 33 34		4	90 91 92 93 94	6		150 151 152 153 154	10 10 10	4	210 211 212 213 214	14 14	8 12	270 271 272 273 274		4	330 331 332 333 334	22 22 22		30 31 32 33 34	2		30 31 32 33 34	2. 2. 2. 2. 2.
35 36 37 38 39	2 2 2	20 24 28 32 36	95 96 97 98 99	6 6	20 24 28 32 36	155 156 157 158 159	10 10 10	20 24 28 32 36	215 216 217 218 219	14 14 14	24 28	275 276 277 278 279	18 18 18	20 24 28 32 36	335 336 337 338 339	22 22 22	20 24 28 32 36	35 36 37 38 39	2 2	28	35 36 37 38 39	2. 2. 2. 2.
40 41 42 43 44	2 2 2	40 44 48 52 56	100 101 102 103 104	6 6	40 44 48 52 56	160 161 162 163 164	10 10 10	40 44 48 52 56	220 221 222 223 224	14 14 14	40 44 48 52 56	280 281 282 283 284	18 18 18	40 44 48 52 56	340 341 342 343 344	22 22 22	40 44 48 52 56	40 41 42 43 44	2 4 2 4 2 5 2 5 2 5	8	40 41 42 43 44	2. 2. 2. 2. 2.
45 46 47 48 49	3	8	105 106 107 108 109	7 7 7	0 4 8 12 16	165 166 167 168 169	11 11 11	8 12	225 226 227 228 229	15 15	8 12	285 286 287 288 289	19 19 19	8 12	345 346 347 348 349	23 23 23	4	45 46 47 48 49	3 3 3 3 3 3		45 46 47 48 49	3. 3. 3. 3.
50 51 52 53 54	333	20 24 28 32 32 36	110 111 112 113 114	7 7 7	20 24 28 32 36	170 171 172 173 174	11 11 11	20 24 28 32 36	230 231 232 233 234	15 15 15	20 24 28 32 36	290 291 292 293 294	19 19 19	20 24 28 32 36	350 351 352 353 354	23 23 23	20 24 28 32 36	50 51 52 53 54	3 2	24 28 32	50 51 52 53 54	3. 3. 3. 3.
55 56 57 58 59	3	40 44 48 52 56	115 116 117 118 119	7 7 7	40 44 48 52 56	175 176 177 178 179	11 11 11		235 236 237 238 239	15 15 15	44 48 52	295 296 297 298 299	19 19 19	40 44 48 52 56	355 356 357 358 359	23 23 23	40 44 48 52 56	55 56 57 58 59	3 4 3 4	14 18 52	55 56 57 58 59	3. 3. 3. 3.
60	4	0	120	8	0	180	12	0	240	16	0	300	20	0	360	24	0	60	4	0	60	4.0

POLARIS

LHAT Corr.	LHAT Corr.	LHAT Corr.	LHAT Corr.	LHAT Corr.	LHAT Corr
. , ,	. , ,	0 1 1	. , ,	. , ,	. , ,
358 56 - 54	89 43 90 46 26	128 40 129 39 14	178 28 + 54 180 37 + 54	270 37 + 26 271 41 + 26	309 39 -14 310 37 -14
3 20 56	91 48 24	130 38 1 16	182 56 + 55	272 43 + 25	311 36 18
5 52-56 8 45-57	92 50 23	131 37 + 17	188 27 + 57	274 48 23	313 34-17
16 47 - 59	94 53 -21	133 30 + 19	196 37+59	276 50+21	314 34-19
35 41 50	96 53 - 20 97 53 - 19	135 37 + 20 136 38 + 21	215 51 + 50	277 51 + 20	316 34 - 20 317 34 - 21
40 16 58 43 42 57	98 53 17	137 39 + 22	224 00 + 58	279 51 17	318 35 25
49 07-56	100 51-16	139 44+24	220 30 + 56	281 49+16	319 37 -24
51 25 55	101 50 - 15 102 48 - 14	140 46 + 25 141 50 + 26	231 51 + 55 233 59 + 54 233 59 + 53	282 48+15 283 47+14	321 41 -25 322 44 -26
55 30 53	103 47 13	142 54 27	236 00 50	284 46 13	323 48 2
59 07-51	104 45 -11	145 04+29	230 40+51	286 42+11	324 52 -29
60 48 - 50 62 25 - 49	106 40 - 10 107 38 - 9	146 10 + 30 147 16 + 31	241 23+50 243 01+49	287 40 + 10 288 37 + 9	327 02 - 30 328 08 - 31
63 59 48	108 35 7	148 24 + 32	244 36 + 48	289 35 7 8	329 15 32
65 29 46 66 57 46	109 32 6 110 30 6	149 32+34 150 42+34	246 08+46 247 36+45	290 32 + 6 291 30 + 6	331 31 34
68 22 -44	111 27 - 4	151 52+36	250 26+44	292 27 + 4	332 41 -36
71 05 -43 72 24 -42	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	154 16+37 155 30+38	251 48+43 253 08+42	294 21 + 3 295 18 + 2	335 03 - 37 336 16 - 38
73 41 41	115 15 1	156 45 + 39	254 26 41	296 15 + 1	337 30 30
74 57 39 76 11 39	116 12 + 1 117 09 + 1	150 10+41	256 59+39	297 12 - 1	340 03-41
79 26-37	110 00+ 3	160 39 + 42 162 01 + 43	258 11 + 38 259 24 + 37	299 06 - 2 300 03 - 3	341 22 - 42 342 43 - 43
79 46 35	120 00 4	163 25 + 44	260 35 + 36	301 00 4	344 06 4
80 56 34 82 05 33	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	164 51 + 46 166 20 + 47	262 55 + 34	301 57 6 302 55 7	345 31 46 346 58 4
83 12 - 32	122 52 + 8	167 51 +48	265 11+32	303 52 8	348 28 -48
85 25 31 30	124 47 + 9 125 45 + 10	$171 04 + 49 \\ 172 47 + 50$	266 17+31 267 23+30	305 47 9 306 45 10	351 39 - 49 353 20 - 50
87 36 29	126 43 112	174 34 51	268 29 29	307 43 11	355 06 51
88 40 - 27 89 43 - 27	127 42+12 128 40+13	176 27 + 52 178 28 + 53	269 33+28 270 37+27	308 41 12 13	356 57 53 358 56 53

LHAT measured westward. Refraction not included: Use Table A.

ADDITIONAL STARS

Name	Mag.	SHA	Dec.
		0 /	0 /
Alkaid	1. 9	153 40	N49 36
γ Argus	1. 9	238 04	S47 10
& Can. Maj . †	2. 0	253 29	S26 18
Castor	1. 6	247 16	N32 01
β Centauri	0. 9	150 03	S60 06
El Nath t	1. 8	279 20	N28 34
γ Gem †	1. 9	261 24	N16 27
Orionis †	1. 9	275 32	S 1 58
Schedir	2. 1-2. 6	350 41	N56 13

† The planetary section of the Astronomical Navigation Tables may be used for these stars.

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STARS

	Alphabeti	cal order			Order	of SHA	
Name	Mag.	зна	Dec.	SHA	Dec.	RA	Name
Acamar Achernar 1 Acrux 2 Adhara † Aldebaran 3	0. 6 1. 1 1. 6	315 59 336 06 174 08 255 54 291 50	840 32 S57 31 S62 47 S28 54 N16 24	14 31 16 22 28 50 34 39 50 07	N14 54 S29 55 S47 14 N 9 37 N45 05	23 02 22 55 22 05 21 41 20 40	Markab Fomalhaut Al Na'ir Enif Deneb
Alioth Al Na'ir Alnilam † Alphard † Alphecca †	. 2. 2 1. 8 2. 2	$\begin{array}{ccc} 167 & 07 \\ 28 & 50 \\ 276 & 40 \\ 218 & 48 \\ 126 & 56 \end{array}$	N56 16 S47 14 S 1 14 S 8 25 N26 54	54 42 63 00 77 04 81 14 84 54	S56 55 N 8 43 S26 22 N38 44 S34 25	20 21 19 48 18 52 18 35 18 20	Peacock Altair Nunki Vega Kaus Aust.
Alpheratz 4 Al Suhail Altair 5 Antares 6 Arcturus 7	2. 2 0. 9 1. 2	358 38 223 32 63 00 113 31 146 44	N28 47 S43 12 N 8 43 S26 10 N19 29	$\begin{array}{ccc} 91 & 10 \\ 96 & 55 \\ 97 & 33 \\ 103 & 13 \\ (109 & 20) \end{array}$	N51 30 N12 36 S37 04 S15 39 S68 56	17 55 17 32 17 30 17 07 16 43	Etamin Rasalague Shaula Sabik α Tri. Aust.
Argus † Bellatrix † Betelgeux 8 Canopus 9 Capella 10	1. 7 0. 1-1. 2 - 0. 9	234 40 279 29 271 59 264 20 281 53	S59 20 N 6 18 N 7 24 S52 40 N45 56	113 31 120 45 126 56 (137 17) 141 04	S26 18 S22 28 N26 54 N74 24 S60 36	16 26 15 57 15 32 14 51 14 36	Antares Dschubba Alphecca Kochab Rigil Kent.
'aph	. 2. 3 1. 5 1. 6	358 28 149 10 168 54 173 00 50 07	N58 50 836 06 859 23 856 48 N45 05	146 44 149 10 159 27 159 35 167 07	N19 29 S36 06 S10 52 N55 14 N56 16	14 13 14 03 13 22 13 22 12 52	Arcturus θ Centauri Spica Mizar Alioth
Deneb Kait † Denebola † Dschubba Dubhe 12 Enif	2. 2 2. 5 2. 0	349 49 183 28 120 45 194 57 34 39	S18 18 N14 53 S22 28 N62 04 N 9 37	168 54 173 00 174 08 183 28 194 57	S59 23 S56 48 S62 47 N14 53 N62 04	12 44 12 28 12 23 11 46 11 00	β Crucis γ Crucis Acrux Denebola Dubhe
Ctamin Fomalhaut . 13 Iamal † Kaus Aust Kochab	1.3 2.2 2.0	91 10 16 22 329 01 84 54 (137 17)	N51 30 S29 55 N23 12 S34 25 N74 24	208 40 218 48 (221 52) 223 32 234 40	N12 15 S 8 25 S69 29 S43 12 S59 20	10 05 9 25 9 13 9 06 8 21	Regulus Alphard Miaplacidus Al Suhail • Argus
darfak darkab diaplacidus . dizar Vunki	2. 6 1. 8 2. 4	309 56 14 31 (221 52) 159 35 77 04	N49 39 N14 54 S69 29 N55 14 S26 22	244 33 245 55 255 54 259 21 264 20	N28 10 N 5 22 S28 54 S16 38 S52 40	7 42 7 36 6 56 6 43 6 23	Pollux Procyon Adhara Sirius Canopus
Peacock 14 Polaris Pollux 15 Procyon 16 Rasalague †	2. 1 1. 2 0. 5	54 42 (333 51) 244 33 245 55 96 55	S56 55 N88 59 N28 10 N 5 22 N12 36	271 59 276 40 279 29 281 53 282 03	N 7 24 S 1 14 N 6 18 N45 56 S 8 16	5 52 5 33 5 22 5 12 5 12	Betelgeux Alnilam Bellatrix Capella Rigel
tegulus 17 tigel 18 tigil Kent. 19 tuchbah 1 abik 1	0.3 0.3 2.8	208 40 282 03 141 04 339 29 103 13	N12 15 S 8 16 S60 36 N59 56 S15 39	291 50 309 56 315 59 329 01 (333 51)	N16 24 N49 39 S40 32 N23 12 N88 59	4 33 3 20 2 56 2 04 1 45	Aldebaran Marfak Acamar Hamal Polaris
haula 20 pica 21 Tri. Aust	1. 2 1. 9	97 33 259 21 159 27 (109 20) 81 14,	S37 04 S16 38 S10 52 S68 56 N38 44	336 06 339 29 349 49 358 28 358 38	S57 31 N59 56 S18 18 N58 50 N28 47	1 36 1 22 0 41 0 06 0 05	Achernar Ruchbah Deneb Kait Caph Alpheratz

 $SHA = 360^{\circ} - RA$

 $GHA* = GHA\gamma + SHA*$

May-Aug., 1943



INTERPOLATION OF GHA

	SU	'N, PLANETS,	Ψ		MOON	
Int.	Corr.	Int, Corr.	Int. Corr.	Int. Corr.	Int. Corr.	Int. Corr.
111 8	0 1	111 8 0 1	111 8 . /	711 8 0 1	111 8 0 1	m 8 0
00 00	0 00	03 17 0 50	06 37 1 40	00 00 0 00	03 20 0 49	06 39 1 37
01	0 01	21 0 50 25 0 51	41 1 41	02 0 01	24 0 50	40 1 36
05	0 02		40 1 49	06 0 02	29 0 51	47 1 30
09	0 03	20 0 50	49 1 49	10 0 03	33 0 59	34 1 40
13	0 04	00 0 54	33 1 14	14 0 03	37 0 52 1 0 53	30 1 41
17			3/ 1 1-			07 00 1 42
21	0 05	41 0 55	07 01 1 40	22 0 05		
25 29	0 06 0 07	45 0 56	05 1 46	26 0 06		08 1 43
29		49 0 57	09 1 47	31 0 07	53 0 56	
33	0 08	53 0 58	13 1 48	35 0 08	58 0 57	16 1 45
37	0 09	57 0 .00	17 1 49	39 0 09	04 09 0 00	20 1 46
41	0 10	04 01 100	21 1 00	43 0 10	06 0 09	25 1 47
45	0 11	05 1 01	95 1 01	47 0 11	10 1 00	90 1 40
49	0 12	00 1 02	90 1 02	-, 0 12	14 1 01	33 1 49
53	0 13	13 1 03	22 1 00	55 0 10	10 1 02	97 1 00
57	0 14	17 1 04	37 1 04	01 00 0 14	99 1 03	41 1 01
01 01	0 15	21 1 00	41 1 00	04 0 19	97 1 04	45 1 34
05	0 16	25 1 06	45 1 00	08 0 10	31 1 00	40 1 00
09	0 17	90 1 07	49 1 07	19 0 17	25 1 00	54 1 34
13	0 18	33 1 08	59 1 08	16 0 18	30 1 01	58 1 06
17	0 19	37 1 09	E7 1 09	20 0 19	49 1 08	08 09 1 96
21	0 20	41 1 10	08 01 2 00	24 0 20	47 1 09	06 1 0
21 25	0 21	45 1 11	05 2 01	20 0 21	51 1 10	10 1 00
29	0 22	40 1 12	09 2 02	22 0 22	FC 1 11	14 1 38
33	0 23	53 1 13	13 2 03	97 0 23	0= 00 1 12	10 2 00
37	0 24	57 1 14	17 2 04	41 0 24	05 00 1 13	29 4 01
41	0 25	05 01 1 15	21 2 05	45 0 20	08 1 14	27 2 02
45	0 26	05 1 16	25 2 06 25 2 07	40 0 20	12 1 15	31 2 03
49	0 27	09 1 17	29 2 07	F9 U 21	16 1 16	35 2 0-
53	0 28		33 2 08	E0 U 28	20 1 16	39 2 03
57	0 29	13 1 19	37 2 09	02 02 0 29	20 1 18 25 1 18	43 2 06
	0 30	17 1 20	2 10	02 02 0 30	20 1 10	43 2 07
	0 31	21 1 21	41 2 11	00 0 31	29 1 20	47 2 08
05	0 32	25 1 22	45 2 12	10 0 32	33 1 21	52 2 09
09	0 33	29 1 23	49 2 13	14 0 22	01 1 99	56 2 10
13	0 34	33 1 24	53 2 13	10 0 24	41 1 23	09 00 2 11
17	0 35	01 1 25	57 2 15	44 0 25	40 1 94	04 2 12
21	0 36	41 1 26	09 01 2 16	20 0 20	49 1 95	08 2 12 08 2 13
25	0 37	40 1 97	05 2 17	31 0 27	04 1 96	12 2 14
29	0 38	49 1 99	09 2 18	30 0 26	00 1 97	16 2 14 21 2 15
33	0 39	00 1 00	13 2 19	00 0 20	00 02 1 98	21 2 16
37	0 40	0/ 1 20	11 9 90	40 0 40	00 1 20	25 2 17
41	0 41	06 01 1 31	21 2 21	41 0 41	10 1 30	49 0 10
45	0 42	00 1 39	25 2 22	01 0 40	14 1 21	33 2 18
49	0 43	09 1 32	29 2 23	99 0 12	10 1 20	37 2 20
53	0 44	10 1 24	33 9 94	03 00 0 44	20 1 22	41 2 21
57	0 45	17 1 25	37 2 25	04 0 45	21 1 21	40 9 90
03 01	0 46	21 1 26	41 2 26	00 0 46	01 1 25	50 2 23
05	0 47	20 1 27	45 2 27	12 0 47	30 1 26	54 2 24
09	0 48	29 1 20	49 2 28	16 0 49	39 1 27	90 0 01
13	0 48	33 1 20	53 2 28	20 0 10	43 1 37	10 00 2 2
17		3/ 1 40	01 0 00	24 0 49		
21	0 50	41 1 40	10 00 2 30			

Correction to be added to GHA for interval of GCT

DIP

Subtract from altitude observed with sea horizon.

Height	Corr.	Height	Corr.	Height	Corr.	Height	Corr
Ft. 0 2 6 6 12 21 31 33 58 75 93 114 137 162	, 1 2 3 4 5 6 7 8 9 10 11 12	Ft. 160 180 210 250 280 310 350 390 430 4520 570 620	13 14 15 16 17 18 19 20 21 22 23 24	Ft. 620 670 730 780 840 900 960 1030 1160 1230 1310 1380	25 26 27 28 29 30 31 32 33 34 35 36	Ft. 1380 1460 1540 1620 1700 1790 1870 1960 2060 2150 2250 2340 2440	37 38 39 40 41 42 43 44 45 46 47 48

REFRACTION

A. Total correction.—For use with H. O. 208, H. O. 209, H. O. 211, H. O. 214, and the Polaris Table. Subtract from observed altitude.

Height in feet	Observed altitude										
.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	5°	10°	15°	20°	30°	45°	60°				
	,	,	,	,	,	- 0	,				
0	10	5	4	3	2	1	1				
5,000	8	5 5	3	2 2	1	1	Ō				
10,000	7		3	2	1	1	0				
15,000	6	4 3 3 2	2 2	2	1	1	0				
20,000	5	3	2	1	1	1	0				
25,000	4		2	1	1	0	0				
30,000	3	2	1	1	1	0	0				
35,000	3	2	1	1	1	0	0				
40,000	2	1	1	1	0	0	0				

GLOSSARY OF NAVIGATION TERMS

- AGONIC LINE—Line connecting points of zero magnetic variation.
- AIR NAVIGATION—Determining, and keeping an account of, an aircraft's position while flying from point to point.
 - Pilotage—Navigation with reference to visible ground objects.
 - Dead Reckoning Navigation based on known values of time, speed, distance and direction.
 - Radio—Navigation by use of radio aids such as radio ranges, marker beacons and direction finding stations.
 - Celestial—Navigation with reference to the positions of the celestial bodies.
- AIR SPEED—Speed of an aircraft with reference to the surrounding air.
 - Indicated—Air speed shown by the air speed indicator.
 - Calibrated—Indicated air speed corrected for instrument and installation errors.
 - **True**—Calibrated air speed corrected for temperature and pressure (altitude).
- ALTITUDE (celestial) Angular distance from the celestial horizon to the center of a celestial body measured upon the vertical circle passing through the body. It is also the angle at the center of the earth subtended by this arc.
- ALTITUDE INTERCEPT—Angular difference between computed altitude of a body and its observed (true) altitude. Distance (in nautical miles) of observer's line of position from his assumed position.
- ASTRONOMICAL TRIANGLE—Triangle on the celestial sphere bounded by the hour and vertical circles through a body, and the observer's (celestial) meridian.
- **AZIMUTH**—The angle at the zenith (or arc of the horizon) measured from the observer's meridian to the vertical circle

passing through a body. It is measured from the North branch of the meridian if observer is in North latitude and from the South branch if he is in South latitude, and toward the East if body is rising or West if body is setting, through 180°.

AXIS

- Earth—Centerline about which the earth
- **Celestial Sphere**—Earth's axis extended to the celestial sphere.
- **BEARING**—Direction of one object to another measured clockwise through 360°.
 - Relative—Direction of an object with reference to the centerline of the aircraft.
 - True—Direction of an object with reference to true North.
 - Magnetic—Direction of an object with reference to magnetic North.
- CHART—Representation of the earth's surface, or a portion thereof, on a flat surface.

 Maps are primarily concerned with the land, while charts usually supply information about water and land bounded by water.
- on the earth's surface from which any observer will observe a given celestial body at the same altitude for a given instant of time.
- **COLLIMATION**—Act of bringing a celestial body and bubble into coincidence in the field of an aircraft octant.
- COURSE-Intended track.
 - **True**—Course measured with reference to true North.
 - **Magnetic**—Course measured with reference to magnetic North.
 - Compass—Course measured with reference to compass North (direction in which compass needle points).



- **DECLINATION** Arc of the hour circle measured from the equinoctial to the celestial body, North or South through 90°.
- DEVIATION Influence of local magnetic disturbances within the aircraft on the magnetic compass needle, causing the needle to point to other than magnetic North. The angular difference between magnetic North and compass North, which changes with heading of aircraft.

DIP

- **Compass** Deflection of compass needle from the horizontal due to the influence of the vertical component of the earth's magnetic field.
- Celestial A sextant altitude correction caused by depression of the horizon in proportion to aircraft's height. Must be considered when using sea horizon as horizontal reference plane.
- **DRIFT**—Effect of crosswind. (Also see DRIFT ANGLE.)
- **DRIFT ANGLE**—Angular difference between heading and track.
- **DRIFT CORRECTION ANGLE** Angular difference between heading and course.
- **ECLIPTIC**—Path of earth in its revolution around the sun, or path of sun in its *apparent* revolution around the earth.
- **EQUATOR**—Great circle on the earth's surface lying midway between the poles. Used as reference line for the measurement of latitude.
- **EQUINOCTIAL**—Projection of the earth's equator onto the celestial sphere. Reference line for the measurement of declination.
- **EQUINOX**—Intersection of the equinoctial and the ecliptic.
 - Vernal—Point where the sun changes declination from South to North (First Point of Aries).
 - Autumnal—Point where the sun changes declination from North to South (First Point of Libra).
- FIRST POINT OF ARIES—(See Equinox, Vernal).

- FIX—Geographical location of aircraft as determined by two or more lines of position.
- **GEOGRAPHICAL POSITION**—Point where a line connecting the center of the earth with a body would intersect the surface of the earth.
- **GREAT CIRCLE**—Circle on the surface of a sphere, the plane of which passes through the center of the sphere.
- **GROUND SPEED**—Speed of the aircraft with reference to the ground.
- **HEADING**—Direction in which the aircraft is pointed.
 - True-Heading with reference to true North.
 - Magnetic—Heading with reference to magnetic North.
 - Compass—Heading with reference to compass North.

HORIZON

- Celestial (true) Great circle on the celestial sphere, the plane of which is perpendicular to the zenith-nadir line.
- Observer's—Plane passing through the eye of the observer, parallel to the celestial horizon.
 - **Note:** Celestial horizon and observer's horizon are so close, relatively, that for observations of all celestial bodies other than the moon they are considered to coincide.

HOUR ANGLE

- Local—An arc of the equinoctial measured from the observer's meridian (upper branch) to the hour circle passing through a celestial body, over West through 360°.
 - Note: When used as an argument to enter II. O. 214 (or any other table of precomputed solutions of the astronomical triangle), local hour angle is measured only through 180° and is then named East if the body is East of the observer, and West if it is West of him.
- Greenwich—Arc of the equinoctial measured from the Greenwich meridian to the hour circle passing through the celestial body, over West through 360°.
- Sidereal—Arc of the equinoctial measured from the First Point of Aries to the hour



- circle passing through the body, over West through 360°.
- HOUR CIRCLE—Great circle on the celestial sphere passing through both poles and a celestial body.
- INDEX CORRECTION—Angular amount by which the counter on a sextant or octant is in error in recording the altitude of a body due to misalignment of index glass and arm, slippage or other mechanical faults within the instrument.
- INSTRUMENT CORRECTION—Total angular correction which must be applied to each altitude reading because of index and bubble error in a sextant or octant.
- **ISOGONIC LINE**—Line connecting points of equal magnetic variation.
- **KNOT**—Unit of speed equal to one nautical mile per hour.
- **LATITUDE** Angular distance North and South of the equator measured in degrees of arc from 0° to 90°.

LINE OF POSITION

- General—Straight line on the earth's surface representing all possible positions of an aircraft at a given instant of time.
- Celestial—Small arc of a circle of equal altitude on which the observer is located. For short distances this arc is considered to be a straight line.
- **LONGITUDE** Angular distance East and West of the prime meridian, measured in degrees of arc from 0° to 180°.
- **MAP**—(see CHART).
- **MERIDIAN**—Great circle on the earth's surface passing through both poles. Projected onto the celestial sphere it becomes a celestial meridian.
 - Prime (Greenwich)—Meridian used as reference line for the measurement of longitude. Passes through Greenwich, England.
 - Observer's—Meridian passing through the observer's position.
- **NADIR**—Point on the celestial sphere directly beneath the observer.
- **NAUTICAL MILE**—Unit of distance equal to approximately 6080 feet, or one minute

- of arc of a great circle on the earth's surface, hence one minute of latitude, or one minute of longitude at the equator.
- OCTANT—Instrument used to measure the altitudes of celestial bodies. Specifically, one capable of measuring angles up to and including 90°. However, as commonly used, the term is synonymous with the term "sextant."
- PARALLAX—Angle subtended at the center of the moon by the radius of the earth.
- PARALLEL (of latitude)—Division of latitude parallel to the equator. Parallels are small circles.
- PELORUS—A dummy compass card equipped with sighting vanes for taking bearings on terrestrial or celestial objects.

POLES

- Earth-Ends of the earth's axis.
- **Celestial**—Earth's poles projected onto the celestial sphere.
- POLAR DISTANCE—Arc of the hour circle intercepted between a celestial body and the elevated pole. One side of the astronomical triangle. Equal to 90° minus declination of the body.
- RADIUS OF ACTION—Distance an aircraft can fly with a given amount of fuel and under given wind conditions and still return to the same or an alternate base.
- RHUMB LINE—Line which intersects all meridians at the same angle.

REFRACTION

- **General**—Bending of light as it passes from one medium to another of different density.
- Celestial—Bending of light rays from a celestial body on entering the earth's atmosphere, causing an error in measuring the altitude of the body.
- RIGHT ASCENSION—An arc of the equinoctial lying between the First Point of Aries and the hour circle passing through a body, measured East through 24 hours.
- **SOLSTICE**—Point of maximum declination of the sun. If maximum northerly declination it is known as summer solstice; if maximum southerly declination, it is winter solstice.



SPHERE

General—A body bounded by a surface, all points of which are equidistant from a point within called the center.

Celestial—A theoretical globe of infinite radius whose point of origin is considered to be the center of the earth.

SEMIDIAMETER—A sextant altitude correction which must be taken into account when using either the upper or lower limb (edge) of the sun or moon to achieve collimation. Ordinarily, therefore, this correction applies only to observations made with a marine sextant.

SEXTANT—Same as Octant except that it is capable of measuring angles up to 120°. Term commonly used to signify any type of altitude-measuring instrument.

SMALL CIRCLE—Circle on the earth's surface, the plane of which does not pass through the center of the earth.

STATUTE MILE—An arbitrary unit of distance equal to 5280 feet.

TRACK—Actual path made good by an aircraft over the ground.

True—Track measured with reference to true North.

Magnetic—Track measured with reference to magnetic North.

Compass—Track measured with reference to compass North.

Great Circle—Shortest distance between two points on the earth's surface.

TIME-Lapse between two events.

Solar (Apparent)—Time derived from passage of the true sun.

Civil (Mean)—Time derived from passage of the mean sun (an imaginary sun which is considered to move along the equinoctial at a constant rate throughout the year).

Sidereal (Star)—Time derived from passage of the First Point of Aries (or a star).

VARIATION — Angular difference between true North and magnetic North. Caused by the fact that true (geographic) North and magnetic North are not located at the same position on the earth's surface. Changes with aircraft's geographical position.

VECTOR—Any quantity having direction and magnitude which are represented graphically by a directed straight line segment. In navigation the principal vector quantities considered are heading and air speed of the aircraft, track (intended or actual) and ground speed, and the direction and velocity of the wind.

VERTICAL CIRCLE — Great circle on the celestial sphere passing through zenith, nadir and a celestial body.

ZENITH—Point on the celestial sphere directly above the observer.

Distance—Arc of the vertical circle lying between the celestial body and zenith. Equal to 90° minus altitude of the body. One side of the astronomical triangle.







ABBREVIATIONS

a	Altitude intercept	Corr.	Correction
alt. (or h)	Altitude	D.A.	Drift angle
A.M.	Antemeridian or forenoon	dec.	Declination
A.S.	Air speed	dist.	Distance
Az	Azimuth	DLo	Difference of longitude
C	Course	Dep.	Departure
Cel.	Celestial	Dev.	Deviation
C.A.S.	Calibrated air speed	DL	Difference of latitude
CC	Compass course	DR	Dead Reckoning
CE	Compass error	E	East
CH	Compass heading	ETA	Estimated time of arrival

GLOSSARY OF NAVIGATION TERMS

G.P.	Geographical position	SHA
GAT	Greenwich apparent time	TH
GCT	Greenwich civil time	T.A.S.
GHA	Greenwich hour angle	Temp.
G.S.	Ground speed	TC
GST	Greenwich sidereal time	Tk
HA	Hour angle	T/t
h(H)	Altitude	Var.
hc	Computed altitude	W
$h_{\mathbf{O}}$	True (observed) altitude	Z
hs	Sextant or octant altitude	Zd
I.A.S.	Indicated air speed	ZD
I.C.	Instrument correction	$Z_{\mathbf{n}}$
Kts	Knots	1976
Lat.	Latitude	
Long.	Longitude	ZT
m	Difference of meridional parts	
M	Meridional parts	
min.	minutes (of time)	
MH	Magnetic heading	
Mag.	Magnetic	
MC	Magnetic course	0
m.p.h.	Miles per hour (statute miles)	•
MTr	Meridian transit	*
N	North	0
Na.	Nadir	ত
L.O.P.	Line of position	T
NM	Nautical miles	
P	Pole	ø
Pd	Polar distance	λ
par.	Parallax	β
P.M.	Postmeridian or afternoon	Δ
$P_{\mathbf{n}}$	North celestial pole	γ
PN	Point of no return	
$P_{\mathbf{S}}$	South celestial pole	
R.A.	Radius of action	
RA	Right ascension	
R.B.	Relative bearing	
Ref.	Refraction	
S	South	
570		

SHA	Sidereal hour angle
TH	True heading
T.A.S.	True air speed
Temp.	Temperature
TC	True course
Tk	Track
T/t	Time to turn
Var.	Variation
W	West
Z	Zenith
Zd	Zenith distance
ZD	Zone description
Z _n	True bearing of a celestial body (measured from true north through 360°)
ZT	Zone time



SYMBOLS

- ⊙ The sun

 The moon
- * A star or planet
- 2 Altitude lower limb
- o Altitude upper limb
- Y Vernal Equinox or First Point of Aries
- ø Bearing (Phi)
- λ Longitude (Lambda)
- β Beta Δ Delta
- y Gamma



POSITION LEGEND

1—DR position 2—Approximate fix

3-Fix







Semidiameter

SD

ANSWERS TO PROBLEM WORK

Exact agreement cannot be expected with problems involving vector diagrams and chart work since the plotted angles or information obtained on a computer may vary slightly. Therefore, altitudes should be within \pm 50 feet; air speed \pm 2 knots or 2 m.p.h.; latitude and longitude \pm 5 minutes, and courses and bearings within one degree of the results tabulated herewith.

	CHART DRAWINGS		LEM WORK NO. 2	AIRCRA	PROBLEM WORK NO. 3 AIRCRAFT COMPASS DRAWING		
	ROBLEM WORK NO. 4 IMETER CORRECTION			M WORK NO. 5			
No.	TRUE ALTITUDE	No.	I.A.S. (m.p.h.)	C.A.S. (knots)	T.A.S. (knots)		
1	8300′	1		129	154		
2	3080′	2		146	164		
3	23,300′	3	188	169			
4	11,200′	4	187	168			
5	5180′	5		149	164		
6	19,100′	6	179	160			
7	1990′	7		132	144		
8	9000	8	185	165			
9	17,750	9		144	146		
10	13,850′	10		126	131		
11	6170′	11		137	163		
12	1410	12	200	177			
13	2830′	13		150	162		
14	10,200′	14		161	202		
15	8500′	15		167	205		
16	6270′	16		143	148		
17	7500′	17	185	166			
18	9950′	18	187	168			
19	8700′	19		161	178		
20	12,200′	20		109	. 111		



PROBLEM WORK NO. 6 APPLYING COMPASS ERRORS

No.	TRUE COURSE	VARIATION	MAGNETIC COURSE	DEVIATION	COMPASS COURSE
1		10°E			80°
2	270°			3°W	
3			24°		23°
4	2°				346°
5		5°W		5°W	
6			343°	'4°E	
7		0°	122°		
8	359°		346°		
9		10°W		1°E	
10		15°E	100°		
11	223°		237°		
12		9°E			219°
13	147°				154°
14		11°W		9°E	
15			315°	5°W	
16			201°		200°
17	312°			6°W	
18		8°E	326°		
19	3°				343°
.20		5°W			100°

PROBLEM WORK NO. 7 TRACK AND HEADING

	TRACK		TRACK		HEADING		HEAD	ING
No.	TRUE	VAR.	MAGNETIC	DRIFT	MAGNETIC	DEV.	COMPASS	TRUE
1			103°		101°		104°	115°
2	231°	79 126		4°R		2°E		227°
3		14°W		4°L	65°		68°	
4		10°E		6°R		0°		336°
5			81°	3°R		7°E		93°
6	276°			2°R		9°W		274°
7			121°	1°R	120°		124°	
8	242°			2°R			223°	240°
9		16°E			155°	6°W		171°
10	209°		221°			4°E		209°
11	173°		183°				185°	175°
12	198°	16°E		4°R		5°W		
13	114°	V	131°		124°	4°E		
14		11°E		1°L	346°			357°
15		14°E		1°L			3°	7°
16	300°				281°	6°E		297°
17		12°W			262°	11	276°	250°
18	222°		236°		232°		237°	
19	200°	24°E	176°				190°	
20	118°	744		4°R		6°E		114°





PROBLEM WORK NO. 8 TIME_SPEED_DISTANCE

No.	DISTANCE (Nautical Miles)	No.	SPEED (Knots)	No.	TIME
1	181.25	9	118.05	16	1h26m
2	213.11	10	157.85	17	1h56m
3	347.64	11	109.12	18	0h35m
4	111.46	12	142.09	19 -	1h20m
5	468.05	13	141.96	20	1h42m
6	240.30	14	185.36		
7	284.40	15	148.15		
8	152.54				

PROBLEM WORK NO. 9-A VECTOR DIAGRAMS						LEM WOR	PROBLEM WORK NO. 10 DOUBLE DRIFT		
No.		ADING COMPASS	GROUND SPEED	DRIFT	No.	WIND	DRIFT	No.	WIND
							-	1	
1	69°		104	16°R	1	22°/28	10°R	1	168°/11
2	152°		102	21°R	2	64°/47	25° R	2	316°/23
3	155°		92	· 15°L	3	236°/27	10°R	3	163°/17
4	315°		130	15°L	4	296°/25	12°L	4	102°/40
5	216°		141	8°L	5	116°/26	14°L	5	122°/23
6	162°		176	14°L	6	119°/19	7°L	6	43°/25
7	162°		176	8°R	7	344°/12	6°R	7	180°/19
8	248°		125	8°L	8	2°/43	9.°L	8	192°/26
9	45°		165	8°L	9	59°/41	13°R	9	24°/33
10	348°		178	12°R	10	197°/41	16°R	10	339°/25
11	359°		158	9°L	11	27°/16	8°L	11	305°/19
12	24°		196	8°L	12	161°/30	11°L	12	355°/14
13	92°		139	8°R	13	336°/38	12°R	13	193°/41
14	71°		132	11°L	14	310°/17	7°R	14	114°/23
15	335°		163	5°L	15	142°/36	18°L	15	233°/21
16	195°	192°	142	9°R	16	23°/33	12°R	16	41°/25
17	24°	26°	151	7°R	17	98°/52	22°L	17	125°/17
18	82°	87°	168	6°L	18	264°/22	11°L	18	251°/36
19	199°	185°	127	9°L	19	213°/10	4°L	19	136°/18
20	280°	286°	140	10°L	20	338°/29	12°R	20	156°/22

DEAD RECKONING REVIEW TEST NO. 1

- 4 (a) Magnetic course = 306°. True course = 296°.
- (b) True track = 206°. Compass heading = 197°. Magnetic course = 190°.
 (c) True heading = 29°. Compass course = 15°. Magnetic course = 21°.
- 5 True altitude = 9300 feet.
- 6 (a) Calibrated air speed = 158 knots. True air speed = 191 knots.
- (b) True air speed = 193 knots.
- 7 (a) 05:44 GCT. (b) 118 knots. (c) 690 Nautical miles.
- 8 (a) Ground speed = 163 knots. True heading = 282°. Drift = 10°L.
- (b) Ground speed = 94 knots. Track = 74°. Drift = 14°R.
- (c) Wind = $313^{\circ}/56$ knots. Drift = 15° L.
- Wind = $238^{\circ}/22$ knots.
- 10 Distance out = 529 Nautical miles. Time to turn = 12:21 GCT.



RA			ORK NO. 11-A		RADI	PROBLE US OF ACT		K NO. 11-B ALTERNA	TE BAS
	TRUE	TRUE HEADING		TIME		True He	ading to		TIME
No.	OUT	IN	OF ACTION	TURN	No.	Destination	Alternate	DISTANCE OUT	TURN
1	78°	266°	524	12:33	1	38°	177°	293	2:39
2	301°	139°	301	12:21	2	222°	163°	57	:49
3	206°	10°	262	15:37	3	39°	249°	219	2:19
4	256°	65°	751	22:02	4	280°	137°	280	2:02
5	280°	82°	231	12:08	5	138°	281°	534	2:47
6	185°	37°	230	8:57	6	334°	227°	159	1:35
7 .	48°	234°	514	10:25	7	51°	158°	95	1:42
8	22°	238°	222	17:37	8	123°	332°	194	1:09
9	354°	227°		3:51	9	186°	284°	143	:51
10	123°	328°		4:02	10	296°	194°	63	:38
			WORK NO. 13 GN CORRECTI	ON				RK NO. 16 TRIANGLI	<u> </u>
	PROBLEM WORK NO. 14 RADIO BEARINGS GHA AND DECLINATION				-				
WOI	RK NO. 14 RADIO							RK NO. 18 DIAGRAMS	
WOI R BE	RK NO. 14 RADIO				No.				LHA
WOI BE	RK NO. 14 RADIO ARINGS	GHA	GHA	DEC.	. No.	HOUR	ANGLE 1	GHA	
WOH BE No.	RK NO. 14 RADIO ARINGS Mercator Bearing	No.	GHA 185°00′	DEC. N 14°44′	1	HOUR	ANGLE 1	GHA BODY	105°02′F
WOH R BE. No.	Mercator Bearing 54° 348°	No.	GHA 185°00′ 152°52′	DEC. N 14°44′ N 16°12′	1 2	HOUR	ANGLE 1	GHA BODY 330°41′	105°02′I 133°34′I
WOH R BE No.	Mercator Bearing 54° 348° 240°	No. 1 2 3	GHA 185°00' 152°52' 195°57'	DEC. N 14°44′ N 16°12′ N 17°20′	1 2 3	HOUR	ANGLE 1	GHA BODY 330°41′ 66°42′	105°02′F 133°34′F 106°42′\
WOH R BE. No. 1 2 3 4	Mercator Bearing 54° 348° 240° 232°	No. 1 2 3 4	GHA 185°00' 152°52' 195°57' 193°46'	DEC. N 14°44′ N 16°12′ N 17°20′ N 18°37′	1 2 3 4	HOUR	ANGLE 1	GHA BODY 330°41' 66°42' 122°43'	105°02′I 133°34′I 106°42′V 67°17′I
WOH RE BE	Mercator Bearing 54° 348° 240°	No. 1 2 3 4 5	GHA 185°00' 152°52' 195°57' 193°46' 76°12'	DEC. N 14°44' N 16°12' N 17°20' N 18°37' N 19°54'	1 2 3 4 5	HOUR	ANGLE 1	GHA BODY 330°41' 66°42' 122°43' 234°15'	105°02′F 133°34′F 106°42′N 67°17′F 117°04′N
No. 1 2 3 4 5 6	Mercator Bearing 54° 348° 240° 232° 69°	No. 1 2 3 4 5 6	GHA 185°00' 152°52' 195°57' 193°46' 76°12' 41°59'	DEC. N 14°44' N 16°12' N 17°20' N 18°37' N 19°54' N 21°47'	1 2 3 4 5 6	HOUR	ANGLE 1	GHA BODY 330°41' 66°42' 122°43' 234°15' 93°45'	105°02′F 133°34′F 106°42′V 67°17′F 117°04′V 160°45′F
No. 1 2 3 4 5 6 7	Mercator Bearing 54° 348° 240° 232° 69° 247°	No. 1 2 3 4 5 6 7	GHA 185°00' 152°52' 195°57' 193°46' 76°12' 41°59' 334°38'	DEC. N 14°44' N 16°12' N 17°20' N 18°37' N 19°54' N 21°47' N 22°13'	1 2 3 4 5 6 7	HOUR	ANGLE 1	GHA BODY 330°41' 66°42' 122°43' 234°15' 93°45' 28°51'	105°02′F 133°34′F 106°42′V 67°17′F 117°04′V 160°45′F 34°21′V
WOH RESERVANCE STATE OF THE PROPERTY OF THE PR	Mercator Bearing 54° 348° 240° 232° 69° 247° 305° 155°	No. 1 2 3 4 5 6 7 8	GHA 185°00' 152°52' 195°57' 193°46' 76°12' 41°59' 334°38' 353°10'	DEC. N 14°44' N 16°12' N 17°20' N 18°37' N 19°54' N 21°47' N 22°13' N 22°31'	1 2 3 4 5 6 7 8	HOUR	ANGLE 1	GHA BODY 330°41' 66°42' 122°43' 234°15' 93°45' 28°51' 114°34'	105°02′F 133°34′F 106°42′V 67°17′F 117°04′V 160°45′F 34°21′V 24°34′V
WOH R BE. No. 1 2 3 4 5 6 7 8 9	ARK NO. 14 AADIO ARINGS Mercator Bearing 54° 348° 240° 232° 69° 247° 305° 155° 343°	No. 1 2 3 4 5 6 7 8 9	GHA 185°00' 152°52' 195°57' 193°46' 76°12' 41°59' 334°38' 353°10' 316°32'	DEC. N 14°44′ N 16°12′ N 17°20′ N 18°37′ N 19°54′ N 21°47′ N 22°13′ N 22°31′ N 22°20′	1 2 3 4 5 6 7 8 9	HOUR	SHA	330°41′ 66°42′ 122°43′ 234°15′ 93°45′ 28°51′ 114°34′ 347°15′	105°02′I 133°34′I 106°42′\ 67°17′I 117°04′\ 160°45′I 34°21′\ 24°34′\ 150°12′I
WOR REE No. 1 2 3 4 5 6 7 8 9 10	Mercator Bearing 54° 348° 240° 232° 69° 247° 305° 155°	No. 1 2 3 4 5 6 7 8 9 10	GHA 185°00' 152°52' 195°57' 193°46' 76°12' 41°59' 334°38' 353°10' 316°32' 35°48'	NATION DEC. N 14°44' N 16°12' N 17°20' N 18°37' N 19°54' N 21°47' N 22°13' N 22°31' N 22°20' N 22°05'	1 2 3 4 5 6 7 8 9	GHA ARIES	SHA SHA 50°07′	330°41′ 66°42′ 122°43′ 234°15′ 93°45′ 28°51′ 114°34′ 347°15′ 310°07′	105°02′F 133°34′F 106°42′\ 67°17′F 117°04′\ 160°45′F 34°21′\ 24°34′\ 150°12′F 64°53′F
WOR REE No. 1 2 3 4 5 6 7 8 9 10 111	ARK NO. 14 ADIO ARINGS Mercator Bearing 54° 348° 240° 232° 69° 247° 305° 155° 343° 87° 290°	No. 1 2 3 4 5 6 7 8 9 10 11	GHA 185°00' 152°52' 195°57' 193°46' 76°12' 41°59' 334°38' 353°10' 316°32' 35°48' 196°46'	NATION DEC. N 14°44' N 16°12' N 17°20' N 18°37' N 19°54' N 21°47' N 22°13' N 22°31' N 22°20' N 22°05' N 8°06'	1 2 3 4 5 6 7 8 9	GHA ARIES	SHA 50°07′ 259°21′	330°41′ 66°42′ 122°43′ 234°15′ 93°45′ 28°51′ 114°34′ 347°15′ 310°07′ 182°35′	105°02′I 133°34′I 106°42′\ 67°17′I 117°04′\ 160°45′I 34°21′\ 24°34′\ 150°12′I 64°53′I 1°25′\
WOR REE No. 1 2 3 4 5 6 7 8 9 110 111 112	ARK NO. 14 ADIO ARINGS Mercator Bearing 54° 348° 240° 232° 69° 247° 305° 155° 343° 87° 290° 165°	GHA No. 1 2 3 4 5 6 7 8 9 10 11 12	GHA 185°00' 152°52' 195°57' 193°46' 76°12' 41°59' 334°38' 353°10' 316°32' 35°48' 196°46' 192°58'	NATION DEC. N 14°44′ N 16°12′ N 17°20′ N 18°37′ N 19°54′ N 21°47′ N 22°13′ N 22°31′ N 22°20′ N 8°06′ N 39′	1 2 3 4 5 6 7 8 9 10 11 12	HOUR GHA ARIES 283°14′ 27°16′	SHA 50°07′ 259°21′ 63°00′	330°41′ 66°42′ 122°43′ 234°15′ 93°45′ 28°51′ 114°34′ 347°15′ 310°07′ 182°35′ 90°16′	105°02′F 133°34′F 106°42′\ 67°17′F 117°04′\ 160°45′F 34°21′\ 24°34′\ 150°12′F 64°53′F 1°25′\ 19°46′\
WOR RESERVATION OF THE PROPERTY OF THE PROPERT	ARK NO. 14 ADIO ARINGS Mercator Bearing 54° 348° 240° 232° 69° 247° 305° 155° 343° 87° 290° 165° 311°	GHA No. 1 2 3 4 5 6 7 8 9 10 11 12 13	GHA 185°00' 152°52' 195°57' 193°46' 76°12' 41°59' 334°38' 353°10' 316°32' 35°48' 196°46' 192°58' 58°25'	DEC. N 14°44′ N 16°12′ N 17°20′ N 18°37′ N 19°54′ N 21°47′ N 22°13′ N 22°31′ N 22°20′ N 8°06′ N 39′ N 5°32′	1 2 3 4 5 6 7 8 9 10 11 12 13	HOUR GHA ARIES 283°14′ 27°16′ 207°56′	50°07′ 259°21′ 63°00′ 291°50′	330°41′ 66°42′ 122°43′ 234°15′ 93°45′ 28°51′ 114°34′ 347°15′ 310°07′ 182°35′ 90°16′ -139°46′	105°02′I 133°34′I 106°42′\ 67°17′I 117°04′\ 160°45′I 34°21′\ 24°34′\ 150°12′I 64°53′I 1°25′\ 19°46′\ 130°09′I
WOR REE No. 1 2 3 4 5 6 7 8 9 110 111 12 13 14	ARK NO. 14 ADIO ARINGS Mercator Bearing 54° 348° 240° 232° 69° 247° 305° 155° 343° 87° 290° 165° 311° 78°	GHA No. 1 2 3 4 5 6 7 8 9 10 11 12 13 14	GHA 185°00' 152°52' 195°57' 193°46' 76°12' 41°59' 334°38' 353°10' 316°32' 35°48' 196°46' 192°58' 58°25' 28°28'	DEC. N 14°44′ N 16°12′ N 17°20′ N 18°37′ N 19°54′ N 21°47′ N 22°13′ N 22°31′ N 22°20′ N 22°05′ N 8°06′ N 39′ N 5°32′ S 7°55′	1 2 3 4 5 6 7 8 9 10 11 12 13 14	HOUR GHA ARIES 283°14′ 27°16′ 207°56′ 104°44′	50°07′ 259°21′ 63°00′ 291°50′ 113°31′	330°41′ 66°42′ 122°43′ 234°15′ 93°45′ 28°51′ 114°34′ 347°15′ 310°07′ 182°35′ 90°16′ 139°46′ 218°15′	105°02′H 133°34′H 106°42′\ 67°17′H 117°04′\ 160°45′H 34°21′\ 24°34′\ 150°12′H 64°53′H 1°25′\ 19°46′\ 130°09′H 97°52′\
WOR REE No. 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15	ARK NO. 14 ADIO ARINGS Mercator Bearing 54° 348° 240° 232° 69° 247° 305° 155° 343° 87° 290° 165° 311° 78° 126°	GHA No. 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15	GHA 185°00' 152°52' 195°57' 193°46' 76°12' 41°59' 334°38' 353°10' 316°32' 35°48' 196°46' 192°58' 58°25' 28°28' 61°05'	NATION DEC. N 14°44′ N 16°12′ N 17°20′ N 18°37′ N 19°54′ N 21°47′ N 22°13′ N 22°31′ N 22°20′ N 8°06′ N 39′ N 5°32′ S 7°55′ S 5°03′	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15	HOUR GHA ARIES 283°14' 27°16' 207°56' 104°44' 210°06'	50°07′ 259°21′ 63°00′ 291°50′ 113°31′ 16°22′	330°41′ 66°42′ 122°43′ 234°15′ 93°45′ 28°51′ 114°34′ 347°15′ 310°07′ 182°35′ 90°16′ 139°46′ 218°15′ 226°28′	105°02′H 133°34′H 106°42′\ 67°17′H 117°04′\ 160°45′H 34°21′\ 24°34′\ 150°12′H 64°53′H 1°25′\ 19°46′\ 130°09′H 97°52′\ 113°17′H
WOR REE No. 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16	ARK NO. 14 ADIO ARINGS Mercator Bearing 54° 348° 240° 232° 69° 247° 305° 155° 343° 87° 290° 165° 311° 78° 126° 50°	GHA No. 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16	GHA 185°00' 152°52' 195°57' 193°46' 76°12' 41°59' 334°38' 353°10' 316°32' 35°48' 196°46' 192°58' 58°25' 28°28' 61°05' 11°49'	NATION DEC. N 14°44' N 16°12' N 17°20' N 18°37' N 19°54' N 21°47' N 22°13' N 22°31' N 22°20' N 22°05' N 8°06' N 39' N 5°32' S 7°55' S 5°03' S 29°55'	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16	283°14′ 27°16′ 207°56′ 104°44′ 210°06′ 113°45′	50°07′ 259°21′ 63°00′ 291°50′ 113°31′ 16°22′ 245°55′	330°41′ 66°42′ 122°43′ 234°15′ 93°45′ 28°51′ 114°34′ 347°15′ 310°07′ 182°35′ 90°16′ -139°46′ 218°15′ 226°28′ 359°40′	105°02′H 133°34′H 106°42′\ 67°17′H 117°04′\ 117°04′\ 160°45′H 34°21′\ 24°34′\ 150°12′H 64°53′H 1°25′\ 130°09′H 97°52′\ 113°17′H 2°35′H
WOR REE No. 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17	ARK NO. 14 ADIO ARINGS Mercator Bearing 54° 348° 240° 232° 69° 247° 305° 155° 343° 87° 290° 165° 311° 78° 126° 50° 359°	GHA No. 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17	GHA 185°00' 152°52' 195°57' 193°46' 76°12' 41°59' 334°38' 353°10' 316°32' 35°48' 196°46' 192°58' 58°25' 28°28' 61°05' 11°49' 344°15'	NATION DEC. N 14°44' N 16°12' N 17°20' N 18°37' N 19°54' N 21°47' N 22°13' N 22°31' N 22°20' N 22°05' N 8°06' N 39' N 5°32' S 7°55' S 5°03' S 29°55' N 7°24'	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17	283°14′ 27°16′ 207°56′ 104°44′ 210°06′ 113°45′ 250°08′	50°07′ 259°21′ 63°00′ 291°50′ 113°31′ 16°22′ 245°55′ 77°04′	330°41′ 66°42′ 122°43′ 234°15′ 93°45′ 28°51′ 114°34′ 347°15′ 310°07′ 182°35′ 90°16′ -139°46′ 218°15′ 226°28′ 359°40′ 327°12′	105°02′H 133°34′H 106°42′\ 67°17′H 117°04′\ 116°45′H 34°21′\ 24°34′\ 150°12′H 64°53′H 1°25′\ 19°46′\ 130°09′H 97°52′\ 113°17′H 2°35′H 3°09′H
WOR REE No. 1 2 3 4 4 5 6 7 8 9 10 11 12 13 14 15	ARK NO. 14 ADIO ARINGS Mercator Bearing 54° 348° 240° 232° 69° 247° 305° 155° 343° 87° 290° 165° 311° 78° 126° 50°	GHA No. 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16	GHA 185°00' 152°52' 195°57' 193°46' 76°12' 41°59' 334°38' 353°10' 316°32' 35°48' 196°46' 192°58' 58°25' 28°28' 61°05' 11°49'	NATION DEC. N 14°44' N 16°12' N 17°20' N 18°37' N 19°54' N 21°47' N 22°13' N 22°31' N 22°20' N 22°05' N 8°06' N 39' N 5°32' S 7°55' S 5°03' S 29°55'	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16	283°14′ 27°16′ 207°56′ 104°44′ 210°06′ 113°45′	50°07′ 259°21′ 63°00′ 291°50′ 113°31′ 16°22′ 245°55′	330°41′ 66°42′ 122°43′ 234°15′ 93°45′ 28°51′ 114°34′ 347°15′ 310°07′ 182°35′ 90°16′ -139°46′ 218°15′ 226°28′ 359°40′	105°02′H 133°34′H 106°42′\ 67°17′H 117°04′\ 117°04′\ 160°45′H 34°21′\ 24°34′\ 150°12′H 64°53′H 1°25′\ 130°09′H 97°52′\ 113°17′H 2°35′H

CELESTIAL REVIEW TEST NO. 1

3 (a) LHA = 21° West. (b) LHA = 70° East. (c) LHA = 17° East. (e) LHA = 42° West.

(b) LHA = 70° East. (c) LHA = 13° West.

PROBLEM WORK NO. 19 ALTITUDE CORRECTIONS		NO. 19 NO. 20 ALTITUDE LATITUDE BY			PROBLEM WORK NO. 21 LOCAL ZONE TIME			
					ARRIVAL TIME			
No.	Ho	No.	LATITUDE	No.	GCT	ZONE TIME		
1	49°11′	1	32°32′N	1	22:00 May 1	12:30 May 1		
2	57°49′	2	38°51′N	2	06:00 May 6	20:30 May 5		
3	36°17′	3	37°05′N	3	21:00 May 10	09:00 May 11		
4	52°41′	4	39°45′N	4	17:30 May 15	03:30 May 16		
5	39°01′	5	30°44′N	5	05:00 May 21	16:00 May 21		
6	34°22′	6	37°19′N	6	18:45 May 25	08:15 May 25		
7	30°48′	7	43°06′N	7	12:00 May 31	05:00 May 31		
8	38°06′	8	23°56′N	8	00:15 May 16	13:45 May 15		
9	23°17′	9	31°48′N	9	22:00 May 1	10:00 May 2		
10	39°41′	10	25°01′N	10	22:30 May 10	09:30 May 11		
11	41°14′	11	34°10′N	11	15:30 May 5	01:30 May 6		
12	27°27′	12	26°45′N	12	12:00 May 20	23:00 May 20		
13	42°38′	13	43°15′N	13	00:15 May 26	12:15 May 26		
14	35°22′	14	29°52′N	14	23:00 May 15	12:30 May 15		
15	28°51′	15	44°13′N	15	18:00 May 30	08:30 May 30		
16	39°16′	16	37°16′N	16	03:30 May 2	20:30 May 1		
17	30°32′	17	28°41′N	17	18:54 May 5	09:24 May 5		
18	45°07′	18	44°12′N	18	01:00 May 11	18:00 May 10		
19	41°58′	19	33°32′N					
20	41°27′	20	38°59'N					

PROBLEM WORK NO. 22 LCT - GCT

	LCT			GCT		
No.	TIME	DATE	No.	TIME	DATE	
1	04:30:20 PM	May 1	11	06:14:40	May 6	
2	05:16:00 AM	May 5	12	06:21:20	May 1	
3	10:34:00 PM	May 9	13	06:28:40	May 10	
4	11:39:30 AM	May 16	14	06:54:00	May 15	
5	08:54:20 AM	May 20	15	00:50:40	May 21	
6	09:33:20 AM	May 25	16	00:41:44	May 26	
7	10:43:30 PM	May 29	17	00:26:40	May 30	
8	00:30:00 AM	May 11	18	17:16:00	May 15	
9	08:26:10 PM	May 1	19	10:53:40	May 6	
10	02:26:56 AM	May 16	20	18:47:16	May 19	

	ASSUME	PROBLEM D POSITION	PROBLEM WORK NO. 24 ALTITUDE AND AZIMUTH(H.O. 214)					
		ED POSITION	_	15			AZIM	LITTI
No.	Lat.	Long.	LHA	Dec.	No.	Hc	AZIM	OTH
1	34° N	110°48′E	92°W	N 19°29′	1	28°18.2′	N 91	.3°W
2	23°S	172°20′W	18°E	N 16°12′	2	46°45.9′	N 93	.8°E
3	14° N	117°28′W	57° E	N 22°19′	3	14°13.5′	N 117	.9°E
4	22° N	178°11′E	34° W	N 18°37′	4	56°23.9′	N 107	.2°W
5	11°S	124°04′E	77°W	S 60°36′	5	49°17.9′	N 105	.1°W
6	15°N	117°26′E	80°W	N 5°22′	6	62°47.9′	S 34	.8°W
7	33°N	168°31′W	20°W	N 14°45′	7	37°40.8′	N 104	.2°E
8	18°S	104°51′E	48°W	N 25°17′	8	17°57.8′	N 142	.8°W
9	15°S	167°46′E	64° E	S 26°22′	9	60°38.7′	N 105	.9°E
10	32°S	114°57′W	78°E	N 1°25′	10	44°02.0′	N 121	.8°W
11	19°N	127°21′W		S 10°52′	11	64°56.2′	N 45	.8°E
12	7°S	91°58′W		N 16°24′	12	55°06.4′	N 55	
13	20° N	116°16′W		N 7°24′	13	73°36.6′	S 88	
14	4°N	152°26′W		S 8°16′	14	20°15.8′	S 152	.8°W
15	17°S	86°32′E		S 52°40′	15	40°33.0′	N 116	
16	31°S	178°01′W		N 18°37′	16	32°06.8′	S 133	
17	20° N	116°53′W		N 6°18′	17	45°34.0′	S 114	
18	18°S	172°39′E		N 21°45′	18	35°45.5′	N 147	
10	-			14 21 43	10	05 45.5		
10	14°S	178°46'\\	7 22° F	S 60°36'	10	24°18 1′	N 120	3°W
19 20							N 129 N 66 WORK NO. SINGLE LI	27
20	24°N PROI ASSUMEI	162°27'W BLEM WORK POSITION- (PLOT (54°W	N 5°22′	20	66°18.1′ PROBLEM DVANCING	N 66 WORK NO.	27 INES
20	24°N PROI ASSUMEI	162°27'W BLEM WORK D POSITION-	54°W NO. 25 AND N —INTERCEPT—	N 5°22′	20	66°18.1′ PROBLEM DVANCING	WORK NO.	27 INES N. M
20	PROI ASSUMEI	BLEM WORK POSITION (PLOT O	NO. 25 AND N INTERCEPT— ON CHART)	N 5°22' IO. 26 AZIMUTH	20 A)	66°18.1′ PROBLEM DVANCING OF P	WORK NO. SINGLE LI	27 INES N. M
20 No.	PROI ASSUME Lat.	BLEM WORK D POSITION (PLOT C	54°W NO. 25 AND N INTERCEPT INTERCEPT	N 5°22' IO. 26 AZIMUTH AZIMUTH	A) No.	PROBLEM DVANCING OF P Az N 104° E S 146° W	WORK NO. SINGLE LI OSITION	27 INES N. M Advan
No.	PROI ASSUME Lat. 35°S	BLEM WORK D POSITION (PLOT C D POSITION Long. 155°45'E	NO. 25 AND N —INTERCEPT— ON CHART) INTERCEPT 18.6' toward	N 5°22′ IO. 26 AZIMUTH AZIMUTH S 70.7°E S 11.9°W S 131.1°E	20 Al No. 1	66°18.1′ PROBLEM DVANCING OF P Az N 104° E S 146° W S 138° W	N 66 WORK NO. SINGLE LI OSITION Intercept 28' away	27 (NES N. M Advan 15 33 133
No. 1 2 3 4	24°N PROI ASSUMEI ASSUME Lat. 35°S 35°S 35°S 30°N	BLEM WORK D POSITION (PLOT COMPANY) D POSITION Long. 155°45′E 153°23′E 153°49′E 160°26′W	NO. 25 AND N —INTERCEPT— ON CHART) INTERCEPT 18.6' toward 0.6' away 8.6' away 28.1' away	N 5°22′ IO. 26 AZIMUTH AZIMUTH S 70.7°E S 11.9°W S 131.1°E N 85.1°W	No. 1 2 3 4	66°18.1′ PROBLEM DVANCING OF P Az N 104° E S 146° W S 138° W N 123° W	N 66 WORK NO. SINGLE LI OSITION Intercept 28' away 46' toward 9' toward 20' toward	27 (NES N. M. Advan 15 33 133 82
No. 1 2 3 4 5	24°N PROI ASSUME Lat. 35°S 35°S 35°S 30°N 30°N	162°27′W BLEM WORK POSITION (PLOT C D POSITION Long. 155°45′E 153°23′E 153°49′E 160°26′W 158°36′W	NO. 25 AND N —INTERCEPT— ON CHART) INTERCEPT 18.6' toward 0.6' away 8.6' away 28.1' away 19.9' toward	N 5°22′ IO. 26 AZIMUTH S 70.7°E S 11.9°W S 131.1°E N 85.1°W N 96.0°E	No. 1 2 3 4 5	66°18.1′ PROBLEM DVANCING OF P Az N 104°E S 146°W S 138°W N 123°W S 172°E	N 66 WORK NO. SINGLE LI OSITION Intercept 28' away 46' toward 9' toward 20' toward 7' toward	N. M Advan 15 33 133 82 53
No. 1 2 3 4 5 6	24°N PROI ASSUME Lat. 35°S 35°S 35°S 30°N 30°N 30°N	162°27′W BLEM WORK POSITION (PLOT C D POSITION Long. 155°45′E 153°23′E 153°49′E 160°26′W 158°36′W 161°31′W	NO. 25 AND N —INTERCEPT— ON CHART) INTERCEPT 18.6' toward 0.6' away 8.6' away 28.1' away 19.9' toward 39.1' away	N 5°22′ N 5°22′ N 5°22′ N 5°22′ N 5°22′ N 5°22′ N 70.7°E S 11.9°W S 131.1°E N 85.1°W N 96.0°E N 163.0°E	No. 1 2 3 4 5 6	66°18.1′ PROBLEM DVANCING OF P Az N 104°E S 146°W S 138°W N 123°W S 172°E S 156°E	N 66 WORK NO. SINGLE LI OSITION Intercept 28' away 46' toward 9' toward 20' toward 7' toward 28' toward	N. M Advan 15 33 133 82 53 25
No. 1 2 3 4 5 6 7	24°N PROI ASSUME Lat. 35°S 35°S 35°S 30°N 30°N 30°N 30°N	162°27′W BLEM WORK POSITION (PLOT C D POSITION Long. 155°45′E 153°23′E 153°49′E 160°26′W 158°36′W 161°31′W 152°25′E	NO. 25 AND N —INTERCEPT— ON CHART) INTERCEPT 18.6' toward 0.6' away 8.6' away 28.1' away 19.9' toward 39.1' away 7.2' away	N 5°22′ N 5°22′ N 5°22′ N 5°22′ N 5°22′ N 5°22′ N 70.7°E S 11.9°W S 131.1°E N 85.1°W N 96.0°E N 163.0°E N 116.7°W	No. 1 2 3 4 5 6 7	66°18.1′ PROBLEM DVANCING OF P Az N 104°E S 146°W S 138°W N 123°W S 172°E S 156°E N 109°E	N 66 WORK NO. SINGLE LI OSITION Intercept 28' away 46' toward 9' toward 20' toward 7' toward 28' toward 28' toward	N. M Advan 15 33 133 82 53 25 6
No. 1 2 3 4 5 6 7 8	24°N PROI ASSUME Lat. 35°S 35°S 35°S 30°N 30°N 30°N 39°N 39°N	162°27′W BLEM WORK D POSITION (PLOT C D POSITION Long. 155°45′E 153°23′E 153°49′E 160°26′W 158°36′W 161°31′W 152°25′E 151°14′E	INTERCEPT 18.6' toward 0.6' away 8.6' away 28.1' away 19.9' toward 39.1' away 7.2' away 0.0	N 5°22' IO. 26 AZIMUTH S 70.7°E S 11.9°W S 131.1°E N 85.1°W N 96.0°E N 163.0°E N 116.7°W 0.0°	No. 1 2 3 4 5 6 7 8	66°18.1′ PROBLEM DVANCING OF P Az N 104°E S 146°W S 138°W N 123°W S 172°E S 156°E N 109°E S 105°E	N 66 WORK NO. SINGLE LI OSITION Intercept 28' away 46' toward 9' toward 20' toward 7' toward 28' toward 28' toward 28' toward 34' away	N. M Advan 15 33 133 82 53 25 6 18
No. 1 2 3 4 5 6 7 7 8 9	24°N PROI ASSUME Lat. 35°S 35°S 35°S 30°N 30°N 30°N 39°N 39°N 39°N	162°27′W BLEM WORK D POSITION (PLOT C D POSITION Long. 155°45′E 153°23′E 153°49′E 160°26′W 158°36′W 161°31′W 152°25′E 151°14′E 151°04′E	INTERCEPT 18.6' toward 0.6' away 8.6' away 28.1' away 19.9' toward 39.1' away 7.2' away 0.0 14.2' toward	N 5°22' IO. 26 AZIMUTH S 70.7°E S 11.9°W S 131.1°E N 85.1°W N 96.0°E N 163.0°E N 116.7°W 0.0° N 164.1°W	No 1 2 3 4 5 6 7 8 9	66°18.1′ PROBLEM DVANCING OF P Az N 104°E S 146°W S 138°W N 123°W S 172°E S 156°E N 109°E S 105°E N 125°W	N 66 WORK NO. SINGLE LI OSITION Intercept 28' away 46' toward 9' toward 20' toward 28' toward 28' toward 28' toward 34' away 40' away	27 (NES N. M. Advan 15 33 133 82 25 6 18 40
No. 1 2 3 4 5 6 7 8 9 10	24°N PROI ASSUME Lat. 35°S 35°S 35°S 30°N 30°N 30°N 39°N 39°N 39°N 39°N 33°N	162°27′W BLEM WORK D POSITION (PLOT C D POSITION Long. 155°45′E 153°23′E 153°49′E 160°26′W 158°36′W 161°31′W 152°25′E 151°14′E	INTERCEPT 18.6' toward 0.6' away 8.6' away 28.1' away 19.9' toward 39.1' away 7.2' away 0.0 14.2' toward 21.0' toward	N 5°22' IO. 26 AZIMUTH S 70.7°E S 11.9°W S 131.1°E N 85.1°W N 96.0°E N 163.0°E N 116.7°W 0.0°	No 1 2 3 4 5 6 7 8 9 10	66°18.1′ PROBLEM DVANCING OF P Az N 104°E S 146°W S 138°W N 123°W S 172°E S 156°E N 109°E S 105°E N 125°W S 140°W	N 66 WORK NO. SINGLE LI OSITION Intercept 28' away 46' toward 9' toward 20' toward 28' toward 28' toward 28' toward 28' toward 34' away 40' away 37' toward	N. M Advan 15 33 133 133 82 25 6 18 40
No. 1 2 3 4 5 6 7 7 8 9	24°N PROI ASSUME Lat. 35°S 35°S 35°S 30°N 30°N 30°N 39°N 39°N 39°N	162°27′W BLEM WORK D POSITION (PLOT C D POSITION Long. 155°45′E 153°23′E 153°49′E 160°26′W 161°31′W 152°25′E 151°14′E 151°04′E 135°30′W	INTERCEPT 18.6' toward 0.6' away 8.6' away 28.1' away 19.9' toward 39.1' away 7.2' away 0.0 14.2' toward	N 5°22' IO. 26 AZIMUTH S 70.7°E S 11.9°W S 131.1°E N 85.1°W N 96.0°E N 163.0°E N 116.7°W 0.0° N 164.1°W N 81.6°E	No 1 2 3 4 5 6 7 8 9	66°18.1′ PROBLEM DVANCING OF P Az N 104°E S 146°W S 138°W N 123°W S 172°E S 156°E N 109°E S 105°E N 125°W	N 66 WORK NO. SINGLE LI OSITION Intercept 28' away 46' toward 9' toward 20' toward 28' toward 28' toward 28' toward 34' away 40' away	27 (NES N. M. Advan 15 33 133 82 25 6 18 40
No. 1 2 3 4 5 6 7 8 9 10 11	24°N PROI ASSUMEI Lat. 35°S 35°S 35°S 30°N 30°N 30°N 39°N 39°N 39°N 33°N 33°N	162°27′W BLEM WORK D POSITION (PLOT C D POSITION Long. 155°45′E 153°23′E 153°49′E 160°26′W 158°36′W 161°31′W 152°25′E 151°14′E 151°04′E 135°30′W 136°01′W	INTERCEPT 18.6' toward 0.6' away 8.6' away 28.1' away 19.9' toward 39.1' away 7.2' away 0.0 14.2' toward 21.0' toward 3.8' toward 22.0' away 7.2' away 7.2' away	N 5°22' IO. 26 AZIMUTH S 70.7°E S 11.9°W S 131.1°E N 85.1°E N 163.0°E N 163.0°E N 164.1°W N 81.6°E N 140.4°W	No. 1 2 3 4 4 5 6 7 8 9 10 11	66°18.1′ PROBLEM DVANCING OF P Az N 104°E S 146°W S 138°W N 123°W S 172°E S 156°E N 109°E S 105°E N 125°W S 140°W N 147°E	N 66 WORK NO. SINGLE LI OSITION Intercept 28' away 46' toward 9' toward 20' toward 7' toward 28' toward 28' toward 34' away 40' away 37' toward 44' away	N. M Advan 15 33 133 82 53 25 6 18 40 6
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CELESTIAL REVIEW TEST NO. 2

- 3 (a) LHA Sun = 160° West. (b) LHA Star = 40° East. GHA Star = 240° .
- 4(a) GCT = 02:31, January 3rd. (b) LCT = 6:08 AM July 16th.
- 5 (a) LZT = 6:30 PM August 3rd. (b) LZT = 4:30 PM January 6th.
- 6 GHA Sun = 350°49', Declination = 14°53'N.
 - GHA Moon = 23°46', Declination = 1°35'S.
 - GHA* Sirius = 287°58', Declination = 16°38'S.
- 7 $H_0 Sun = 30^{\circ}13'$. $H_0 Venus = 60^{\circ}09'$. $H_0 Altair = 20^{\circ}04'$. $H_0 Moon = 29^{\circ}15'$.
- 8 Latitude = 32°48' North.
- 9 Altitude Intercept = 7.1 away, Azimuth = N 158°E.

тн	ROBLEM NO. REE STA	28		TRAC				ORK NO		N FIXES	
	F	IX		POSITION			Ground			True	
No.	Lat.	Long.	No.	Lat.	Long	g.	Track	Speed	Drift	Wind	Heading
1	31°57′N	9°19′W	1					177			
2	32°08′S	136°33′E	2	34°48′N	127°15′	w	231°	185	11°L	340°/34	242°
3	35°08'N	16°59′E	3	33°25′N	130°07′	w	240°	200	18°L	358°/63	258°
4	31°31′N	179°40′W	4	33°27′N	133°41′	w	271°	213	4°R	108°/38	267°
5	39°36′N	175°27′W	5	31°31′N	136°54′	w	235°	160	7°R	181°/26	228°
6	32°38′N	119°25′W									
7	36°08'N	125°33'E									
8	31°33′N	139°25′W									
	STAR ID	ENTIFICAT	NOI	NO. 30 BY H. O. 2	14	L				NO. 31 AN ALTIT	TUDE
No.			No.			No.	ATITU				
No.	STA		No.	BY H. O. 2		No.	LAT	DE BY I	No.	LATITU	JDE
No.	STA Vega	AR	No	STAR Rasalague		No.	LAT	DE BY I	No.	LATITU 32°4	JDE I'N
No. 1 2	STA Vega Adhara	AR	No.	STAR Rasalague Kaus-Austr		No.	LAT	DE BY I ITUDE '58'N '10'N	No.	LATITU	JDE L'N P'N
No.	STA Vega	AR	No	STAR Rasalague		No. 1 2	LAT: 25° 3° 45°	DE BY I	No. 11 12	LATITU 32°41 23°39	UDE UDE
No. 1 2 3	Vega Adhara Spica	AR .	No. 11 12 13	STAR Rasalague Kaus-Austr Canopus		No. 1 2 3	25° 3° 45°	DE BY I ITUDE °58'N °10'N °57'N	No. 11 12 13	1 LATITU 32°41 23°39 .22°49	JDE I'N D'N D'N
No. 1 2 3 4	Vega Adhara Spica Altair	AR .	No. 11 12 13 14	STAR Rasalague Kaus-Austr Canopus Denebola		No. 1 2 3 4	25° 3° 45° 13° 24°	DE BY I ITUDE '58'N '10'N '57'N	No. 11 12 13 14	23°41 23°39 .22°49 32°44	JDE I'N D'N D'N B'N
No. 1 2 3 4 5	Vega Adhara Spica Altair Regulus	AR .	No. 11 12 13 14 15	STAR Rasalague Kaus-Austr Canopus Denebola Alioth		No. 1 2 3 4 5	25° 3° 45° 13° 24°	PERY I	No. 11 12 13 14 15	23°39 .22°49 .22°49 .22°49 .22°49 .22°49 .22°49	JDE I'N P'N P'N B'N P'N
No. 1 2 3 4 5	Vega Adhara Spica Altair Regulus Miaplac	s cidus ca	No. 11 12 13 14 15 16	STAR Rasalague Kaus-Austr Canopus Denebola Alioth Dschubba		No. 1 2 3 4 5 6	LATI 25° 3° 45° 13° 24° 43°	DE BY 1 ITUDE 258'N 210'N 257'N 221'S 200'S	No. 11 12 13 14 15 16	23°39 .22°49 .22°49 .32°44 .29°19 .12°39	JDE I'N I'N I'N I'N I'N I'N I'N I'S
No. 1 2 3 4 5 6 7	Vega Adhara Spica Altair Regulus Miaplac	s cidus ca	No. 11 12 13 14 15 16 17	STAR Rasalague Kaus-Austr Canopus Denebola Alioth Dschubba Shaula		No. 1 2 3 4 5 6 7	LATI 25' 3' 45' 13' 24' 43' 29'	DE BY 1 ITUDE 258'N 210'N 257'N 221'S 200'S 256'N	No. 11 12 13 14 15 16 17	23°49 23°39 22°49 32°44 29°19 12°39	JDE I'N O'N O'N O'N O'N O'N O'N O'N O'S



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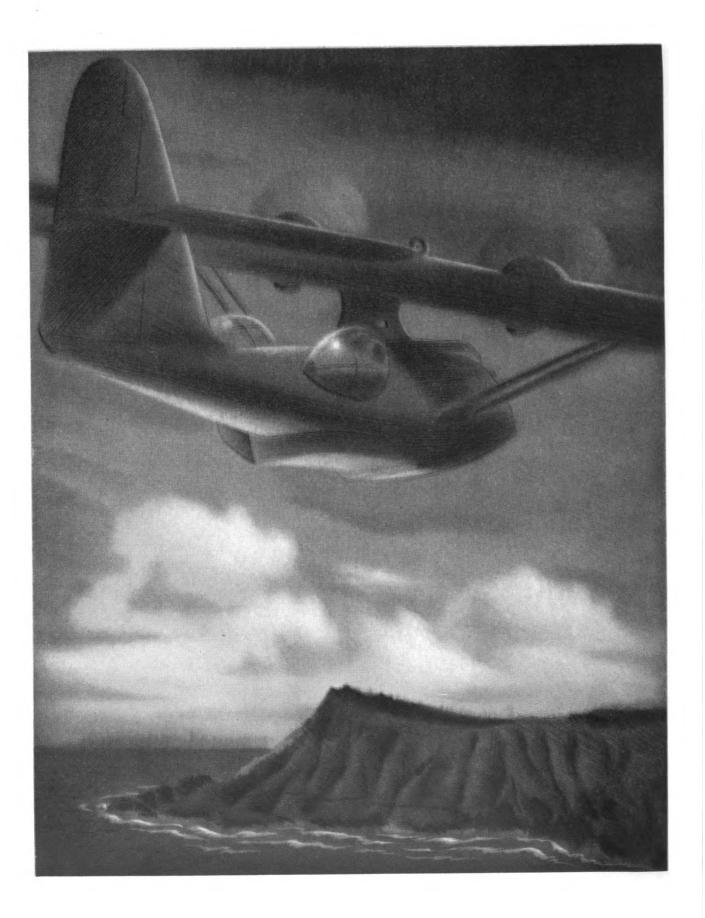
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